

Three electrodes touch-mode capacitive pressure sensor

K-M. Chang, G-J. Hwang, Y-L. Hsien

Abstract A three-electrode capacitive pressure sensor for touch-mode operation with sensitivity of 0.030 pF/kPa (or 10.4 mV/kPa using CP-10 C/V converter circuit) in the pressure range of 170–280 kPa is presented with theoretical explanation of experimental results. A special ring structure is designed to integrate a sensing capacitor and a reference capacitor into the same cavity to partially cancel out the temperature effect. A third electrode is included to eliminate two-level connections without reducing its pressure sensitivity. The sensor offers the advantages of simple fabrication processes, planar connections, as well as high sensitivity, near-linear output, and large over-range pressure.

1

Introduction

The usual capacitive sensors are parallel plate capacitors composed of silicon diaphragm and metal electrode on the insulating substrate. When a pressure is applied, the diaphragm deforms and the sensor capacitance will change accordingly. The capacitance-to-pressure characteristics of the sensor are nonlinear due to the inverse dependence of capacitance on the gap separation [Hanneborg and Ohlckers (1990)]. Specific compensation circuits and modifications to the sensor structure have been applied to reduce the nonlinearity [Puers et al. (1990), Rosengren et al. (1992)]. However, these approaches increase the complexity in either the circuitry or in fabrication processes. A simple and effective method that can be applied to the conventional capacitive sensors to improve linearity is to allow the diaphragm to touch the bottom-insulated electrode [Ding et al. (1990), Ko et al. (1996)]. The increased linearity after touch point pressure is supposed to be due to the nonlinearity of the pressure–capacitance relation being compensated by the membrane becoming more rigid [Rosengren et al. (1992)].

In the literature [Pons et al. (1993), Ko et al. (1982), Schnatz et al. (1992)], two capacitors on the same sensor assembly are necessary for capacitive sensor detecting circuits in order to

compensate the environmental changes and to achieve differential measurement. In general, this approach will increase the sensor size for the dual capacitor design and need additional connections between the electrodes of sensing and reference capacitors. The two-level connections between the electrodes of sensing and reference capacitors. The two-level connections for top and bottom electrodes could be avoided by splitting the capacitors into two parts and connecting in series by the metallization on the plate [Schnatz et al. (1992)]. This arrangement will reduce the capacitance value due to the series connection and hence decrease the sensor sensitivity. In this paper, as shown in Fig. 1, we will present a capacitive pressure sensor for touch mode operation with a special structure design that will allow the integration of two capacitors in a sensor cell without decreasing the sensor sensitivity for planar connections.

2

Sensor design

For the design of touch-mode pressure sensor, a computer simulation program has been developed at Case Western Reserve University to accurately simulate the performance of touch mode sensors using the finite element analysis with modified boundary conditions [Ko et al. (1996)]. Their results are used as a reference in our sensor design.

Their simulation curve of normalized deflection ratio (w_0/h) against the normalized pressure (Pa^4/Eh^4) for square diaphragm can be used for touch point pressure estimation, where w_0 is the center deflection of diaphragm; h , the diaphragm thickness; P , the differential pressure; a , the length of square diaphragm; E , the Young's modulus. The touch point pressure P_0 is determined by letting the center deflection w_0 equal the cavity gap g . The touch mode pressure sensor is designed to operate in the linear region ($1.2P_0$ to $2P_0$) after touch-point pressure P_0 . A sensor with touch-point pressure of 0.4 atm differential pressure, between the applied and cavity pressure, can be obtained as the diaphragm parameters, $h = 5 \mu\text{m}$, $a = 700 \mu\text{m}$, and $g = 3 \mu\text{m}$ are provided.

According to the simulation results for near-linear operation, the maximum touched length of the diaphragm, at full-scale pressure, is about 70% of the total length of the diaphragm, at full-scale pressure, is about 70% of the total length of the diaphragm. This implies that the touched area of the sensor under full-scale pressure is about 49% of the diaphragm area. Therefore, two capacitors (C_{ap} and C_{bp} defined below) can be placed by a ring structure in one cavity as shown in Fig. 1. The central area is used as the sensing capacitor and

K-M. Chang, G-J. Hwang, Y-L. Hsien
Department of Electronics Engineering, National Chiao Tung University, 1001, Ta Shueh Road, Hsinchu, Taiwan ROC

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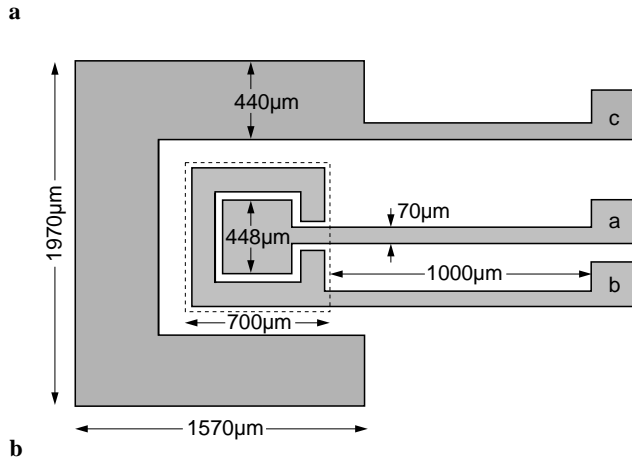
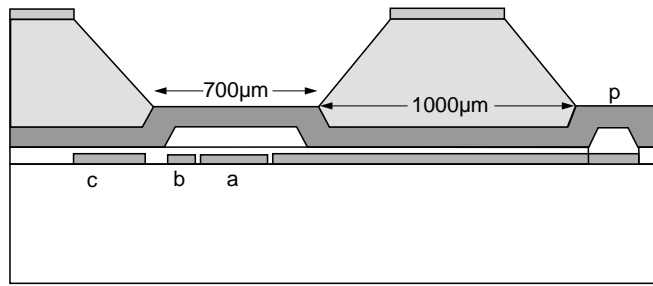


Fig. 1a,b. A schematic drawing of the three electrodes capacitive pressure sensor: a cross-section view b top view

the edge area as the reference capacitor. Normally, the electrode contact on p^+ silicon diaphragm is needed. The design of our sensor avoids the need of contacting the electrode on the silicon diaphragm by connecting the capacitors in the cavity in series with a large capacitor (C_{pc}) located at the edge under the bonding area. As can be found in Fig. 1, the capacitor C_{ac} is the series connection of C_{ap} and C_{pc} and the C_{bc} is the series connection of C_{bp} and C_{pc} . The electrode connections for C_{ac} and C_{bc} are planar connections. The large capacitor C_{pc} is composed by the p^+ silicon plate and the metal plate on the Pyrex substrate with a thin glass layer that is also used as the insulating layer in the cavity. The large value in capacitance is owing to the high dielectric constant of glass, thin glass spacing and large size.

3 Fabrication

The sensors are fabricated using bulk micromachining technique with four masks. The fabrication sequence, illustrated in Fig. 2 at key stages, involves both silicon and glass processing.

N-type, (100) oriented, double-side polished, 4-in silicon wafer with thickness 480 μm is used as top wafer. After initial cleaning, a 1 μm silicon dioxide is grown by wet oxidation at 1000 $^\circ\text{C}$ for 5 h. The oxide film on the front side of silicon wafer is patterned by standard photolithography and wet-etched in BHF to open window for the cavity formation. The wafer is then immersed in a 33 wt% KOH solution at 60 $^\circ\text{C}$ for 10 min to form cavities of thickness 3 μm in depth (Fig. 2a). After cavity formation, the oxide film of the front side is etched off and the

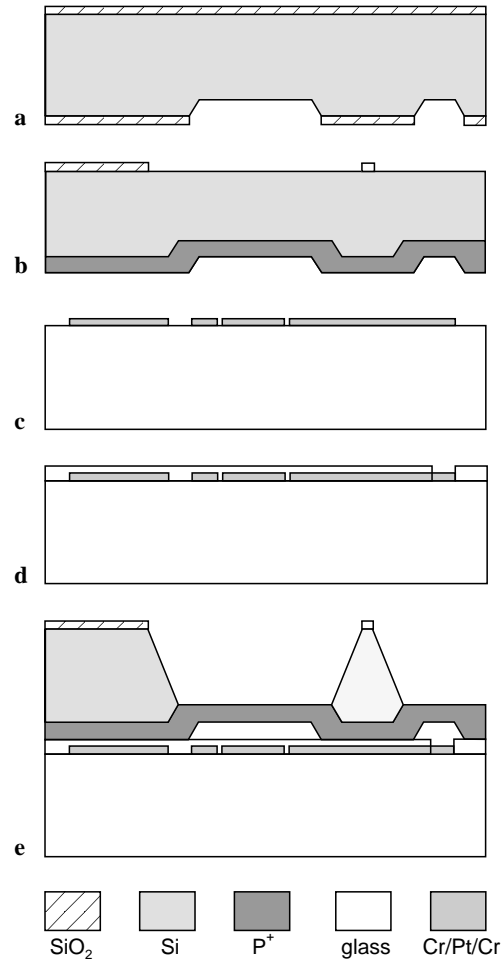


Fig. 2a–e. The fabrication sequence at key stages

oxide film on the backside is protected by photoresist during oxide etching. This oxide film of the backside is used as a mask for the boron diffusion. Next, boron diffusion is carried out at 1125 $^\circ\text{C}$ in a gas mixture of 98% N_2 and 2% O_2 for 6 h with boron nitride disk as the diffusion source. A 5 μm p^+ layer is formed on the front side of the silicon wafer [Chang et al. (1998)]. After boron diffusion, steam oxidation is performed at 800 $^\circ\text{C}$ for 30 min in order to remove the boron silicate glass (BSG) formed during diffusion. The BSG film and the backside oxide film are then patterned and etched to open the windows for the diaphragm formation (Fig. 2b).

Double-side polished, 4-in Pyrex 7740 glass wafer with thickness 500 μm is used as the bottom wafer. The lift-off technique is used in the glass processing. After glass cleaning, a stencil layer of photoresist is patterned on the glass wafer. A multi-metal film (5 nm Cr/250 nm Pt/5 nm Cr) is deposited on the inverted pattern of the stencil layer and the exposed area by electron beam evaporation. After evaporation, a mixture of H_2SO_4 and H_2O_2 is used to lift-off the stencil layer. The multi-metal film with the desired pattern is left on the glass wafer and forms the bottom plate of the capacitor and the output feedthrough (Fig. 2c). This multi-metal film offers several advantages of reliable interconnect materials with low resistance, good adhesion to the glass, inert reaction to silicon

etchant KOH and oxide etchant. The sheet resistance of this multi-metal film is measured to be 20Ω per square. A glass film of Pyrex 7740 with thickness $0.6 \mu\text{m}$ is then sputtered on the top of the multi-metal diaphragm touched the bottom plate of the metal film and dielectric material of capacitors. After glass sputtering, the contact windows of bonding pads are opened by standard photolithography and wet etching (Fig. 2d).

The prepared top silicon wafer and the glass wafer are aligned and then anodically bonded together. These bonded pair of silicon and glass wafers is then immersed into a 20 wt% KOH at 60°C , in considerations of Si/oxide selectivity and etch rate, and is etched from the backside of silicon to form the diaphragm (Fig. 2e) [Seidel et al. (1990)]. After completion of backside etching, the wafer is diced into individual chip for pressure testing.

4 Testing system

The layout of the test system is shown in Fig. 3. It includes a compressed air tank, a pressure control system, a mechanical pump, a high-pressure chamber, and a capacitance measurement system. The capacitance measurement system includes two measurement units: a capacitance bridge and a CP-10 circuit. A switch is used to select the measurement unit. The CP-10 circuit is a capacitance-to-voltage converter using switched capacitor circuit [Ko and Yeh (1994)]. The block diagram of the CP-10 is shown in Fig. 4. It consists of a voltage, capacitance, and frequency controlled current source (VCFCl), a charge substrator (Σ), and a current-to-voltage converter (R). When $C_f \cdot f \cdot R \gg 1$, the output voltage V_{out} could be determined as

$$V_{\text{out}} = [(V_g \cdot C_x) - (V_o \cdot C_o)] / C_f \quad (4.1)$$

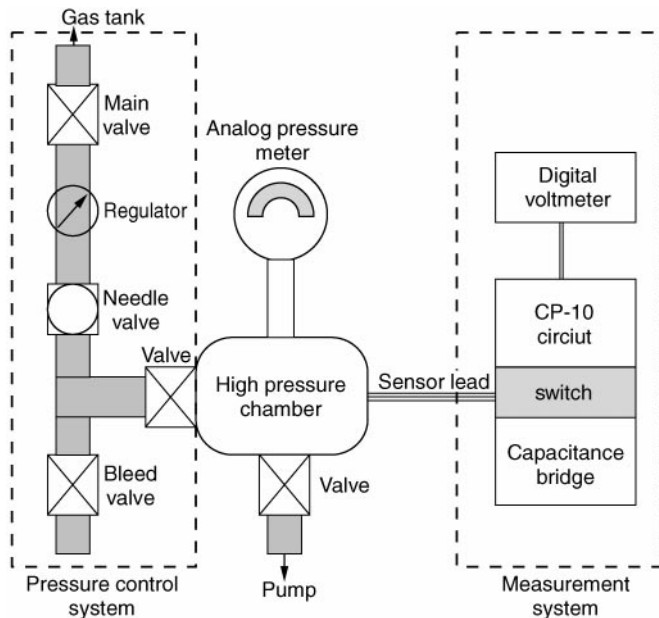


Fig. 3. The layout of test system

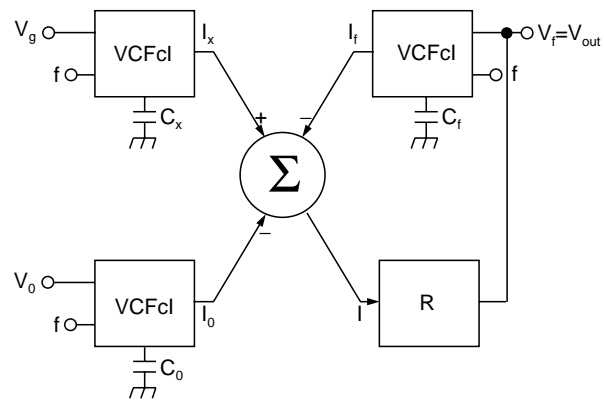


Fig. 4. The block diagram of the CP-10 converter circuit [after Ko (1994)]

where V_g and V_o are the adjustable voltages, C_x is the sensor capacitance, C_o the total internal and external offset capacitor, and C_f the external feedback capacitor. The circuit sensitivity, S_c , can be defined as

$$S_c = \frac{dV_{\text{out}}}{dC_x} = \frac{V_g}{C_f} \quad (4.2)$$

This implies that the circuit sensitivity S_c can be controlled by varying V_g or C_f and is not affected by the stray capacitance. Besides, the offset can be adjusted by changing V_o or C_o without affecting the sensitivity. The sensor fabricated has three terminals on the glass substrate and one connection on the p^+ diaphragm. Referring to Figs. 1 and 4, the electrode “a” is for the sensing capacitor C_x , electrode “b” is for the reference capacitor C_o and the electrode “c” is connected to the ground. If one sensing capacitor C_x on the sensor is used, a conventional external capacitor will be used as C_o for offset adjustment. Otherwise, the central capacitor is used as the sensing capacitor C_x and the edge reference capacitor is used as C_o for offset adjustment.

5 Results and discussion

In order to verify the operation of the ring structure of the sensor, an electrical contact on the p^+ silicon layer is connected. Five capacitance outputs of the capacitors C_{ap} , C_{bp} , C_{ac} , C_{bc} and C_{ab} are measured by the Capacitance Bridge. These capacitances are defined as follows:

- C_{ap} the capacitance between the central sensing plate on the glass denoted by “a” and the silicon p^+ plate denoted by “p”
- C_{bp} the capacitance between the edge reference plate on the glass denoted by “b” and the silicon p^+ plate
- C_{ac} the capacitance between sensing “a” and “c” electrodes. It is the series capacitance of the sensing capacitance C_{ap} and the large capacitance C_{pc} (the large capacitance between the silicon p^+ plate and the metal plate at the clamped area on the glass denoted by “c”)
- C_{bc} the capacitance between reference “b” and “c” electrodes. It is the series capacitance of the reference capacitance C_{bp} and the large capacitance C_{pc}

C_{ab} the capacitance of the sensing electrode “a” and the reference electrode “b”. It is the series capacitance of C_{ap} and C_{bp} in parallel with the parasitic capacitance between “a” and “b” electrodes on the glass substrate C_{abs}

The connections of C_{ap} and C_{bp} are the two-level connections and those of C_{ac} , C_{bc} , and C_{ab} are the planar connections.

Four voltage outputs, namely V_{ab-p} , V_{ab-c} , V_{ap} , and V_{ac} , are also measured by the CP-10 circuit. These voltage outputs are defined as follows:

- V_{ab-p} the output voltage from CP-10 as connecting the C_{ap} as the C_x and the C_{bp} as the C_o on the CP-10 circuit board
- V_{ab-c} the output voltage from CP-10 as connecting the C_{ac} as the C_x and the C_{bc} as the C_o
- V_{ap} the output voltage from CP-10 as connecting the C_{ap} as the C_x and a conventional capacitor as the C_o .
- V_{ac} the output voltage from CP-10 as connecting the C_{ac} as the C_x and a conventional capacitor as the C_o

5.1

Capacitance output

Figure 5 presents the measured capacitance-to-pressure characteristics of the five capacitors at 25°C. The pressure inside the sensor cavity is 1 atm (101 kPa) because it sealed at 1 atm and 25°C. As shown in Fig. 5, the measured capacitance C_{ap} at zero differential pressure between the applied and cavity pressure is 12.249 pF. This measured capacitance 12.249 pF is larger than the calculated capacitance 0.6 pF for the center capacitor inside the cavity with electrode area $448 \mu\text{m} \times 448 \mu\text{m}$, cavity gap $3\text{e} \mu\text{m}$, and air dielectric constant. The difference between 12.249 and 0.6 pF is due to the existence of two capacitances that are connected in parallel with the capacitors inside the cavity. The first one is the capacitance of the metal film feedthrough located at the bonding area from

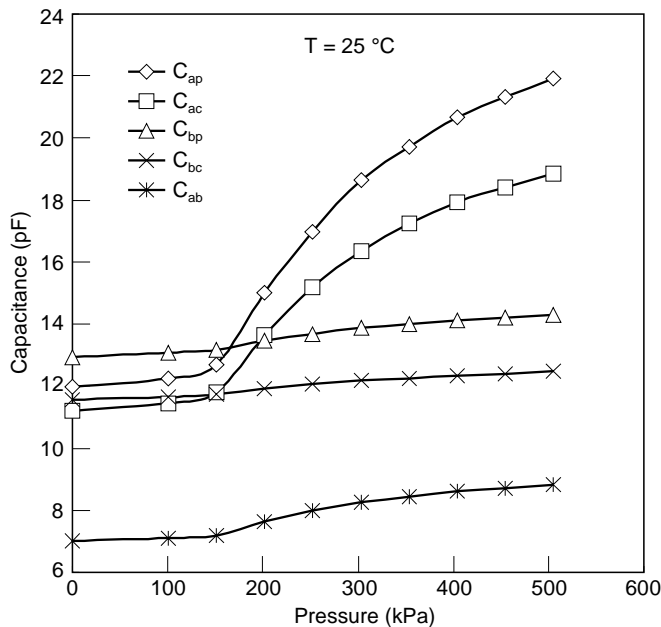


Fig. 5. The capacitance-to-pressure characteristics of the sensor

the electrode inside cavity to the contact pad. The other is the stray capacitance of test system from the sensor contact pad to the Capacitance Bridge in the test system. The metal film feedthrough capacitance is estimated to be 5.5 pF and the stray capacitance of the test system is measured to be 6 pF. The metal film feedthrough with area of length $1000 \mu\text{m}$ and width $70 \mu\text{m}$, as shown in Fig. 1b, and the p^+ silicon layer with a $0.6 \mu\text{m}$ glass layer between them form a capacitor that is connected in parallel with the capacitors inside the cavity. The $1000 \mu\text{m}$ length of metal film feedthrough is needed for a silicon wafer with thickness $480 \mu\text{m}$ etched in KOH for the openings of the diaphragm and contact pads. This metal film feedthrough capacitor is similar to the capacitor C_{pc} under the bonding area but has small area. According to the sensor design, the area of C_{pc} is 24 times the area of metal film feedthrough capacitor. The measured capacitance of C_{pc} is 140 pF including the stray capacitance of test system 6 pF. This gives that the capacitance of metal film feedthrough is 5.5 pF ($\approx 134/24$). The area of capacitor C_{bp} inside cavity is designed to be nearly equal to, but slightly larger than, the area of the capacitor C_{ap} . Therefore, the measured capacitance of C_{bp} at zero differential pressure is 13.069 pF as illustrated in Fig. 5. The capacitance of C_{ac} is the series capacitance of the central sensing capacitance C_{ap} and the large capacitance C_{pc} as

$$C_{ac} = C_{ap} C_{pc} / (C_{ap} + C_{pc}) \quad (5.1)$$

This series connection implies that the capacitance C_{ac} is smaller than the capacitance C_{ap} . The measured capacitance C_{ac} at zero differential pressure is 11.444 pF [$\approx 12.249 \times 140 / (12.249 + 140)$], which is smaller than the measured capacitance C_{ap} of 12.249 pF. Accordingly, the capacitance C_{bc} is the series capacitance of C_{bp} and C_{pc} as

$$C_{bc} = C_{bp} C_{pc} / (C_{bp} + C_{pc}) \quad (5.2)$$

The measured capacitance C_{bc} at zero differential pressure is 11.662 pF [$\approx 13.069 \times 140 / (13.069 + 140)$] that is smaller than the capacitance C_{bp} of 13.069 pF. Finally, the capacitance of C_{ab} is the series capacitance of two nearly capacitance C_{ap} and C_{bp} , plus the parasitic capacitance between “a” and “b” electrodes on the glass substrate C_{abs} as

$$C_{ab} = [C_{ap} C_{bp} / (C_{ap} + C_{bp})] + C_{abs} \quad (5.3)$$

The measured capacitance of C_{ab} is 7.094 pF.

The sensor is designed to have differential touch point pressure 0.4 atm (40 kPa) as discussed in Section 2. The pressure inside the cavity is 1 atm (101 kPa). As can be found in Fig. 5, the center of the diaphragm touches the bottom of the cavity around 141 kPa. After touch point pressure, the values of capacitances C_{ap} , C_{ac} , and C_{ab} increase linearly first and then become saturated in the high-pressure range. The outputs of edge reference capacitors C_{bp} and C_{bc} are almost unchanged as applied pressure because C_{bp} is placed outside the deformed area of the diaphragm. In general, these experimental curves are in good agreement with the sensor design for touch-mode operation.

The average pressure sensitivity of the sensor is determined in the linear region from 170 to 280 kPa after touch-point pressure 141 kPa according to the sensor design. As shown in Fig. 5, the average pressure sensitivity of C_{ac} ($\Delta C_{ac} / \Delta P$) is

0.030 pF/kPa and that of C_{ap} ($\Delta C_{ap}/\Delta P$) is 0.037 pF/kPa. The value of $\Delta C_{ac}/\Delta P$ is about 20% ($=|0.030 - 0.037|/0.037$) less than that of $\Delta C_{ap}/\Delta P$. This difference is again due to the existence of the metal film feedthrough capacitance and the spray capacitance of the test system as discussed before. According to (5.1) along with the pressure-independent capacitance of C_{pc} ($\Delta C_{pc}/\Delta P = 0$) that is located under the bonding area, $\Delta C_{ac}/\Delta P$ becomes

$$\Delta C_{ac}/\Delta P = \frac{\Delta C_{ap}/\Delta P (C_{pc}(C_{ap} + C_{pc}) - C_{ap}C_{pc})}{(C_{ap} + C_{pc})^2} \quad (5.4)$$

The capacitance of C_{ap} at the 225 kPa midpoint-pressure of the operation range from 170 to 280 kPa is 16 pF as shown in Fig. 5. From (5.4) and $C_{pc} = 140$ pF, we have

$$\begin{aligned} \Delta C_{ac}/\Delta P &= \frac{\Delta C_{ap}/\Delta P (140 \times (16 + 140) - 16 \times 140)}{(16 + 140)^2} \\ &= 0.8 \frac{\Delta C_{ap}}{\Delta P} \end{aligned} \quad (5.5)$$

This implied that the smaller the metal film feedthrough capacitance and the stray capacitance of test system as compared to $C_{pc} = 140$ pF, the closer the pressure sensitivity of C_{ac} ($\Delta C_{ac}/\Delta P$) and C_{ap} ($\Delta C_{ap}/\Delta P$) will be. This relatively large value of the metal film feedthrough capacitance and stray capacitance of the measuring system is also the cause of the large discrepancy between C_{ap} and C_{ac} and the poor linearity in the high-pressure range, as illustrated in Fig. 5.

The pressure sensitivity of C_{ab} ($\Delta C_{ab}/\Delta P$) is 0.007 pF/kPa, which is less than the quarter value of the pressure sensitivity of C_{ac} or C_{ap} . This measured result is expected as a consequence of the series connection of C_{ab} . According to the data from Fig. 5, the capacitances of C_{ap} and C_{bp} at the 225 kPa midpoint-pressure of the operation range are 16 and 14.5 pF, respectively, and the capacitance of C_{bp} is insensitive to the applied pressure ($\Delta C_{bp}/\Delta P \cong 0$). The parasitic capacitance between “a” and “b” electrodes on the glass substrate C_{abs} would not be changed significantly with the pressure and could be neglected here. Therefore, $\Delta C_{ab}/\Delta P$ from (5.3) will become

$$\begin{aligned} \Delta C_{ab}/\Delta P &= \frac{\Delta C_{ap}/\Delta P (C_{bp}(C_{ap} + C_{bp}) - C_{ap}C_{bp})}{(C_{ap} + C_{bp})^2} \\ &= \frac{\Delta C_{ap}/\Delta P (14.5 \times (16 + 14.5) - 16 \times 14.5)}{(16 + 14.5)^2} \\ &\leq \frac{1}{4} \frac{\Delta C_{ap}}{\Delta P} \end{aligned} \quad (5.6)$$

The structure of using C_{ab} instead of C_{ap} as sensing capacitor C_x is to avoid the need for contacting the upper electrode on the p^+ layer. This is done by splitting the capacitor C_x into two capacitors C_{ap} and C_{bp} and connecting in series through the p^+ layer [Ko et al. (1982)]. This technique trades the benefit of planar connection at the sacrifice of its sensitivity. However, our special three-electrodes structure using C_{ac} as sensing capacitor and C_{bc} as a reference capacitor offers the advantage of planar connection without decreasing sensitivity and differential sensing to balance out common mode environmental inference.

5.2

Voltage output of CP-10

The voltage output of CP-10, V_{out} , defined in Sect. 4 is given as

$$V_{out} = [(V_g \cdot C_x) - (V_o \cdot C_o)]/C_f \quad (5.7)$$

In the V_{ap} (or V_{ac}) measurements, the central sensing capacitor C_{ap} (or C_{ac}) is connected to C_x with p (or c) connected to the ground of CP-10 and a conventional 17 pF capacitor is connected to C_o of CP-10 for offset adjustment. In the V_{ab-p} (or V_{ab-c}) measurements, the central sensing capacitor C_{ap} (or C_{ac}) is connected to C_x , the edge reference capacitor C_{bp} (or C_{bc}) is connected to C_o for offset adjustment, and p (or c) is the ground. In this study the offset voltage V_o is set to 2.730 V and the circuit sensitivity S_c , V_g/C_f , is kept to a fixed value by setting $V_g = 2.700$ V and $C_f \cong 5$ pF. The output swing is from 1.3 to 4 V of CP-10 for a 5 V power supply.

Figure 6 presents the measured pressure characteristics of output voltages of V_{ap} , V_{ac} , V_{ab-p} , and V_{ab-c} . The curves of V_{ap} and V_{ac} exhibit similar pressure dependence as those of C_{ap} and C_{ac} obtained from the capacitance measurements. However, the discrepancy between the V_{ap} and V_{ac} in the high-pressure range (over 280 kPa) in Fig. 6 is smaller than the discrepancy between the V_{ap} and V_{ac} in the high-pressure range (over 280 kPa) in Fig. 5. This is due to the effect that the CP-10 circuit measures the capacitance difference and does not have the sum of all capacitors as denominator in V_{out} or S_c equation. It could reduce the stray capacitance effect through the offset adjustment of either V_o or C_o . Thus, the outputs of V_{ac} are closer to those of V_{ap} in the high-pressure range and the pressure sensitivity of V_{ac} will be close to the pressure sensitivity of V_{ap} in the operation pressure range. The measured pressure sensitivity of V_{ap} ($\Delta V_{ap}/\Delta P$) is 13.3 mV/kPa

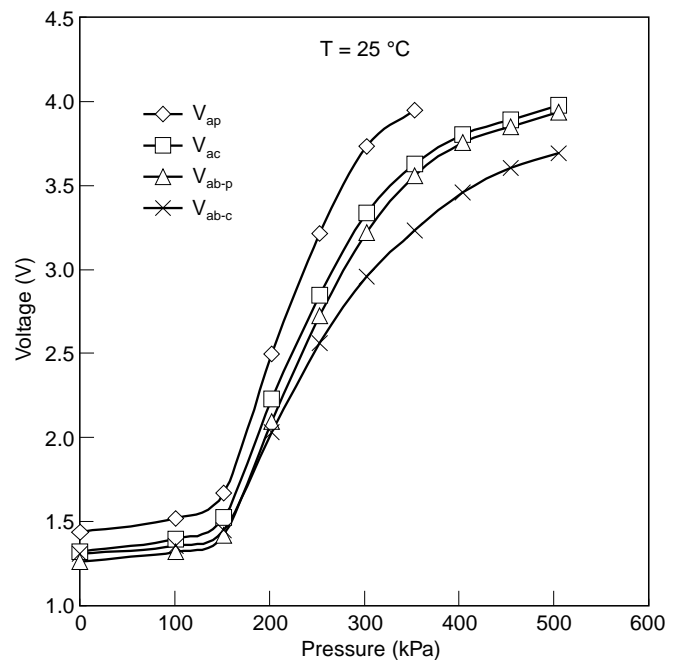


Fig. 6. The voltage-to-pressure characteristics of the sensor

and the pressure sensitivity of V_{ac} ($\Delta V_{ac}/\Delta P$) is 11.8 mV/kPa. Their difference is 10%, while the difference between the pressure sensitivity of C_{ac} and C_{ap} obtained from the capacitance measurements is 20%. In fact, this 10% difference in the pressure sensitivity is theoretically accountable by the planar connections of the ring structure for touch mode operation. In the absence of metal film feedthrough capacitance and stray capacitance of measuring system, the capacitance of C_{ap} in the cavity at 225 kPa would be about 4.5 pF ($=16 - (6 + 5.5)$) and the capacitance of C_{pc} is 134 pF ($=140 - 6$). According to (5.4), the value of $\Delta C_{ac}/\Delta P$ is about 90% of the value of $\Delta C_{ap}/\Delta P$ as

$$\begin{aligned} \Delta C_{ac}/\Delta P &= \frac{\Delta C_{ap}/\Delta P (134 \cdot (4.5 + 134) - 4.5 \cdot 134)}{(4.5 + 134)^2} \\ &\approx 0.9 \frac{\Delta C_{ap}}{\Delta P} \end{aligned} \quad (5.8)$$

The measurements of $\Delta C_{ac}/\Delta P$ and $\Delta C_{cp}/\Delta P$ in (5.8) are made using CP-10 circuit. $\Delta V_{ac}/\Delta P \approx 0.9 \Delta V_{ap}/\Delta P$ was found in the measurements

Also shown in Fig. 6, the pressure sensitivity of V_{ab-c} (ΔV_{ab-c}) is 10.4 mV/kPa, which is less than $\Delta V_{ac}/\Delta P$ value of 11.8 mV/kPa by 10%. In the V_{ab-c} measurements, the C_{bc} is used as C_o in the CP-10 circuit for offset compensation. As the applied pressure increases, the edge reference capacitance C_{bc} would increase slightly ($\Delta C_{bc}/\Delta P = 0.003$ pF/kPa in the pressure range of 170–280 kPa) and therefore cause a slight increase in the “offset voltage” ($=V_o \cdot C_{bc}/C_f$). This increase will result in the reduction of the pressure sensitivity $\Delta V_{ab-c}/\Delta P$ as

$$\begin{aligned} \frac{\Delta V_{ab-c}}{\Delta P} &= \frac{V_g \cdot (\Delta C_{ac}/\Delta P) - V_o \cdot (\Delta C_{bc}/\Delta P)}{C_f} \\ &= \frac{\Delta V_{ac}}{\Delta P} \left[1 - \frac{V_o \cdot (\Delta C_{bc}/\Delta P)}{V_g \cdot (\Delta C_{ac}/\Delta P)} \right] \\ &= \frac{\Delta V_{ac}}{\Delta P} \left(1 - \frac{2.730 \times 0.003}{2.700 \times 0.030} \right) \approx 0.9 \frac{\Delta V_{ac}}{\Delta P} \end{aligned} \quad (5.9)$$

For the same reason, $\Delta V_{ab-p}/\Delta P$ would be equal to $0.9 \Delta V_{ap}/\Delta P$. The experimental results confirm this as the measured value of $\Delta V_{ab-p}/\Delta P$ is 11.8 mV/kPa and the value of $\Delta V_{ap}/\Delta P$ is 13.3 mV/kPa. According to the explanations mentioned above, we could have the calculated relationship between $\Delta V_{ab-c}/\Delta P$ and $\Delta V_{ab-p}/\Delta P$ as

$$\begin{aligned} \Delta V_{ab-c}/\Delta P &= 0.9 (\Delta V_{ac}/\Delta P) \approx 0.9 [0.9 (\Delta V_{ap}/\Delta P)] \\ &\approx 0.9 \{0.9 [(\Delta V_{ap-p}/\Delta P)/0.9]\} \\ &\approx 0.9 \Delta V_{ab-p}/\Delta P \end{aligned} \quad (5.10)$$

The measured values of $\Delta V_{ab-c}/\Delta P$ and $\Delta V_{ab-p}/\Delta P$ are 10.4 and 11.8 mV/kPa, respectively. The experimental result is therefore consistent with the calculated one. This 10% reduction of the pressure sensitivity of ΔV_{ab-c} makes the planar fabrication process possible. The second one is that the use of C_{bc} as reference capacitor C_o in different applications eliminates the need for choosing different C_o for different stray capacitance external connections. The third one is that these two capacitors located in the same cavity can be used as a differential set to compensate for the common mode environmental changes.

Table 1. The capacitance and voltage outputs of sensor

	C_{ac} (pF)	C_{bc} (pF)	V_{ac} (V)	V_{ab-c} (V)
25°C	11.444	11.662	1.396	1.353
60°C	11.505	11.825	1.425	1.350

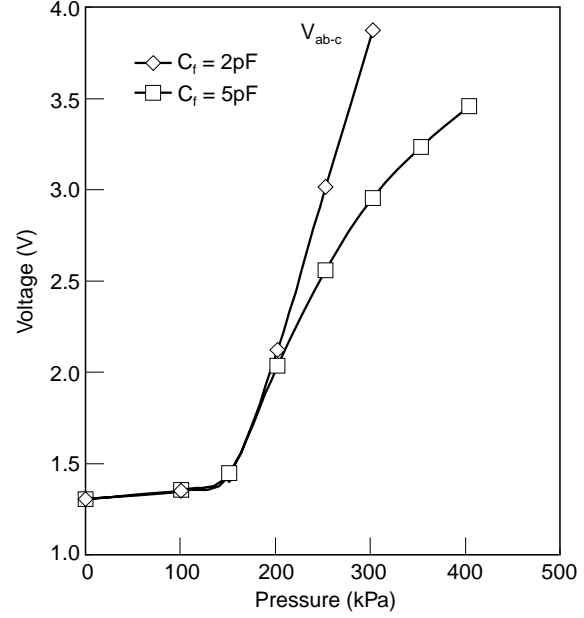


Fig. 7. The voltage-to-pressure characteristics of the sensor

Table 1 lists the measured capacitance and voltage outputs at zero differential pressure at two different temperatures 25 and 60 °C. The capacitances of C_{ac} and C_{bc} in the same cavity of sensor increase with increasing temperature. This increase in capacitance due to temperature change would cause an increase of V_c output by 29 mV. Meanwhile, the V_{ab-c} output is changed only by 3 mV due to the effect that V_{ab-c} measurements using the C_{ac} and C_{bc} as a differential set could partially cancel out the common mode temperature variations.

The voltage sensitivity can be programmed by the circuit sensitivity. The circuit sensitivity is adjusted by changing either the V_g or C_f . Figure 7 shows the increase of the pressure sensitivity of V_{ab-c} as reducing the external capacitor C_f from 5 pF to 2 pF. The stray capacitance existing between the C_f terminals on the CP-10 circuit board is checked to be 4 pF. This stray capacitance is in parallel with the C_f connected externally. Therefore, the measured $\Delta V_{ab-c}/\Delta P$ is increased from 10.4 to 17.0 mV/kPa as the equivalent capacitance C_f is reduced from 9 to 6 pF.

6 Conclusion

A three-electrode capacitive pressure sensor for touch-mode operation in the pressure range from 170 to 280 kPa is designed and tested. A special ring structure is used to integrate a sensing capacitor and a reference capacitor into the same sensor cavity to partially cancel out the temperature

effects. This structure offers the advantages of simple fabrication process, planar connections, as well as high sensitivity, improved linear output, and large over range pressure. A third electrode (c) is included to avoid two-level connections without sacrificing its sensitivity. The sensing capacitor C_{ac} has a pressure sensitivity of 0.030 pF/kPa in the pressure range from 170 to 280 kPa, while the reference capacitor C_{bc} is insensitive to the applied pressure as expected. These two capacitors C_{ac} and C_{bc} are fed as differential inputs to a CP-10 capacitance-to-voltage converter for pressure-to-voltage measurements in order to partially compensate the temperature variation as well as to reduce the stray capacitance effect in the test system and sensor structure. The pressure sensitivity of sensor obtained from the CP-10 is 10.4 mV/kPa for a given fixed circuit sensitivity (g). The circuit sensitivity can be adjusted by changing the value of C_f , when C_f is reduced by a factor (n), the circuit sensitivity will be increased by the same factor ($g' = ng$). The experimental data show that the sensor sensitivity is increased by a factor of 1.6 (from 10.4 to 17.0 mV/kPa) as the C_f is reduced by a factor 1.5 (from 9 to 6 pF). It is expected that future integration of the sensor and the CP-10 circuit into a single chip could further improve the sensitivity.

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