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CHARACTERIZING THE MECHANICAL PROPERTIES OF GRAPHENE AND SINGLE WALLED CARBON NANOTUBES

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ABSTRACT

In this study, the mechanical properties of graphene and single walled carbon nanotubes (SWCNTs) were investigated based on molecular dynamics (MD) simulation. During the characterization of the mechanical properties, the atomistic interactions of the carbon atoms were described using the bonded and non-bonded energies. The bonded energy consists of four different interactions: Bond stretching, bond angle bending, dihedral angle torsion, and inversion. On the other hand, the non-bonded interaction between the carbon atoms within the cut-off ranges was regarded as the van der Waals (vdW) force. The effect of vdW force on the mechanical properties of graphene and SWCNTs would be mainly of concern. Simulation results indicated that the Young's modulus of the graphene with vdW force included is 15% higher than that without considering any vdW interaction. The same tendency also was observed in the armchair and zig-zag SWCNTs. Furthermore, it was revealed that the increment of moduli caused by the vdW force could be primarily attributed to the 1-4 vdW interaction. The influence of the vdW interactions on the mechanical properties of graphene and SWCNTs was then elucidated using the parallel spring concept.

Keywords: Graphene sheet, SWCNTs, Van der Waals interaction, Mechanical properties, Molecular dynamics simulation.

1. INTRODUCTION

With characteristics of high strength and stiffness, the graphene and single walled carbon nanotubes (SWCNTs) have been used as reinforcements in composite materials [1-3]. In the past decade, the mechanical properties of graphene and SWCNTs were characterized using molecular dynamics [4-7], structural mechanics [8-10], and finite element analysis [11]. No matter which analysis was performed, the basic process was to specify the atomistic interaction of the atoms and then implement the corresponding interactions into the designed model. In fact, for the SWCNTs and graphene with the regular and periodic microstructures, the mechanical properties can be determined analytically associated with the atomistic interaction [12,13]. In other words, the mechanical properties of graphene and SWCNTs can be exactly characterized once the corresponding atomistic interactions of the carbon atoms are appropriately defined. Therefore, the proper description of atomic interactions becomes the key issue in evaluating the mechanical properties of graphene and SWCNTs.

In the characterization of graphite sheet and SWCNTs, the atomistic interactions of the carbon at-

oms are generally characterized by tight-binding (TB) [14-17], Tersoff-Brenner approach [18-21] and the pairwise potential [22]. It is noted that the pair-wise energy with the advantage of simplicity [23] was adopted in this study to describe the bonded interaction of carbon atoms. In addition, the non-bonded interaction between the carbon atoms within the cut-off ranges was modeled using the van der Waals (vdW) force. In general, the non-bonded interaction was considered to have less contribution on the mechanical behavior and, sometimes, was neglected in atomistic modeling. However, the vdW force may actually have an influence on the mechanical properties of the nano-materials/nano-structures [24]. In molecular mechanics, all atoms except those that are bounded to each other or connected to a common atom have to be included in the vdW interaction [25]. It means that the 1-4 interactions as well as the higher order terms need to be taken into account in the vdW potentials. Nevertheless, in some molecular dynamics software, such as DL-POLY [26], the selection of the 1-4 vdW interaction as well as its extent is optional. Most studies that focus on the elastic properties of the SWCNTs and graphene rarely explored the effect of vdW force on the mechanical properties of the atomistic structures. In light of the

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light of the forgoing, it is required to conduct a systematic molecular simulation in order to clarify the vdW interaction effect, especially the 1-4 vdW force, on the mechanical responses of the atomistic structures.

In this study, the mechanical properties of the SWCNTs and the graphene were constructed, and the corresponding properties were characterized using MD simulation with various degrees of vdW forces. Because SWCNTs and graphene possess simple microstructures, the influence of vdW interaction on the mechanical responses can be simply investigated from the molecular simulation. By applying uniaxial tensile loading, the Young's modulus of the atomistic structures was measured in terms of the corresponding strain field in the deformed configuration. The moduli obtained based on the molecular structures with various vdW interactions were compared to each other, and the results were discussed accordingly based on the parallel spring concept.

2. POTENTIAL ENERGY FOR THE ATOMISTIC STRUCTURES

2.1 Graphene

A graphene sheet basically contains a layer of carbon where the carbon atoms are arranged in a hexagonal pattern. The interatomic distance between the adjacent carbon atoms is 1.42 Å, and the associated atomistic interaction is covalently bonded by SP^2 hybridized electrons, the bond angle of which is 120 degree to each other [8]. In order to investigate the mechanical properties of the graphene, the atomistic structures have to be constructed in conjunction with the appropriately specified atomistic interaction. In the description of graphene, two kinds of atomistic interactions are normally taken in account: One is bonded interaction, such as the covalent bond, and the other is the non-bonded interaction, *i.e.*, vdW forces and electrostatic forces. Among the atomistic interactions, the covalent bond between two neighboring carbon atoms that provides the building block of the primary structure of the graphene may play an essential role in the mechanical responses. Such bonded interaction can be described using the potential energy that consists of bond stretching, bond angle bending, torsion, and inversion as illustrated in Fig. 1 [23]. Therefore, the total potential energy of the graphite contributed from the covalent bond can be written explicitly as

$$U_{\text{graphite}} = \sum U_r + \sum U_\theta + \sum U_\phi + \sum U_\omega, \quad (1)$$

where U_r is a bond stretching potential; U_θ is a bond angle bending potential; U_ϕ is a dihedral angle torsional potential; and U_ω is an inversion potential. For graphene structure under in-plane deformation, the atomistic interaction is mainly governed by the bond stretching and bond angle bending; therefore, the dihedral torsion and inversion potentials that are related to the out-of-plane deformation were disregarded in the modeling. The explicit form for the bond stretching and bond angle bending can be approximated in terms of elastic springs as [10]

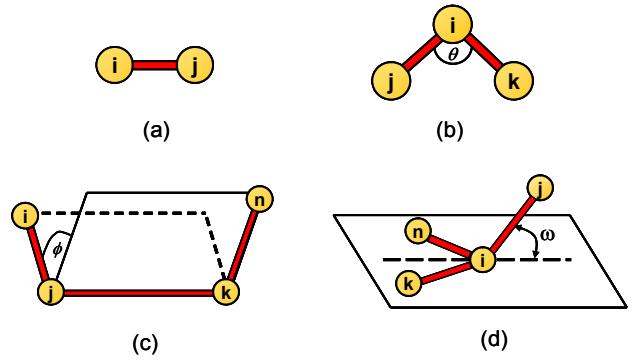


Fig. 1 A schematic of the inter-atomic potential (a) bond stretch, (b) bond angle bending, (c) dihedral angle torsion, (d) inversion

$$U_r = \frac{1}{2} k_r (r - r_0)^2, \quad (2)$$

$$U_\theta = \frac{1}{2} k_\theta (\theta - \theta_0)^2, \quad (3)$$

where k_r and k_θ are the bond stretching force constant and angle bending force constant, respectively. The constants $k_r = 93800 \frac{\text{kcal}}{\text{mole} \times \text{nm}^2}$ and $k_\theta = 126 \frac{\text{kcal}}{\text{mole} \times \text{rad}^2}$ selected from AMBER force field for carbon–carbon atomic-interaction were employed in our molecular simulation [27]. The parameters r_0 and θ_0 represent bond length and bond angle in equilibrium position, which are assumed to be 1.42 Å and 120 degree respectively, in the graphite atomistic structures.

In addition to the bonded interaction, the non-bonded interaction between the carbon atoms was regarded as the vdW force, which can be characterized using the Lennard-Jones (L-J) potential as

$$U_{\text{vdW}} = 4u \left[\left(\frac{r_0}{r_{ij}} \right)^{12} - \left(\frac{r_0}{r_{ij}} \right)^6 \right], \quad (4)$$

where r_{ij} is the distance between the non-bonded pair of atoms. For the hexagonal graphite, the parameters $u = 0.0556 \text{ kcal/mole}$ and $r_0 = 3.40 \text{ \AA}$ suggested for the carbon–carbon interaction were adopted in the modeling [28]. Moreover, the cutoff distance for the vdW force is assigned to be $3r_0$, which means that beyond this distance, there are no more vdW interactions taking place. In molecular mechanics, all atoms except those that are bound to each other or connected to a common atom have to be accounted for in the calculation of vdW interactions [25]. When we look closely at the atomic structure of graphene shown in Fig. 2, the possible shortest distance between two carbon atoms needed to be considered for the vdW interaction is 2.84 Å (line (a) in Fig. 2 if it is measured from “atom I”). Thus, the carbon atoms with inter-atomic distance greater than 2.84 Å have to be accounted for in the vdW calculation. It is noted that the atomic interaction between atoms I

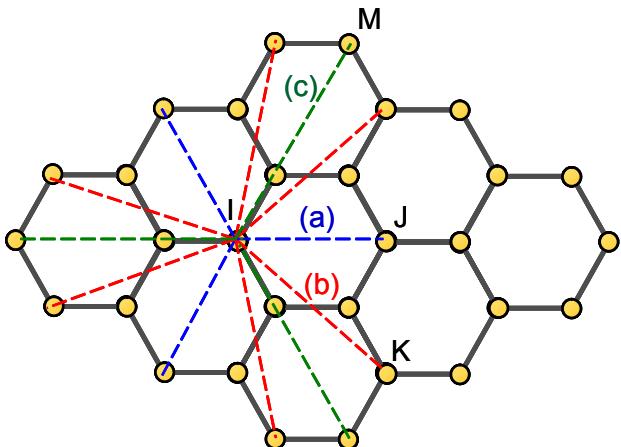


Fig. 2 Interatomic distance in graphene structure ((a) = 2.84 Å, (b) = 3.757 Å, (c) = 4.26 Å)

and J and between atoms I and K are usually denoted as 1-4 vdW interaction since the multiple interactions take place between number 1 atom and number 4 atom. The remaining vdW interactions within the cut-off range are indicated as the higher order vdW interaction. The 1-4 vdW interaction together with the higher order vdW is regarded as the vdW interaction in the molecular mechanics.

2.2 Single Walled Carbon Nanotubes

When modeling the interatomic behaviors of SWCNTs, in addition to the bond stretching potential and the bond angle bending potential given in Eqs. (2) and (3), the dihedral torsional potential and inversion potential which characterize the out of plane deformation have to be included in molecular simulation. For the dihedral torsional potential and inversion potential, Li and Chou adopted the simplest harmonic form to incorporate the two interactions together into a single equivalent term as [10]

$$U_{\tau} = U_{\phi} + U_{\omega} = \frac{1}{2} k_{\tau} (\phi - \phi_0)^2, \quad (5)$$

where k_{τ} is the torsional constant and equal to $40 \frac{kcal}{mole \cdot rad^2}$. The parameter ϕ_0 represents dihedral torsional angle in equilibrium position, which is equal to 180° in the SWCNTs atomistic structures. It should be noted that in the study, the MD simulation was conducted using the DL-POLY package where Dreiding potential was utilized to model the inter-atomic potential of carbon–carbon bonding [29]. For the bond stretching and angle changing behaviors, the mathematical forms of Dreiding potential are exactly the same as those given in Eqs. (2) and (3). Nevertheless, for the dihedral torsion and inversion, the Dreiding torsional potential that accounts for the two portions together is expressed explicitly as

$$U_{\tau} = U_{\phi} + U_{\omega} = A [1 - \cos(m(\phi - \phi_0))]. \quad (6)$$

Because the carbon–carbon bonding in the hexagonal graphite is in resonance, the parameter “ m ” in Eq. (6) should be equal to 2 [29]. Moreover, the parameter A is decided according to the assumption that Dreiding torsional potential should correspond to the dihedral torsional potential given in Eq. (5). It has been found that when A is equal to 10.02 kcal/mole, the Dreiding torsional potential coincides with the dihedral torsional potential well. As a result, the Dreiding torsional potential with $m = 2$ and $A = 10.02$ kcal/mole were employed in our atomistic simulation. In addition to the bonded interaction, the vdW interaction containing 1-4 vdW force and high order interaction was utilized to characterize the non-bonded interaction of SWCNTs. The influences of 1-4 vdW interaction as well as the high order vdW interaction on the mechanical properties of SWCNTs were evaluated from simple tensile tests.

3. CHARACTERIZATION OF MECHANICAL PROPERTIES

In order to evaluate the material properties of graphene sheets and SWCNTs, the simulation box suitable for representing the atomistic structures has to be established. Figure 3 shows the schematic of the simulation box for the graphene sheet. A periodic boundary condition was implemented on all surfaces to demonstrate the infinite graphite structures. It is noted in the graphene sheet that the dimension of the simulation box in the thickness direction is set to be large enough that the vdW interaction between the neighboring layers can not be attained. This special design of the simulation box is intended to simulate the single layer of graphene sheets. The atomistic structure with stress-free configuration was obtained by performing an NPT ensemble with time increments at 1fs for 100ps (the total iteration steps are 100000) until the potential energy accomplished a stable value. The NPT ensemble represents that the pressure and temperature of the system may approach the specified values during the MD simulation. This process is accomplished through the Berendsen thermostat by scaling the velocities and positions of atoms at each step to push the temperature and pressure toward the desired value ($P = 0$ and $T = 0K$) [30,31]. In the same manner, the simulation box as shown in Fig. 4 was generated to simulate the SWCNTs. The lateral directions of the simulation were designed to be large enough that the neighboring SWCNTs would not be interacted mutually. The MD simulation was carried out under the DL-POLY package originally developed by Daresbury Laboratory [26] in conjunction with the homemade subroutine for post-processing.

Subsequently, the mechanical properties of the atomistic structures with specified intermolecular potentials were determined from the simple tension tests. The methodology developed to evaluate the mechanical properties of the atomistic structures was motivated from the technique commonly used in the continuum

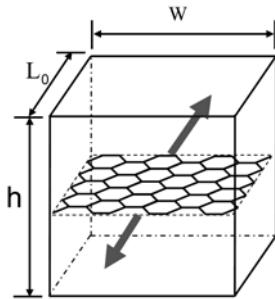


Fig. 3 Axial stress applied in graphene sheet ($W = 46.86 \text{ \AA}$, $L_0 = 51.65 \text{ \AA}$, $h = 34.0 \text{ \AA}$)

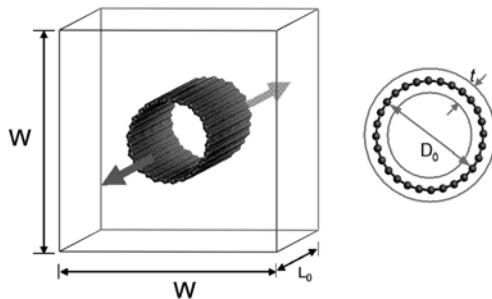


Fig. 4 Axial stress applied in SWCNTs ($W = 30 \text{ \AA}$, $L_0 = 85.2 \text{ \AA}$)

solid. The same concept was extended and applied to the atomistic structures by means of a modified NPT ensemble in MD simulation with the characteristics of varying a simulation box in shape and size [32]. In other words, axial stresses were implemented on both sides of the simulation box with other faces being traction free as shown in Figs. 3 and 4 for graphene and SWCNTs, respectively. After the energy minimization process, the equilibrated graphene atomistic structure under axial loading was obtained, and the Young's modulus was defined in the continuum manner as

$$E = \frac{\sigma}{\varepsilon}, \quad (7)$$

where ε is the strain component measured in the loading direction. In Eq. (7), σ should be the stress directly acting on the atomistic structure. However, for the case of graphene sheets as shown in Fig. 3, because the dimension of the graphene sheet in thickness direction is not compatible to the size of the simulation box, the stress in the graphene sheet has to be converted from the stress acting on the simulation box, σ_{box} , in terms of the geometric parameters as

$$\sigma = \frac{\sigma_{\text{box}} h}{t}, \quad (8)$$

where h is the height of the simulation box, and t is the thickness of the graphene sheet, which is equal to 3.4 \AA . The Young's moduli associated with various vdW interactions obtained from MD simulation for graphene sheets are presented in Table 1.

Table 1 Mechanical properties of graphene and SWCNTs obtained based on different degrees of vdW interaction

	Young's modulus (GPa)			
	No vdW	High order vdW	1-4 vdW	1-4 vdW + high order vdW
Graphene sheet	793.8	792	913	912
Zig-zag SWCNT (10,0)	782.5	781	905.3	904.6
Zig-zag SWCNT (26,0)	793.6	791.8	912.8	911.9
Armchair SWCNT (5,5)	781	779	900	899.6
Armchair SWCNT (15,15)	793	791	912	911

It is noted that in the above simulation, the NPT ensemble as well as the modified NPT ensemble was conducted to characterize the modulus of the nanostructures, and thus only active atoms (the one follows the Newtonian second law) were accounted for in the atomistic model. In addition, because the simulation was performed based on load control, the configurations of the nanostructures before/after the loading were measured for the evaluation of strain variation. Each time when the loading (0.01GPa) was applied, it was found that the deformed atomistic structure with energy minimization could be achieved after 100ps simulation time. As a result, the strain rate of the deformed process was measured as the strain increment associated with the simulation time. In this study, the strain rate is around $1 \times 10^6 \text{ s}^{-1}$.

In the same manner, the mechanical properties of SWCNTs were determined by a modified NPT ensemble such that uniaxial stress can be independently applied on the SWCNTs with stress free in the lateral direction. Again, after the energy minimization process, the equilibrated SWCNTs atomistic structure was obtained, and the modulus was evaluated by measuring the axial strain associated with the applied axial stress. It is noted that the stress implemented on the SWCNTs was calculated from the stress acting on the simulation box, σ_{box} , associated with the cross section as

$$\sigma = \frac{\sigma_{\text{box}} W^2}{A}, \quad (9)$$

where $A = \pi D_0 t$. The Young's modulus of SWCNTs with various radii obtained based on modified NPT ensemble in terms of different vdW interactions are presented in Table 1. Both zig-zag and armchair SWCNTs with different radii were considered in the atomistic simulation.

4. RESULTS AND DISCUSSIONS

Table 1 illustrates the Young's modulus of graphene sheets and SWCNTs with different degrees of vdW interactions. The graphene sheet with 1-4 vdW interaction demonstrates the highest Young's modulus among all cases, and the increment relative to the graphene without any vdW interaction is 15%. On the contrary, the graphene sheet with only the high order vdW interaction included exhibits the lowest value of Young's modulus. It seems that the higher order vdW interaction has a negative effect on the Young's modulus although the effect is not as significant as that of the 1-4 vdW interaction. These phenomena can be explained from the Lennard-Jones potential given in Eq. (4). By taking the derivative of the *L-J* potential function, the *L-J* force as well as the corresponding "spring" constants in terms of the interatomic distance is derived as

$$F = -\frac{\partial U_{vdW}}{\partial r_{ij}} = 4u \left[12 \times r_0^{12} \times \left(\frac{1}{r_{ij}} \right)^{13} - 6 \times r_0^6 \times \left(\frac{1}{r_{ij}} \right)^7 \right], \quad (10)$$

$$K = -\frac{\partial F}{\partial r_{ij}} = 4u \left[156 \times r_0^{12} \times \left(\frac{1}{r_{ij}} \right)^{14} - 42 \times r_0^6 \times \left(\frac{1}{r_{ij}} \right)^8 \right], \quad (11)$$

and the corresponding results were plotted in Fig. 5. It can be seen that the spring constant at the vdW distance less than 4.2311Å is positive and becomes negative when the distance is greater than 4.2311Å. Based on the parallel spring concept, it is apparent that the positive spring constant may increase the Young's modulus of the materials; in contrast, the negative spring constant may reduce the Young's modulus. When the atomic interactions are treated as an arrangement of parallel springs, the modulus of the atomistic structures is dependent on the spring constants. Again, when we examine the atomic distances of 1-4 vdW interactions shown in Fig. 2, they are 2.84Å and 3.757Å as denoted by line (a) and (b), and the corresponding "spring" constants are positive. Thus, including the 1-4 vdW energy into the interatomic potential may enhance the modulus of the graphene and the SWCNTs as well. However, for the higher order vdW interaction, the atomistic distances are no less than 4.26Å, which are greater than critical value of 4.2311Å. Thus, the associated spring constants are negative, resulting in the negative contribution of the moduli. Moreover, since the negative spring constants of higher order vdW interaction usually are much less than the positive spring constants provided by the 1-4 vdW interaction, the higher order vdW interaction plays a minor role in the properties of the graphene sheet. The same tendency is also observed in the zig-zag and armchair SWCNTs with different radii. Agrawal *et al.* [6] indicated that the moduli of the SWCNTs are not influence by whether the vdW interaction was taken into account or not. In fact, if only the high order vdW interaction

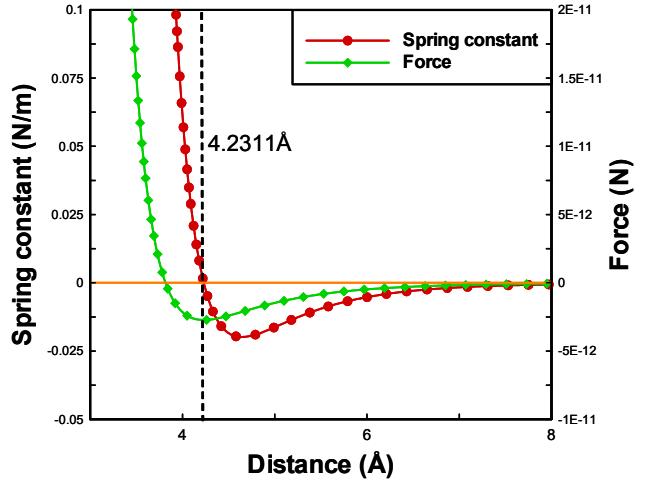


Fig. 5 Interatomic force and spring constant calculated based on *L-J* potential

was considered as the vdW interaction in their modeling, the results presented are quite promising. On the other hand, the literature [24] addressed that the moduli of the SWCNTs can be enhanced by the vdW interaction up to 10%. According to our earlier examinations, it is probable to have the improved properties when 1-4 vdW interaction is accounted for in the atomistic simulation. Thus, whether the 1-4 vdW interaction is employed in the molecular simulation would be the crucial issue in the characterization of mechanical properties of graphene and SWCNTs, which should be treated with caution when we model the properties of the atomistic structures.

In addition, the moduli of the SWCNTs derived based on pair-wise potential as well as the 1-4 vdW interaction are around 0.9TPa which is in agreement with the results obtained from the tight-binding potential [15,16] and the Tersoff-Brenner potential [4,18,19, 21] as well as the experimental data [33,34]. Hernández *et al.* [15] and Cai *et al.* [16] calculated the Young's modulus of SWCNTs by second derivative of the strain energy with tight-binding method and Young's modulus of SWCNTs is equal to 1.2TPa and 0.95TPa, respectively. Bao *et al.* [4] evaluated the Young's modulus of graphene and SWCNTs as 1.2TPa and 0.93TPa respectively by conducting MD simulation with Brenner potential. The moduli of 0.7TPa for SWCNTs was obtained by Sammalkorpi *et al.* [18]. In addition, Reddy *et al.* [19] modeled the Young's modulus of finite graphene structure using continuum mechanics approach based on the Brenner potential and the computed Young's modulus of graphene is equal to 0.7TPa. Jeng *et al.* [21] investigated the mechanical properties of typical zigzag and armchair SWCNTs through the MD simulation with Tersoff potential. Result indicated that the Young's modulus of SWCNTs is determined to be 1.06TPa. In light of the published data, it seems that the moduli of SWCNTs are varying from 0.7TPa to 1.2TPa, and our current data are within the range. If we checked the experimental data [33,34], the corresponding value is also fluctuating between 0.9TPa to 1TPa. It is worthy to mention that because the effect of the 1-4 vdW interaction is around

15% in terms of the modulus of the SWCNTs, it is really difficult to characterize the inference from the experimental observation. Furthermore, based on our simulation, it is found that the influence of charity on the modulus of SWCNTs is not appreciable, which agrees well with the results addressed in the literature [4,5,12,18].

5. CONCLUSIONS

The mechanical properties of graphene and SWCNTs were investigated according to different extents of the vdW interactions. Both 1-4 vdW interaction and high order vdW interaction are of concern. By applying tensile loading, the deformed configuration of the atomistic structures was calculated through the molecular simulation, and then the mechanical properties were determined accordingly. Results indicate that the 1-4 vdW interaction can increase the modulus of the atomistic structures up to 15%, and the enhancement is attributed to the positive spring constant caused by such atomistic interactions. In contrast, the high order vdW interaction can lessen the modulus, but the decrease is not appreciable as compared to the 1-4 vdW interaction. Thus, combining the high order vdW interaction with the 1-4 vdW potentials in the molecular simulation still can improve the moduli of the graphene and SWCNTs as well.

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