



## Accuracy enhanced thermal face recognition



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### HIGHLIGHTS

- The recognizer employs both critical thermal features and geometric features.
- The critical geometric features would not be influenced by hair style.
- The topography of blood vessels is unique for every human.
- The recognizer uses direct information of the topography of blood vessels.
- Performance of the recognizer is invariable when the hair of frontal bone varies.

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### ABSTRACT

Human face recognition has been generally researched for the last three decades. Face recognition with thermal image has begun to attract significant attention gradually since illumination of environment would not affect the recognition performance. However, the recognition performance of traditional thermal face recognizer is still insufficient in practical application. This study presents a novel thermal face recognizer employing not only thermal features but also critical facial geometric features which would not be influenced by hair style to improve the recognition performance. A three-layer back-propagation feed-forward neural network is applied as the classifier. Traditional thermal face recognizers only use the indirect information of the topography of blood vessels like thermogram as features. To overcome this limitation, the proposed thermal face recognizer can use not only the indirect information but also the direct information of the topography of blood vessels which is unique for every human. Moreover, the recognition performance of the proposed thermal features would not decrease even if the hair of frontal bone varies, the eye blinks or the nose breathes. Experimental results show that the proposed features are significantly more effective than traditional thermal features and the recognition performance of thermal face recognizer is improved.

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### 1. Introduction

Personal recognition with computer is important since the need to recognize persons automatically in various areas, such as surveillance, attendance identification, human computer interface, airport security checks, and immigration checks [1,2]. The traditional recognition methods, such as secret code and ID card are no longer able to satisfy the need. Biometric recognition has become an important recognition method [3,4]. Biometric systems work in a similar procedure [5–8]. In the beginning, every user of

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the system is registered into a database with a specified method. A certain characteristic of every user is captured. When a person needs to be identified, the biometric system will compare his/her characteristic with all characteristics stored in the database to find out the possible match. Biometrics use physical characteristic or personal trait to identify the person. Physical characteristics are generally obtained from living human body. The most common physical features used are facial features, eye features (iris and retina), hand geometry, fingerprints and so on [9,10]. Personal traits are more appropriate for applications which need interaction. It is more convenient but less secure. The commonly used personal traits are signature and voices [11,12]. Among these biometric systems, face recognition has become a significant research topic for no physical interaction is required in its operation [13,14].

Most of the face recognition systems used visible image due to the availability of low cost visible band optical cameras. But these

cameras requires external source of illumination because the illumination of environment may dramatically affect the accuracy of result [15,16]. To overcome this limitation, thermal image have been suggested as a solution since it represents the heat radiation from facial skin temperature clearly, even under completely dark environment [17,18]. Facial skin temperature is closely related to the underlying blood vessels which are unique for each human being [19]. Therefore, the thermal face recognizers are excellent candidates for face recognition. A few studies have begun to use thermal image to recognize faces on two aspects. One used distribution of temperature of thermal face image as features, for instance, thermogram [20,21]. The other one used distribution of high and low frequency signals in thermal face image as features, for instance, LBP (Local Binary Pattern) and eigenface which may be preprocessed by DCT (Discrete Cosine Transform) or wavelet or polar [22,23]. Following feature extraction, the extracted features are sent to a classifier for recognition. Neural network is an efficient face recognition classifier and the back-propagation feed-forward learning algorithm is one of the most useful and popular method of neural networks [24].

However, the practical recognition performance is still insufficient. There are three major reasons which are described below.

1. Traditional thermal face recognizers cannot employ facial geometric features which have been used generally and successfully in face recognition of visible face images since thermal face images have lower resolution and higher noise than visible face images.
2. The recognition performance of traditional thermal face recognizers decrease easily when the hair of frontal bone vary, the eye blink or the nose breathe.
3. Traditional thermal face recognizers only use the indirect information of the topography of blood vessels like thermogram as features rather than direct information of the topography of blood vessels.

In this paper, a novel thermal face recognizer which can overcome the three major problems described above is proposed to significantly improve the recognition accuracy. The image preprocessing techniques and extracted features of the recognition scheme are described. A three-layer back-propagation feed-forward neural network is applied as the classifier [24].

The rest of this paper is organized as follows. The recognition algorithm is introduced in Section 2. Experimental results and discussion are presented in Section 3. Section 4 draws the conclusion.

## 2. Recognition algorithm

In this section, procedure of the proposed recognition system is presented and divided into three parts. The three parts are the image preprocessing that segments the face area out of the background, the features extraction that extracts features from a segmented image, and the classification that uses features as inputs to neural network classifier. The image preprocessing part employs Otsu's method to find the optimal binarization threshold for segmenting the background, and then precisely indicates the location of nose tip, eye, and mouth of thermal face image [25]. The features extraction part extracts six kinds of features: (1) the angle of the bridge of the nose, (2) the area of the bridge of the nose, (3) the perimeter of cheek square of face, (4) the temperature distribution statistics of cheek square of face, (5) the location of high temperature area of cheek square of face, and (6) the distance between high temperature area of cheek square of face. The third part, face classifier, uses a back-propagation feed-forward neural network as face classifier. The details of the techniques which are used in these three parts are described in subsequent subsections.

### 2.1. Segments out the background and indicates the location of nose tip, eye, and mouth of thermal face image

In this study, grayscale thermal face image in far-infrared (8–12  $\mu\text{m}$ ) band is captured with lateral as shown in Fig. 1(a). Front face is often captured in traditional face recognition study whether using thermal face image or using visible face image [26,27]. However, thermal face recognition that patterns of blood vessels under skin are critical is much different from visible face recognition that configuration of facial features is critical. Since lateral face not only has no interference from the hair of front bone but also has more complete cheek area which contains most blood vessels under facial skin, lateral of thermal face is used for recognition in this study.

Grayscale image (as seen in Fig. 1a) is converted into binary image (as seen in Fig. 1b) in order to segment the background, and then precisely indicates the location of nose tip, eye, and mouth of thermal face image. Otsu's method is adopted to find the optimal binarization threshold  $k^*$  [25]. Threshold  $k^*$  used to transfer grayscale image  $f(x, y)$  to binary image  $g(x, y)$  is given by

$$g(x, y) = \begin{cases} 0 & \text{if } f(x, y) \leq k^* \\ 1 & \text{if } f(x, y) > k^* \end{cases}$$

Although the outline of the top of the head is not clear, the outline of the nose, eye and mouth is in clear shape in Fig. 1(b). Thus, the exact location of the nose tip, eye and mouth can be labeled. Further, a precise and complete cheek square of thermal lateral face image can be determined, as described in Section 2.4. When image is scanned with column from left to right and pixels are scanned from top to bottom in a column, the nose tip is the first pixel which has gray value. As soon as the nose tip is found, eye is the first trough in vertical direction from nose tip to top of the image. Similarly, mouth is second trough in vertical direction from nose tip to bottom of the image as shown in Fig. 1(b).

### 2.2. The angle of the bridge of the nose

The angle of the bridge of the nose varies from person to person especially for different races. After the location of nose tip, eye, and mouth of thermal face image are precisely indicated in Section 2.1, the angle of the bridge of the nose can be found. As can be seen in Fig. 2 which is part area of Fig. 1(b), the included angle  $\theta$  is included by  $y_1$  which connects eye to nose tip and  $y_2$  which connects eye to mouth. Consequently, the included angle  $\theta$  can represent the angle of the bridge of the nose and does not be influenced by hair style. Further,  $\theta$  hold with the same person even though there is some tilt of chin or there is different distance between capturing instrument and face.

### 2.3. The area of the bridge of the nose

The area of the bridge of the nose varies much from person to person even for same races. As soon as the straight line  $y_1$  which connects eye to nose tip are determined in Section 2.2, the area of the bridge of the nose can be found. As can be seen in Fig. 2, the area  $A$  can represent the area of the bridge of the nose and does not be influenced by hair style. This feature  $A$  can be obtained with few calculations which calculate the number of pixels locating above  $y_1$ . This feature depends on distance between capturing instrument and face. The thermal images were normalized to same size in order to avoid this effect.

### 2.4. The perimeter of cheek square of face

After the method that indicates the precise ambit of cheek at thermal lateral face is define and described as follows, the perimeter of cheek square of face can be calculated.

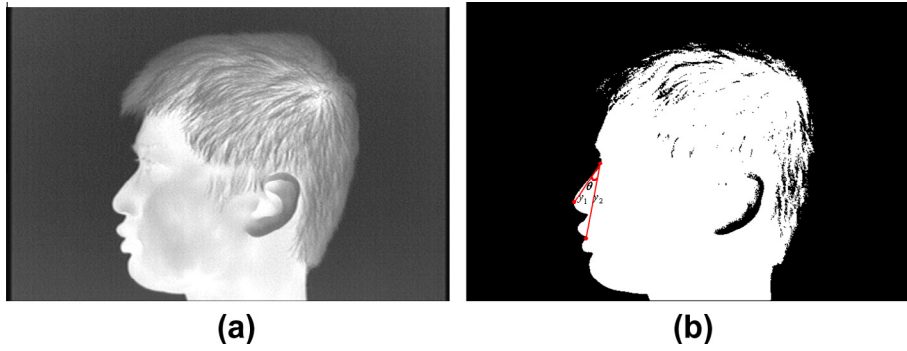


Fig. 1. Thermal lateral face and corresponding binary image. (a) Grayscale image of thermal lateral face. (b) Corresponding binary image.

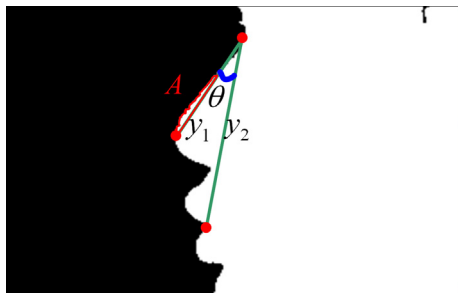


Fig. 2. The angle of the bridge of the nose  $\theta$  and the area of the bridge of the nose  $A$ .

Human faces are naturally symmetric and even the profiles follow geometric rule. Since the location of eye, nose tip and mouth have been identified by the method that is described in Section 2.1, cheek square at thermal lateral face image can be define clearly. As can be seen in the Fig. 3, cheek square at thermal lateral face image is circled. The left boundary of cheek is twice distant as the distance from nose tip to mouth. The vertical distance from mouth to the bottom boundary of cheek is half of the distance from nose

tip to mouth. The top boundary of cheek is middle of the distance from nose tip to eye. Every side of cheek square has the same length.

The location and dimension of cheek squares on different faces are different because the geometric length of different faces are different. Therefore, the perimeter of cheek square of face is an efficient feature to recognize face. This feature can be obtained with few calculations by calculating the number of pixels of the cheek square.

2.5. The temperature distribution statistics of cheek square of face

Individual cheek has individual representation of temperature which is according to the topography of blood vessels of cheek. Cheek square at thermal lateral face image which can represent temperature has been circled in Fig. 3. The gray value pixels in cheek square are converted to corresponding temperature value according to the formula provided by the far-infrared capturing instrument.

Before gather temperature distribution statistics of cheek square, the temperature range is set from 30.5 °C to 33.5 °C. The range is divided into nine sections with the interval 0.375 °C;

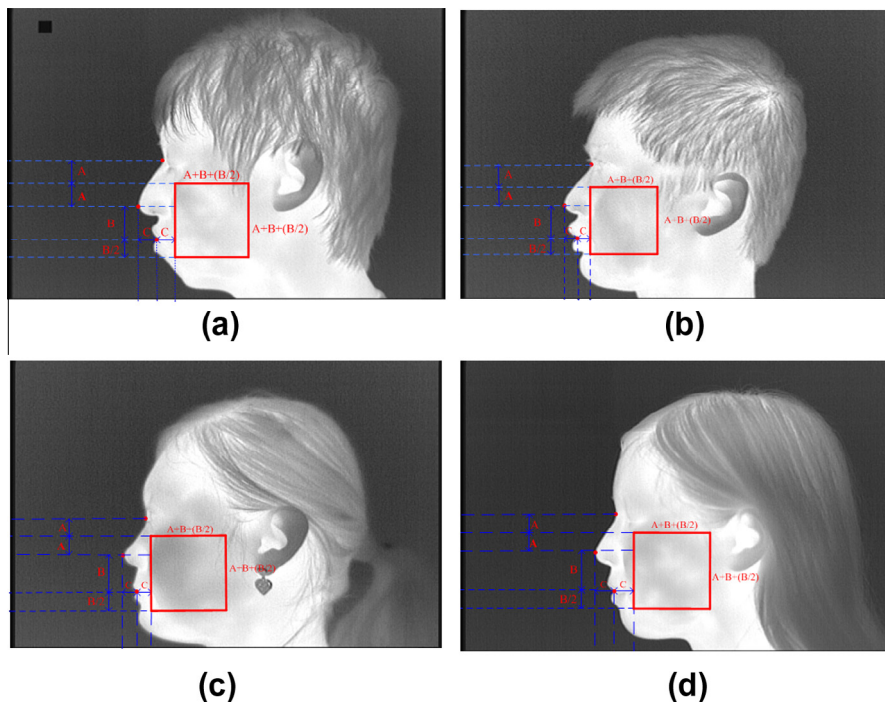


Fig. 3. The ambit of individual cheek square at thermal lateral face image.

therefore, the center is 32 °C which is the average temperature of skin. The corresponding temperature of all pixels of the cheek square is divided into these nine sections. Temperature which is higher than 33.5 °C is made into one section; similarly, temperature which is lower than 30.5 °C is made into one section.

As shown in Fig. 4, temperature distribution statistics of cheek square of different person are made. The number of pixels of each temperature section in cheek square is calculated. The *x*-axis coordinate represents the temperature section, and *y*-axis coordinate record the number of pixels within each temperature section.

2.6. The location of high temperature area of cheek square of face

The distribution of high temperature area of cheek is according to the blood vessels which transport warm blood throughout the cheek. The distribution of high temperature area of cheek is unique since the topography of blood vessels of cheek is different even at identical twins [28]. Therefore, the locations of two highest temperature areas which are the direct information of the topography of blood vessels are identified in this section.

Histogram is calculated from cheek of thermal image since the gray value in thermal image is positive relative to temperature. Histogram records the number of pixels of each gray value in a thermal image. As shown in Fig. 5, brightest 10% pixels of histogram are retained in thermal image. Thermal image is converted into binary image by setting brightest 10% pixels with 1 (white) and setting else pixels with 0 (black).

After thermal image is converted into binary image, the two highest temperature areas can be extracted using “8-connected component labeling” algorithm as shown in Fig. 6 [29]. In “8-connected component labeling” algorithm, a pixel is considered as connected when it has neighbors on the same row, column and diagonal.

The cheek square is divided into nine sub-blocks which are numbered.

The locations of first largest and second largest area in cheek square are identified individually. When the retained areas pass through sub-blocks, the sub-block which has more valued pixels is chosen. Since every sub-blocks of cheek square has 11% pixels of cheek square and only 10% pixels are retained, a retained area must belong to a sub-block.

2.7. The distance between high temperature area of cheek square of face

Topography of blood vessels emerges from not only the locations of high temperature areas but also the distance between high temperature areas. The temperature is positive relative to gray value in thermal image. Therefore, the distance between two largest components with high gray value are identified in this section. As can be seen in Fig. 7, the two largest components with high gray value of cheek square are chosen by the method which has been described in Section 2.6.

In order to measure the distance between two largest components in the binary image, centroid of each component (*X*,*Y*) is calculated by

$$X = \frac{\sum_x \sum_y g(x,y)x}{\sum_x \sum_y g(x,y)} \tag{2}$$

$$Y = \frac{\sum_y \sum_x g(x,y)y}{\sum_y \sum_x g(x,y)}$$

where *x*, *y* are the coordinate of the binary image and *g*(*x*,*y*) is the intensity value, that is, *g*(*x*,*y*) = 0 or 1 [30]. As soon as the centroids of two largest components are measured, the distance *D* between two largest components is calculated by

$$D = \sqrt{(X_1 - X_2)^2 + (Y_1 - Y_2)^2} \tag{3}$$

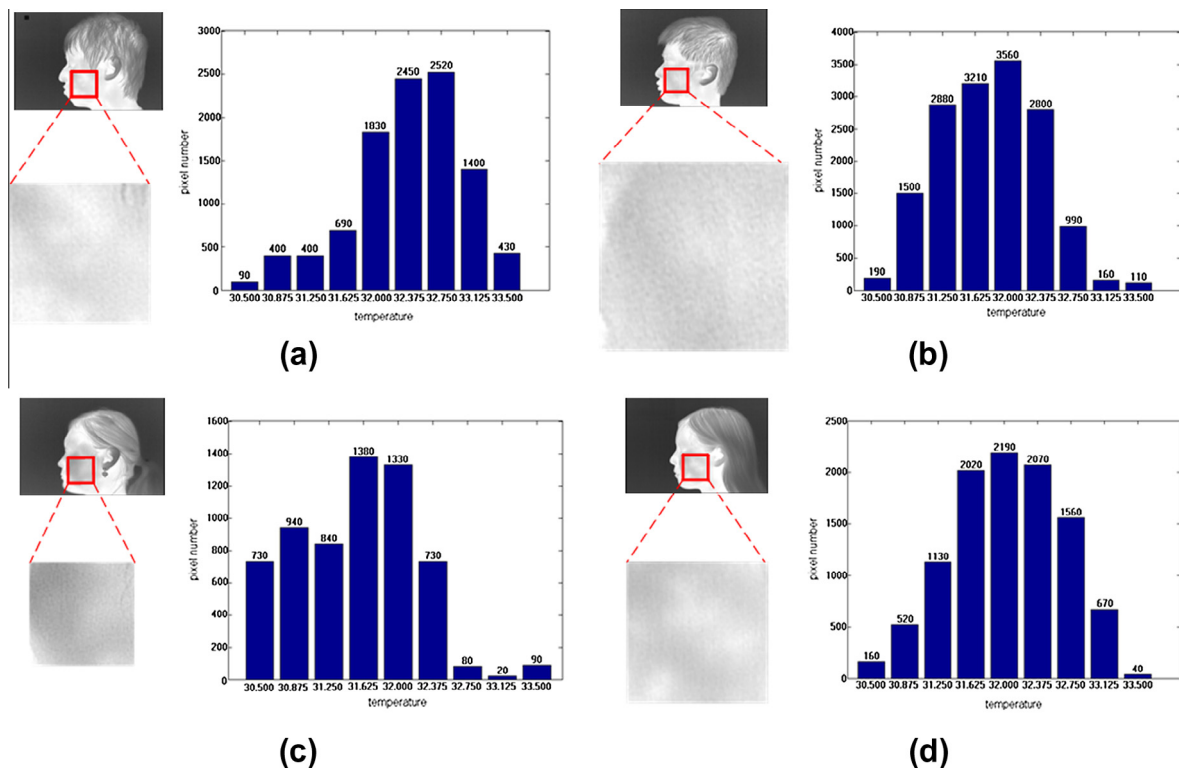
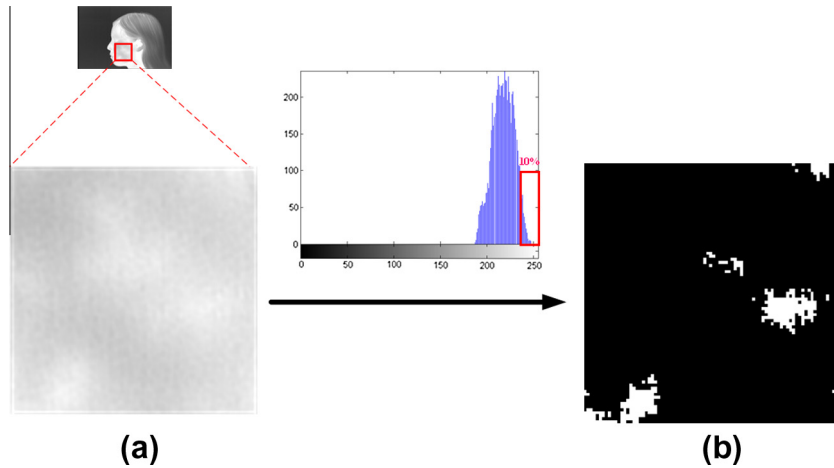
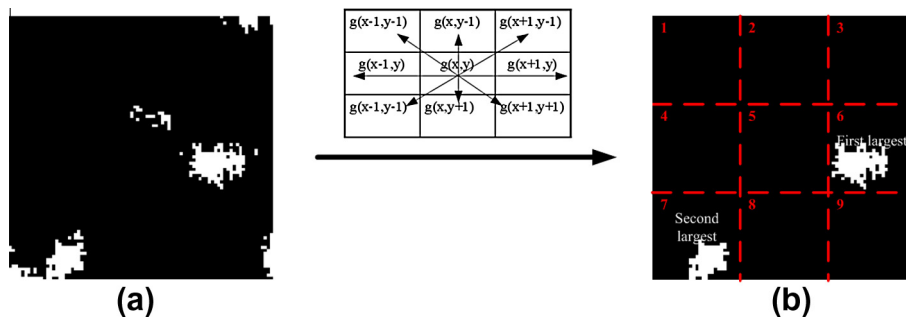


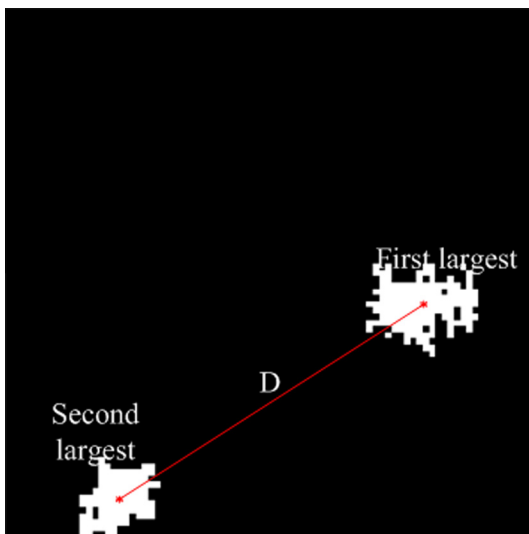
Fig. 4. Temperature distribution statistics of cheek square.



**Fig. 5.** Choose pixels from brightest 10% pixels of histogram of cheek square. (a) Thermal image of cheek square. (b) Binary image with brightest 10% pixels of histogram of cheek square.



**Fig. 6.** Define component using “8-connected component labeling” algorithm and then extract the two largest component. (a) The brightest 10% pixels can be divided with “8-connected component labeling” algorithm. (b) The two largest components of brightest 10% pixels of histogram of cheek square.



**Fig. 7.** As soon as the centroids of two largest components are measured, the distance  $D$  is calculated.

where  $(X_1, Y_1)$  and  $(X_2, Y_2)$  are the coordinate of centroids of two largest components.

### 3. Experimental results and discussion

Sixty persons are involved in Infrared face image for our database. Each of the sixty persons is taken six pictures in different

day. Therefore, there are 360 images of thermal lateral face, and each image has size  $720 \times 480$ . One hundred eighty images of them are used to form training set, and the other one hundred eighty images of them are used to form testing set. Some example images of the dataset are shown in Fig. 8.

Three kinds of Experiment which use different features are performed as shown below. In each experiment, back-propagation feed-forward neural network is applied as the classifier. The neural network is three layers which are input layer, hidden layer and output layer. The number of neurons of input layer is decided by the number of used features. Since 12, 13 and 15 features are used respectively for three different experiments, the number of neurons of input layer are 12, 13 and 15 respectively for three different experiments. The number of neurons of output layer is decided by the number of participated persons which is 60. The number of neurons of hidden layer is decided by

$$N_{hidden} = \frac{N_{input} + N_{output}}{2} \quad (4)$$

where  $N_{hidden}$ ,  $N_{input}$  and  $N_{output}$  is the number of neurons of hidden layer, the number of neurons of input layer and the number of neurons of output layer respectively.

The learning speed  $\eta$  is set to 0.6 in this study. Besides, the neural network employs momentum  $\alpha$  to make weight changes be equal to the sum of a fraction of the last weight change and the new change. Momentum allows the network to react to local gradient in the error surface, and it ranges between 0 and 1. The momentum  $\alpha$  is set to 0.5 in this study.





Fig. 8. Some example images of the dataset.

3.1. Experiment I

In this experiment, all thermal features of cheek which are described in Sections 2.5–2.7 are used to be input features. That is the nine temperature distribution statistics, the location of high temperature area and the distance between high temperature areas. Thus, there are 12 input features and 12 input neurons of the neural network. The hidden layer and output layer have 36 and 60 neurons, respectively. The recognition result for the testing samples is shown in Table 1. The control group uses traditional thermal features which are extracted from whole face and uses same architecture of neural network classifier as this study [31]. In the Ref. [31], traditional thermal features which are extracted from whole face are presented. The thermal image of whole face is processed with Haar wavelet transform and the LL band and the average of LH/HL/HH bands subimages are created for face image. Then a total confidence matrix is formed for the thermal image of whole face by taking a weighted sum of the corresponding pixel values of the LL band and average band. The total confidence matrix is used as a feature vector and is fed into neural network classifier. The recognition performance of the proposed thermal features of cheek and the traditional thermal features which are presented in Ref. [31] is evaluated by the precision and recall which are defined as

$$\text{precision} = \frac{|\{\text{relevant documents}\} \cap \{\text{retrieved documents}\}|}{|\{\text{retrieved documents}\}|} \tag{5}$$

$$\text{recall} = \frac{|\{\text{relevant documents}\} \cap \{\text{retrieved documents}\}|}{|\{\text{retrieved documents}\}|} \tag{6}$$

Precision represents the ability of a measurement to be consistently reproduced. Recall represents the ability to remember experiences. Therefore, precision and recall can be calculated by

$$\text{precision} = \frac{TP}{TP + FP} \tag{7}$$

$$\text{recall} = \frac{TP}{TP + FN} \tag{8}$$

where TP, FP and FN represent True Positive, False Positive and False Negative of recognition results respectively.

As can be seen from Table 1, the proposed thermal features of cheek have significantly higher recognition performance than traditional thermal features.

Table 1  
The recognition result for experiment I.

	Precision (%)	Recall (%)
Traditional thermal features which are extracted from whole face	85	87
Thermal features of cheek proposed by this study	90	89

3.2. Experiment II

In this experiment, cheek correlative features which are described in Sections 2.4–2.7 are used to be input features. That is the perimeter of cheek square, the nine temperature distribution statistics, the location of high temperature area and the distance between high temperature areas. Thus, there are 13 input features and 13 input neurons of the neural network. The hidden layer and output layer have 37 and 60 neurons, respectively. The recognition result for the testing samples is shown in Table 2. The control group is the same control group in experiment I. The recognition performance of experimental group in experiment II is slightly higher than it in experiment I, since the perimeter of cheek square has been acceded as a feature for classifier in experiment II.

3.3. Experiment III

In this experiment, the all thermal features and facial geometric features which are described in Sections 2.2–2.7 are used to be input features for the proposed recognizer. That is the angle of the bridge of the nose, the area of the bridge of the nose, the perimeter of cheek square, the nine temperature distribution statistics, the location of high temperature area and the distance between high temperature areas. Thus, there are 15 input features and 15 input neurons of the neural network. The hidden layer and output layer have 38 and 60 neurons, respectively. The recognition result for the testing samples is shown in Table 3. The control group is the same control group in experiment I. The precision and recall of the proposed recognizer reach 97% and 92% respectively.

Fig. 9 shows the summary of the experiments. Since the proposed thermal features which can directly represent the topography of blood vessels of face are used in experimental group I, the precision and recall are significantly higher than control group. The rising of precision is faster than the recall in the three experimental groups. The precision rises fastest and reaches highest when the critical facial geometric features which would not be

Table 2  
The recognition result for experiment II.

	Precision (%)	Recall (%)
Traditional thermal features which are extracted from whole face	85	87
Cheek correlative features proposed by this study	92	90

Table 3  
The recognition result for experiment III.

	Precision (%)	Recall (%)
Traditional thermal features which are extracted from whole face	85	87
Proposed recognizer	97	92

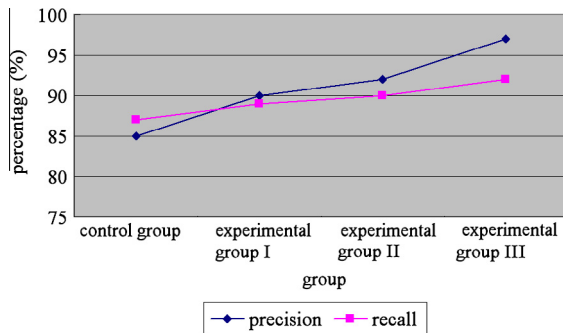


Fig. 9. The recognition result for the experiments.

influenced by hair style are involved in experimental group III. In addition, the precision is higher than the recall in the three experimental groups, whereas the precision is lower than the recall in the control group. Therefore, the proposed features are more conscientious and careful than traditional thermal features which are extracted from whole face because precision represents the ability of a measurement to be consistently reproduced and recall represents the ability to remember experiences. This property is quite suitable for personal recognition of access control system.

#### 4. Conclusions

In this paper, we proposed a novel hybrid neural network face classifier with the facial geometric features and the thermal features. First of all, grayscale thermal face image of far-infrared is captured with lateral, and the image preprocessing technology segments the face area out of the background. Then, several features are extracted from the processed face image. The facial geometric features which are extracted from nose and cheek include the angle of the bridge of the nose, the area of the bridge of the nose, and the perimeter of cheek square of face. The thermal features which are extracted from the cheek square of face include the temperature distribution statistics, the location of high temperature area, and the distance between high temperature areas. Finally, back-propagation neural network is used as classifier.

As documented in the experimental results, the proposed recognizer significantly improves the recognition performance. Possible explanations are:

1. Traditional thermal face recognizers can only use thermal features but facial geometric features, since thermal face image have lower resolution and higher noise than visible face image so that the facial geometric features are difficult to identify. However, the proposed method can indicate the location of nose tip, eye, and mouth from thermal face image precisely so that it extracts not only the thermal features but also two critical facial geometric features which would not be influenced by hair style to improve the recognition performance.
2. Traditional thermal face recognizers usually extract thermal features from whole face. Hence, the recognition performance decreases easily when the hair of frontal bone varies, the eye blinks or the nose breathes. However, the proposed method identifies the cheek area accurately and extracts thermal features from cheek absorbably. Therefore, the recognition ability of the thermal features which are extracted in this study would not decrease when the hair of frontal bone varies, the eye blinks or the nose breathes. Furthermore, the cheek area which is identified in this study is bigger and more complete than the traditional thermal face recognizers. Therefore, the temperature response of the topography of blood vessels of cheek is more

obvious than tradition so that the proposed thermal features are more representative and can be extracted easily to improve the recognition performance.

3. The topography of blood vessels of face is unique even for identical twins. Traditional thermal face recognizers only use the indirect information of the topography of blood vessels, like thermogram as features. However, the proposed method uses not only the indirect information, like thermogram, but also the direct information of the topography of blood vessels, such as the location of high temperature area and the distance between high temperature areas. Therefore, the recognition performance is significantly improved.

However, the proposed method is only applicable to lateral views without glasses.

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