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# Linear trimmed means for the linear regression with AR(1) errors model

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## ABSTRACT

For the linear regression with AR(1) errors model, the robust generalized and feasible generalized estimators of Lai et al. (2003) of regression parameters are shown to have the desired property of a robust Gauss Markov theorem. This is done by showing that these two estimators are the best among classes of linear trimmed means. Monte Carlo and data analysis for this technique have been performed.

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## 1. Introduction

Consider the linear regression model

$$y = X\beta + \varepsilon, \quad (1.1)$$

where  $y$  is a vector of observations for the dependent variable,  $X$  is a known  $n \times p$  design matrix with 1's in the first column, and  $\varepsilon$  is a vector of independent and identically distributed disturbance variables with a distribution of finite variance. We consider the problem of estimating the parameter vector  $\beta$ . From the Gauss–Markov theorem, it is known that the least squares estimator has the smallest covariance matrix in the class of unbiased linear estimators  $My$  where  $M$  satisfies  $MX = I_p$ . However, the least squares estimator is sensitive to departures from normality and to the presence of outliers so we need to consider robust estimators. An interesting question in robust regression is if there is a robust Gauss–Markov theorem, i.e., if there is a robust estimator that is (asymptotically) more efficient than a class of linear robust estimators? This has been done by Chen et al. (2001), who considered a class of estimators based on Winsorized observations and showed that the trimmed mean of Welsh (1987) is asymptotically the best among in this class.

Suppose that the error vector  $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n)'$  has the covariance matrix structure

$$\text{Cov}(\varepsilon) = \sigma^2 \Omega, \quad (1.2)$$

where  $\Omega$  is a positive definite matrix and  $\sigma$  is finite. From the regression theory of the estimation of  $\beta$ , it is known that any estimator having an (asymptotic) covariance matrix of the form

$$\delta(X'\Omega^{-1}X)^{-1} \quad (1.3)$$

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is more efficient than the estimator having (asymptotic) covariance matrix of the form

$$\delta(X'X)^{-1}(X'\Omega X)(X'X)^{-1}, \quad (1.4)$$

where  $\delta$  is some positive constant. In the least squares estimation when the matrix  $\Omega$  is known, Aitken (1935) introduced the generalized least squares estimator (GLS) and showed that it has a covariance matrix of the form (1.3) and the LSE has a covariance matrix of the form (1.4) with  $\delta = \sigma^2$ . It is also well known that, when  $\Omega$  is unknown, the feasible generalized LSE has the asymptotic covariance matrix of the form (1.3). Thus these two generalized type estimators are asymptotically more efficient than the LSE.

Although the GLS and feasible GLS are asymptotically more efficient than the LSE in many regression problems, they are highly sensitive to even very small departures from normality and to the presence of outliers. Therefore developing robust generalized and feasible generalized estimators in each specific regression problem is important. We consider one of the most popular models, the linear regression with AR(1) errors model, a structure of (1.2), as follows:

$$\begin{aligned} y_i &= x_i'\beta + \varepsilon_i, \quad i = 1, \dots, n, \\ \varepsilon_i &= \rho\varepsilon_{i-1} + e_i, \end{aligned} \quad (1.5)$$

where  $e_1, \dots, e_n$  are independent and identically distributed (iid) random variables. Suppose that  $|\rho| < 1$  and  $e_i$  has a distribution function  $F$ .

Denote the transformed vector  $u = \Omega^{-1/2}y$ . One approach to robust estimation is to construct a weighted observation vector  $u^*$  and then construct a consistent estimator which is linear in  $u^*$ . In case  $\rho$  is unknown, all vectors are replaced by the ones with estimating  $\rho$  by estimator  $\hat{\rho}$ ; see for example, Lai et al. (2003). There are two types of weighted observation vectors in this literature. First,  $u^*$  can represent a trimmed observation vector  $Au$  with  $A$  being a trimming matrix constructed from regression quantiles (see Koenker and Bassett, 1978), or residuals based on an initial estimator (see Ruppert and Carroll, 1980; Chen, 1997). Second,  $u^*$  can be a Winsorized observation vector that is defined as in Welsh (1987). In this paper, we use the trimmed observation vector of Koenker and Bassett (1978) to study classes of linear functions based on  $u^*$  for estimation of  $\beta$ , and we develop a robust version of the Gauss–Markov theorem. Based on regression quantiles, Lai et al. (2003) proposed generalized and feasible generalized trimmed means for estimating regression parameters  $\beta$ . Then robust generalized and feasible generalized estimation techniques have been developed.

With the Gauss Markov theorem for linear regression with iid errors model, it is then interesting to see if there are any robust type generalized and feasible generalized estimators for linear regression with the AR(1) errors model that have the desired property of robust Gauss Markov theorem. Our aim in this paper is to show that the estimators in Lai et al. (2003) does have this desired property.

In Section 2 we introduce a class of linear trimmed means when  $\rho$  is known and we establish their large sample theory in Section 3. We also establish the theory for a class of linear trimmed means when  $\rho$  is unknown in Section 4. In both cases, we show that the generalized and feasible generalized trimmed means are the best, respectively, in these two classes of linear trimmed means in terms of asymptotic covariance matrix. Monte Carlo studies and Data analysis are performed and their results are displayed in Section 5. Finally, the proofs of the theorems are presented in Appendix A.

## 2. Linear trimmed mean when $\rho$ is known

For the linear regression with AR(1) errors model (1.5), to obtain a linear trimmed mean we need to specify the quantile for determining the observation trimming and to make a transformation of the linear model to obtain generalized estimators. For a given  $i$ -th dependent variable for model (1.5), assuming that  $i \geq 2$ , one way to derive a generalized estimator is to consider the one step Cochrane and Orcutt (C–O) (1949) procedure as  $y_i = \rho y_{i-1} + (x_i - \rho x_{i-1})'\beta + e_i$ . For error variable  $e$ , we assume that it has distribution function  $F$  with probability density function  $f$ . With the transformation for generalized estimation, a quantile could be defined through variable  $e$  or a linear conditional quantile of  $y_{i-1}$  and  $y_i$ . By the fact that  $x_i$  is a vector with the first element 1, the following two events determined by two quantiles are equivalent:

$$e_i \leq F^{-1}(\alpha) \quad (2.1)$$

and

$$(-\rho, 1) \begin{pmatrix} y_{i-1} \\ y_i \end{pmatrix} \leq (-\rho, 1) \begin{pmatrix} x'_{i-1} \\ x'_i \end{pmatrix} \beta(\alpha), \quad (2.2)$$

with

$$\beta(\alpha) = \beta + \begin{pmatrix} \frac{1}{1-\rho} F^{-1}(\alpha) \\ 0_{p-1} \end{pmatrix}.$$

The event in inequality (2.1) specifies the quantile of the error variable  $e$  and through inequality (2.2) it specifies the conditional quantile of linear function  $(-\rho, 1) \begin{pmatrix} y_{i-1} \\ y_i \end{pmatrix}$ . Here  $\beta(\alpha)$  is called the population regression quantile by Koenker and Bassett (1978). With the specification of quantiles and transformation, we may define the linear trimmed means.

For defining the linear trimmed means, we consider the one step C–O procedure on the matrix form of the linear regression with AR(1) error model of (1.5) which is

$$y = X\beta + \varepsilon,$$

where it can be seen that  $\text{Cov}(\varepsilon) = \sigma^2\Omega$  with

$$\Omega = \frac{1}{1-\rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \dots & \rho^{n-1} \\ \rho & 1 & \rho & \dots & \rho^{n-2} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ \rho^{n-1} & \rho^{n-2} & \rho^{n-3} & \dots & 1 \end{pmatrix}. \tag{2.3}$$

Define the half matrix of  $\Omega^{-1}$  as

$$\Omega^{-1/2'} = \begin{pmatrix} (1-\rho^2)^{1/2} & 0 & 0 & \dots & 0 & 0 \\ -\rho & 1 & 0 & \dots & 0 & 0 \\ 0 & -\rho & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -\rho & 1 \end{pmatrix}.$$

With the above half matrix of  $\Omega$ , we consider the model for the one step C–O procedure  $u = \Omega^{-1/2'}y$  as

$$u = Z\beta + ((1-\rho^2)^{1/2}\varepsilon_1, \varepsilon_2, \varepsilon_3, \dots, \varepsilon_n)', \tag{2.4}$$

where  $Z = \Omega^{-1/2'}X$ . Note that the vector  $u$  and the matrix  $Z$  are both functions of parameter  $\rho$ . The usual descriptive statistics, robust or nonrobust, based on model (1.1) can be carried over straightforwardly to the transformed model (2.4) when  $\rho$  is known. However, when  $\rho$  is unknown,  $u$  and  $Z$  need to be replaced by the ones that place its  $\rho$  by its consistent estimator. Knowing that the GLS is simply the LSE of  $\beta$  for model (2.4), we may consider the linear trimmed mean defined on this transformed model. To validate the terminology calling the linear trimmed means with  $\rho$  being known and unknown, we will show that they are asymptotically equivalent in the sense of having the same asymptotic covariance matrix. This is what the GLS and feasible GLS performed.

For  $0 < \alpha < 1$ , the  $\alpha$ -th (sample) regression quantile of Koenker and Bassett (1978) for the linear regression with AR(1) errors model is defined as

$$\hat{\beta}(\alpha) = \arg \min_{b \in R^p} \sum_{i=1}^n (u_i - z_i'b)(\alpha - I(u_i \leq z_i'b)),$$

where  $u_i$  and  $z_i'$  are the  $i$ -th rows of  $u$  and  $Z$ , respectively, and  $I(A)$  is the indicator function of the event  $A$ . Define the trimming matrix as  $A = \text{diag}\{a_i = I(z_i'\hat{\beta}(\alpha_1) \leq u_i \leq z_i'\hat{\beta}(\alpha_2)) : i = 1, \dots, n\}$  with  $0 < \alpha_1 < \alpha_2 < 1$  where fractions  $\alpha_1$  and  $1-\alpha_2$  of observations, respectively, from low tail and upper tail are trimmed. After the outliers are trimmed by regression quantiles  $\hat{\beta}(\alpha)$  and  $\hat{\beta}(1-\alpha)$ , we have the following submodel:

$$Au = AZ\beta + A \begin{pmatrix} (1-\rho^2)^{1/2}\varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{pmatrix}. \tag{2.5}$$

Since  $A$  is random, the error vector in the above transformed model is now not a set of independent variables. Koenker and Bassett's type generalized trimmed mean (proposed by Lai et al., 2003) is defined as

$$\hat{\beta}_{tm} = (Z'AZ)^{-1}Z'Au. \tag{2.6}$$

We now move to define the linear trimmed means. Any linear unbiased estimator defined in model of (2.4) has the form  $Mu$  with  $M$  being a  $p \times n$  nonstochastic matrix satisfying  $MZ = I_p$ . Since  $M$  is a full-rank matrix, there exist matrices  $H$  and  $H_0$  such that  $M = HH_0$ . Thus, an estimator is a linear unbiased estimator if there exists a  $p \times p$  nonsingular matrix  $H$  and an  $n \times p$  full-rank matrix  $H_0$  such that the estimator can be written as

$$HH_0u.$$

We generalize linear unbiased estimators defined on the observation vector  $u$  to estimators defined on  $Au$  by requiring them to be of the form  $MAu$  where  $M = HH_0$ .

**Definition 2.1.** A statistic  $\hat{\beta}_{ltm}$  is called a  $(\alpha_1, \alpha_2)$  linear trimmed mean if there exists a stochastic  $p \times p$  matrix  $H$  and a nonstochastic  $n \times p$  matrix  $H_0$  such that it has the following representation:

$$\hat{\beta}_{ltm} = HH_0Au, \tag{2.7}$$

where  $H$  and  $H_0$  satisfy the following two conditions:

- (a1)  $nH \rightarrow \tilde{H}$  in probability, where  $\tilde{H}$  is a full rank  $p \times p$  matrix.  
 (a2)  $HH_0Z = (\alpha_2 - \alpha_1)^{-1}I_p + o_p(n^{-1/2})$  where  $I_p$  is the  $p \times p$  identity matrix.

This is similar to the usual requirements for unbiased estimation, except that we have introduced a trimmed observation vector to allow for robustness and considered an asymptotic property instead of unbiasedness.

Two questions arise for the class of linear trimmed means. First, does this class of means contain estimators that have already appeared in the literature? The answer is affirmative because the class of linear trimmed means defined in this paper contains the generalized trimmed mean of Lai et al. (2003) ( $H = (Z'AZ)^{-1}$  and  $H_0 = Z$ ), and the set of Mallows-type bounded influence trimmed means ( $H = (Z'WAZ)^{-1}$  and  $H_0 = Z'W$  with  $W$ , a diagonal matrix of weights; see Section 3). Second, is there a best estimator in this class of linear trimmed means and can we find it if it exists? This question will be answered in the next section.

With the one step C–O procedure, the half matrix  $Q^{-1/2}$  has rows with only a finite number (not depending on  $n$ ) of elements that depend on the parameter  $\rho$ . This trick, traditionally used in econometrics literature for regression with AR(1) errors (see, for example, Fomby et al., 1984, pp. 210–211), makes the study of asymptotic theory for  $\hat{\beta}_{lm}(\alpha)$  similar to what we have for the classical trimmed mean for linear regression. Large sample representations of the linear trimmed mean and its role as generalized robust estimator will be introduced in the next section.

### 3. Asymptotic properties of linear trimmed mean

Let us denote by  $h'_i$  the  $i$ th row of  $H'_0$ ,  $\theta_h = \lim_{n \rightarrow \infty} n^{-1} \sum_{i=1}^n h_i$ ,  $Q_{hz} = \lim_{n \rightarrow \infty} n^{-1} \sum_{i=1}^n h_i z'_i$  and  $Q_z = \lim_{n \rightarrow \infty} n^{-1} Z'Z$ . We assume throughout this section that conditions (a3)–(a6) in Appendix A are satisfied. So, for examples,  $Q_{hs}$  is a full rank matrix and  $Q_z$  is positive definite matrix. It is not difficult to see that these conditions are satisfied in typical analysis of variance designs and these hold in probability when the rows of  $X$  form a random sample from a very wide class of distributions in  $R^p$  (see this point in detail in Koenker and Portnoy, 1987). The following theorem gives a “Bahadur” representation of the  $(\alpha_1, \alpha_2)$  linear trimmed mean.

**Theorem 3.1.** *With assumptions (a1)–(a6), we have*

$$\begin{aligned} n^{1/2}(\hat{\beta}_{lm} - (\beta + \gamma_{lm})) &= n^{-1/2} \tilde{H} \sum_{i=1}^n \{h_i(e_i I(F^{-1}(\alpha_1) \leq e_i \leq F^{-1}(\alpha_2)) - \lambda) \\ &+ [F^{-1}(\alpha_1)I(e_i < F^{-1}(\alpha_1)) + F^{-1}(\alpha_2)I(e_i > F^{-1}(\alpha_2)) - ((1 - \alpha_2)F^{-1}(\alpha_2) \\ &+ \alpha_1 F^{-1}(\alpha_1))] Q_{hz} Q_z^{-1} z_i\} + o_p(1), \end{aligned}$$

where  $\gamma_{lm} = \lambda \tilde{H} \theta_h$ ,  $\lambda = \int_{F^{-1}(\alpha_1)}^{F^{-1}(\alpha_2)} e dF(e)$  and  $\theta_h$  is defined in assumption (a5).

The limiting distribution of the  $(\alpha_1, \alpha_2)$  linear trimmed mean follows from the central limit theorem (see, e.g. Serfling, 1980, p. 30).

**Corollary 3.2.** *By conditions (a1)–(a6),  $n^{1/2}(\hat{\beta}_{lm} - (\beta + \gamma_{lm}))$  has an asymptotic normal distribution with zero mean vector and the following asymptotic covariance matrix:*

$$\begin{aligned} &\left[ \int_{F^{-1}(\alpha_1)}^{F^{-1}(\alpha_2)} e^2 dF(e) - \lambda^2 \right] \tilde{H} Q_h \tilde{H}' + (\alpha_2 - \alpha_1)^{-2} [\alpha_1 (F^{-1}(\alpha_1))^2 + (1 - \alpha_2) (F^{-1}(\alpha_2))^2 \\ &- (\alpha_1 F^{-1}(\alpha_1) + (1 - \alpha_2) F^{-1}(\alpha_2))^2 - 2\lambda (\alpha_1 F^{-1}(\alpha_1) + (1 - \alpha_2) F^{-1}(\alpha_2))] Q_z^{-1}. \end{aligned} \quad (3.1)$$

The  $(\alpha_1, \alpha_2)$  generalized trimmed mean proposed by Lai et al. (2003) is defined by

$$\hat{\beta}_{tm} = (Z'AZ)^{-1} Z'Au. \quad (3.2)$$

From the result of this estimator studied by Ruppert and Carroll (1980), we have

$$n^{-1} Z'AZ \rightarrow (\alpha_2 - \alpha_1) Q_z.$$

By letting  $H = (Z'AZ)^{-1}$  and  $H_0 = Z$ , can see that condition (a2) also holds for  $\hat{\beta}_{tm}$ . So, the  $(\alpha_1, \alpha_2)$  generalized trimmed mean is in the class of  $(\alpha_1, \alpha_2)$  linear trimmed mean's. Moreover, Lai et al. (2003) provided the result that  $n^{1/2}(\hat{\beta}_{tm} - (\beta + \gamma_{tm}))$ , where  $\gamma_{tm} = (\alpha_2 - \alpha_1)^{-1} \lambda Q_z^{-1} \theta_z$ , has an asymptotic normal distribution with zero means and covariance matrix  $\sigma^2(\alpha_1, \alpha_2) Q_z^{-1}$ ,

where

$$\sigma^2(\alpha_1, \alpha_2) = (\alpha_2 - \alpha_1)^{-2} \left[ \int_{F^{-1}(\alpha_1)}^{F^{-1}(\alpha_2)} (e - \lambda)^2 dF(\varepsilon) + \alpha_1 (F^{-1}(\alpha_1))^2 + (1 - \alpha_2) (F^{-1}(\alpha_2))^2 - (\alpha_1 F^{-1}(\alpha_1) + (1 - \alpha_2) F^{-1}(\alpha_2))^2 - 2\lambda(\alpha_1 F^{-1}(\alpha_1) + (1 - \alpha_2) F^{-1}(\alpha_2)) \right]. \tag{3.3}$$

The following lemma orders the matrices  $\tilde{H}Q_h\tilde{H}'$  and  $Q_z$ .

**Lemma 3.3.** For any matrices  $\tilde{H}$  and  $Q_h$  induced from conditions (a1) and (a4), the difference

$$\tilde{H}Q_h\tilde{H}' - (\alpha_2 - \alpha_1)^{-2} Q_z^{-1} \tag{3.4}$$

is positive semidefinite.

The relation in (3.4) then implies the following main theorem.

**Theorem 3.4.** Under the conditions (a.3)–(a.6), the  $(\alpha_1, \alpha_2)$  generalized trimmed mean  $\hat{\beta}_{tm}$  of (3.2) is the best  $(\alpha_1, \alpha_2)$  linear trimmed mean.

Since the  $(\alpha_1, \alpha_2)$  generalized trimmed mean always exists, then the best  $(\alpha_1, \alpha_2)$  linear trimmed mean always exists. A further question is how big is the class of  $(\alpha_1, \alpha_2)$  linear trimmed mean's? However, we do not study the scope of the linear trimmed means.

In the literature, consideration has been given to the development of estimators of regression parameters  $\beta$  that limit the effects of the error variable and the independent variables. Among them, approaches which simultaneously bound the influence of the design points and the residuals for the linear regression model include [Krasker and Welsch \(1982\)](#) and [Krasker \(1985\)](#). On the other hand, the approach of Mallow's type bounded-influence trimmed mean is to bound the influence of the design points and the residuals separately as applied in the AR(1) regression model by [De Jongh and De Wet \(1985\)](#) and in the linear regression model by [De Jongh et al. \(1988\)](#). In a study by [Giltinan et al. \(1986\)](#), they found these two approaches are competitive in a way that neither is preferable to the other one. They also note that Mallow's type estimators should theoretically give more stable inference than the Krasker–Welsch approach.

Let  $w_i, i = 1, \dots, n$ , be real numbers. For  $0 < \alpha < 1$ , Mallow's type bounded-influence regression quantile, denoted by  $\hat{\beta}_w(\alpha)$ , is defined as the solution for the minimization problem

$$\min_{b \in \mathbb{R}^p} \sum_{i=1}^n w_i (u_i - z_i' b) (\alpha - I(u_i \leq z_i' b)).$$

With  $W$  the diagonal matrix of  $\{w_i, i = 1, \dots, n\}$ , the bounded influence trimmed mean is defined as

$$\hat{\beta}_{BI} = (Z'WA_wZ)^{-1}Z'WA_wu$$

where  $A_w = \text{diag}\{a_i : I(z_i'\hat{\beta}_w(\alpha_1) \leq u_i \leq z_i'\hat{\beta}_w(\alpha_2)), i = 1, \dots, n\}$ .

Let  $H = (Z'WA_wZ)^{-1}$  and  $H_0 = WZ$ . This shows that the bounded influence trimmed means also form a subclass of linear trimmed means's (see [De Jongh et al., 1988](#) for their large sample properties).

**Theorem 3.5.** If assumptions (a1)–(a5) hold, then

$$\begin{aligned} (a) \quad n^{1/2}(\hat{\beta}_{BI} - (\beta + \gamma_w)) &= (\alpha_2 - \alpha_1)^{-1} Q_w^{-1} n^{-1/2} \sum_{i=1}^n w_i z_i [(e_i I(F^{-1}(\alpha_1) \leq e_i \leq F^{-1}(\alpha_2)) - \lambda) \\ &\quad + F^{-1}(\alpha_1) I(e_i < F^{-1}(\alpha_1)) + F^{-1}(\alpha_2) I(e_i > F^{-1}(\alpha_2)) - ((1 - \alpha_2) F^{-1}(\alpha_2) \\ &\quad + \alpha_1 F^{-1}(\alpha_1))] + o_p(1), \end{aligned}$$

where  $\gamma_w = (\alpha_2 - \alpha_1)^{-1} \lambda Q_w^{-1} \theta_w$ ,  $Q_w = \lim_{n \rightarrow \infty} n^{-1} \sum_{i=1}^n w_i z_i z_i'$ , a positive definite matrix, and  $\theta_w = \lim_{n \rightarrow \infty} n^{-1} \sum_{i=1}^n w_i z_i$  and

$$(b) \quad n^{1/2}(\hat{\beta}_{BI} - (\beta + \gamma_w)) \rightarrow N(0, \sigma^2(\alpha_1, \alpha_2) Q_w^{-1} Q_{ww} Q_w^{-1}) \text{ where } Q_{ww} = \lim_{n \rightarrow \infty} n^{-1} \sum_{i=1}^n w_i^2 z_i z_i', \text{ a positive definite matrix.}$$

In particular,  $\hat{\beta}_{tm}$  is the example of  $\hat{\beta}_{BI}$  with  $W$  as the identity matrix, and it then belongs to this subclass. We may also show that  $Q_w^{-1} Q_{ww} Q_w^{-1} - Q_z^{-1}$  is positive semidefinite which shows that  $\hat{\beta}_{tm}$  is the best bounded influence trimmed mean.

**Theorem 3.6.** The  $(\alpha_1, \alpha_2)$  generalized trimmed mean is the best bounded influence trimmed mean.

This result is based solely on considerations of the asymptotic variance and ignores the fact that generalized trimmed mean does not have bounded influence in the space of independent variables. It confirms the notion that bounded influence is achieved at the cost of efficiency.

**4. Linear trimmed means when  $\rho$  is unknown**

After the development of the theory of the linear trimmed means for the case where  $\rho$  is known, the next interesting problem is whether, when the parameter  $\rho$  is unknown, the linear trimmed mean of (2.7) with  $\rho$  replaced by a consistent estimator  $\hat{\rho}$  will have the same asymptotic behavior as displayed by  $\hat{\beta}_{l_{tm}}$ . If so, the theory of generalized least squares estimation is then carried over to the theory of robust estimation in this specific linear regression model. Let  $\hat{\Omega}$  be the matrix of  $\Omega$  with  $\rho$  replaced by its consistent estimator  $\hat{\rho}$  which could be the LSE through the C–O estimation procedure. Define matrices  $\hat{u} = \hat{\Omega}^{-1/2} y$ ,  $\hat{Z} = \hat{\Omega}^{-1/2} X$  and  $\hat{\varepsilon} = \hat{\Omega}^{-1/2} \varepsilon$ . Let the regression quantile when the parameter  $\rho$  is unknown be defined as

$$\hat{\beta}^*(\alpha) = \arg \min_{b \in \mathbb{R}^p} \sum_{i=1}^n (\hat{u}_i - \hat{z}'_i b)(\alpha - I(\hat{u}_i \leq \hat{z}'_i b)),$$

where  $\hat{u}_i$  and  $\hat{z}'_i$  are  $i$ -th rows of  $\hat{u}$  and  $\hat{Z}$ , respectively. Define the trimming matrix as  $\hat{A} = \text{diag}\{a_i = I(\hat{z}'_i \hat{\beta}^*(\alpha_1) \leq \hat{u}_i \leq \hat{z}'_i \hat{\beta}^*(\alpha_2)) : i = 1, \dots, n\}$ .

**Definition 4.1.** A statistic,  $\hat{\beta}_{l_{tm}}^*$ , is called a  $(\alpha_1, \alpha_2)$  linear trimmed mean if there exists stochastic  $p \times p$  and  $n \times p$  matrices, respectively,  $H$  and  $H_0$  such that it has the following representation:

$$\hat{\beta}_{l_{tm}}^* = HH_0 \hat{A} \hat{u},$$

where  $H$  and  $H_0$  satisfy conditions (a1) and (a2) for these  $H$  and  $H_0$ .

Koenker and Bassett’s feasible generalized trimmed mean is defined as

$$\hat{\beta}_{tm}^* = (\hat{Z}' \hat{A} \hat{Z})^{-1} \hat{Z}' \hat{A} \hat{u}.$$

From Lai et al. (2003), we can see that  $n^{-1} \hat{Z}' \hat{A} \hat{Z} \xrightarrow{P} (\alpha_2 - \alpha_1) Q_Z$ . By letting  $H = (\hat{Z}' \hat{A} \hat{Z})^{-1}$  and  $H_0 = \hat{Z}$ , we see that  $\hat{\beta}_{tm}^*$  is in the class of  $(\alpha_1, \alpha_2)$  linear trimmed means. Lai et al. (2003) also showed that  $\hat{\beta}_{tm}^*$  and  $\hat{\beta}_{tm}$  have the same Bahadur representation and then they have the same asymptotic distribution. The following theorem states that the linear trimmed means for the cases where  $\rho$  is known and unknown have the same large sample properties.

**Theorem 4.2.**  $\sqrt{n}(\hat{\beta}_{tm}^* - \hat{\beta}_{tm}) = o_p(1)$ .

We then have the result that the feasible generalized trimmed mean is the best linear trimmed mean when  $\rho$  is unknown.

**Theorem 4.3.** *The feasible generalized trimmed mean is the best linear trimmed mean.*

For the rest of this section, we will consider several related questions. First, is the best linear trimmed mean unique for this linear regression with AR(1) errors model? For this, we develop an analogous optimal theory for the trimmed mean of Welsh (1987). Let  $\hat{\beta}_0$  be an initial estimator of  $\beta$  for model (2.4). Let  $\hat{\eta}(\alpha_1)$  and  $\hat{\eta}(\alpha_2)$  represent, respectively, the  $\alpha_1$  and  $\alpha_2$ th empirical quantiles of the regression residuals  $e_i^* = u_i - z'_i \hat{\beta}_0$ ,  $i = 1, \dots, n$ . The Winsorized observation defined by Welsh (1987) is

$$u_i^* = u_i I(\hat{\eta}(\alpha_1) \leq e_i^* \leq \hat{\eta}(\alpha_2)) + \hat{\eta}(\alpha_1) I(e_i^* < \hat{\eta}(\alpha_1)) - \alpha_1 + \hat{\eta}(\alpha_2) I(e_i^* > \hat{\eta}(\alpha_2)) - (1 - \alpha_2).$$

Let  $u^* = (u_1^*, \dots, u_n^*)'$  and denote the trimming matrix by  $B = \text{diag}(I(\hat{\eta}(\alpha_1) \leq e_i^* \leq \hat{\eta}(\alpha_2)), i = 1, \dots, n)$ .

**Definition 4.4.** A statistic  $\hat{\beta}_{lw}$  is called a  $(\alpha_1, \alpha_2)$  Welsh’s type linear trimmed mean if there exists a stochastic  $p \times p$  matrix  $H$  and a nonstochastic  $n \times p$  matrix  $H_0$  such that it has the following representation:

$$\hat{\beta}_{lw} = HH_0 u^*,$$

where  $H$  and  $H_0$  satisfy conditions (a1) and (a2).

**Theorem 4.5.** *With assumptions (a1)–(a7),  $\hat{\beta}_{lw}$  and  $\hat{\beta}_{l_{tm}}$  have the same Bahadur representation of Theorem 3.1 and then they have the same asymptotic distribution.*

If we let  $H = (Z' B Z)^{-1}$  and  $H_0 = Z$ , we see that the generalized Welsh’s (1987) trimmed mean of as

$$\hat{\beta}_w = (Z' B Z)^{-1} Z' u^*, \tag{4.1}$$

is a member of  $(\alpha_1, \alpha_2)$  Welsh’s type linear trimmed mean. We then have the following theorem.

**Theorem 4.6.** *The generalized Welsh’s trimmed mean  $\hat{\beta}_w$  and generalized trimmed mean  $\hat{\beta}_{l_{tm}}$  have the same asymptotic distribution. Hence,  $\hat{\beta}_w$  is the best  $(\alpha_1, \alpha_2)$  Welsh’s type linear trimmed mean.*

The above theorem shows that it is not unique for existence of best robust generalized estimator. As mentioned by one referee that further study of the generalized Huber’s M estimator may provide one more example of best robust

generalized estimator (see Jureckova and Sen, 1984 for a representation of Huber’s M estimator). Hence, further searching for some other types of best robust generalized estimators is not desirable. One interesting question is that if there is one best robust generalized estimator that has asymptotic variances identical or close to the Cramer-Rao lower bound when the error variables follow heavy tail distributions. For the classical linear regression model, the symmetric trimmed mean of Chen and Chiang (1996) and Chiang et al. (2006) has been shown to have asymptotic variances close to the Cramer–Rao lower bound. Hence, showing an extension of symmetric trimmed mean on this linear regression with AR(1) errors model may provide the desirable solution.

We also note here that a best linear trimmed mean is confined in comparison of linear trimmed means of fixed trimming percentages  $(\alpha_1, \alpha_2)$ . Without knowing the distribution  $F$ , can we estimate the best percentages  $(\alpha_1, \alpha_2)$  in terms of asymptotic covariance matrix that still is a best linear trimmed mean? To attack this problem, it involves minimizing the asymptotic covariance matrix (see the approach of Jaeckel, 1971) and the development of optimal theory will be complicated that needs further investigation.

### 5. Monte Carlo study and example

In this section, we first consider a simulation study to compare the feasible GLS  $\hat{\beta}_{FG}$  and the feasible generalized trimmed mean  $\hat{\beta}_{tm}^*$ . By letting  $\hat{\varepsilon}_i = y_i - x_i' \hat{\beta}_{ls}$ , where  $\hat{\beta}_{ls}$  is the LSE of  $\beta$ , we estimate  $\rho$  by  $\hat{\rho} = \hat{\rho}$  by  $\sum_{i=2}^n \hat{\varepsilon}_i \hat{\varepsilon}_{i-1} / \sum_{i=2}^n \hat{\varepsilon}_i^2$ . With sample size  $n=30$ , the simple linear regression model,  $y_i = \beta_0 + \beta_1 x_{i1} + \varepsilon_i$  where  $\varepsilon_i$  follows the AR(1) error is considered. For this simulation, we let the true parameter values of  $\beta_0$  and  $\beta_1$  be 1’s and  $\rho$  be 0.3. This simulation is conducted with the same data generation system, except that the error variable  $e_i$  is generated from the mixed normal distribution  $(1-\delta)N(0,1) + \delta N(0,\sigma^2)$  with  $\delta = 0.1, 0.2, 0.3$  and  $\sigma = 3, 5, 10$  and  $x_i$  are independent normal random variables with mean  $i/2$  and variance 1. A total of 10 000 replications were performed and we compute the mean squares errors (MSE) for the feasible generalized LSE  $\hat{\beta}_{FG}$  and feasible generalized trimmed mean  $\hat{\beta}_{tm}^*$  for  $\alpha_1 = 1 - \alpha_2 = \alpha = 0.1, 0.2, 0.3$  where the total mean squared error is the square of the Euclidean distance between the estimator and true regression parameter  $\beta$ . For convenience, below in this section we re-denote the feasible generalized trimmed mean by  $\hat{\beta}_{tm}(\alpha)$ . The MSEs are listed in Tables 1 and 2.

We may draw several conclusions from Tables 1 and 2:

- (a) The case  $\delta = 0$  indicates that  $\varepsilon_i$  follows a normal distribution. Then the results in these two tables fulfill the statistical theory that the feasible generalized least squares estimator  $\hat{\beta}_{FG}$  is more efficient than other consistent estimators. However, the trimmed means are still efficient in this ideal design.
- (b) The MSE’s of these two estimators both increase when the contaminated percentage  $\delta$  increases or contaminated variance  $\sigma^2$  increases. This verifies the performance of the usual estimators, robust or non-robust.
- (c) The feasible generalized trimmed mean is relatively more efficient than the feasible generalized LSE in all cases of contaminated errors. This result shows that the feasible generalized trimmed mean is indeed, among the class of linear trimmed means, a robust one.
- (d) The simulation results displaying in these two tables show the MSE in most cases of  $\delta$  and  $\sigma$  (not in  $\delta = 0$  and  $(\delta, \sigma) = (0.1, 3)$ ) an decreasing trend with  $\alpha$  increasing). Some further simulation results in our experience show that MSE goes up for  $\alpha$  not too far after 0.3.

Next we consider real data regression analysis. Many firms use past sales to forecast future sales. Suppose a wholesale distributor of sporting goods is interested in forecasting its sales revenue for each of the next 5 years. Since an inaccurate forecast may have dire consequences to the distributor, efficiency of the estimation of regression parameters is an

**Table 1**  
MSE’s for  $\hat{\beta}_{FG}$  and  $\hat{\beta}_{tm}^*$  under contaminated normal distribution ( $n=30$ ).

$\sigma$	$\hat{\beta}_{FG}$	$\hat{\beta}_{tm}^*(0.1)$	$\hat{\beta}_{tm}^*(0.2)$	$\hat{\beta}_{tm}^*(0.3)$
$(\delta = 0)$	0.2654	0.2663	0.2681	0.2690
$(\delta = 0.1)$				
3	0.3746	0.2874	0.2697	0.2698
5	0.7326	0.3644	0.3075	0.2964
10	2.3055	0.5463	0.4184	0.3714
$(\delta = 0.2)$				
3	0.5543	0.3963	0.3600	0.3300
5	1.2306	0.5819	0.4530	0.4229
10	4.4579	1.4236	0.7820	0.6012
$(\delta = 0.3)$				
3	0.7075	0.5380	0.4448	0.4101
5	1.7109	0.9723	0.6503	0.5749
10	6.5214	2.8921	1.5105	1.0893

**Table 2**

MSE's for  $\hat{\beta}_{FG}$  and  $\hat{\beta}_{tm}$  under contaminated normal distribution ( $n=100$ ).

$\sigma$	$\hat{\beta}_{FG}$	$\hat{\beta}_{tm}^*(0.1)$	$\hat{\beta}_{tm}^*(0.2)$	$\hat{\beta}_{tm}^*(0.3)$
( $\delta = 0$ )	0.0921	0.0928	0.0934	0.0937
( $\delta = 0.1$ )				
3	0.1308	0.0964	0.0960	0.0904
5	0.2539	0.1067	0.1059	0.0988
10	0.8494	0.1253	0.1154	0.1111
( $\delta = 0.2$ )				
3	0.1962	0.1257	0.1182	0.1125
5	0.4249	0.1679	0.1343	0.1270
10	1.5763	0.2736	0.1574	0.1543
( $\delta = 0.3$ )				
3	0.2522	0.1670	0.1466	0.1362
5	0.6266	0.2744	0.1844	0.1643
10	2.1937	0.7071	0.2683	0.2147

**Table 3**

MSE's for predictors based on some estimators.

Estimator	Estimate	Observation	Prediction	MSE
$\hat{\beta}_{ls}$	$\begin{pmatrix} 1.053 \\ 4.239 \end{pmatrix}$	$\begin{pmatrix} 146.10 \\ 151.40 \\ 150.90 \end{pmatrix}$	$\begin{pmatrix} 140.94 \\ 145.17 \\ 149.41 \end{pmatrix}$	67.503
$\hat{\beta}_{FG}$	$\begin{pmatrix} 0.142 \\ 4.319 \end{pmatrix}$		$\begin{pmatrix} 142.67 \\ 146.99 \\ 151.31 \end{pmatrix}$	31.336
$\hat{\beta}_{\epsilon_i}$	$\begin{pmatrix} 0.531 \\ 4.268 \end{pmatrix}$		$\begin{pmatrix} 141.38 \\ 145.64 \\ 149.91 \end{pmatrix}$	56.304
$\hat{\beta}_{tm}^*(0.1)$	$\begin{pmatrix} -0.859 \\ 4.386 \end{pmatrix}$		$\begin{pmatrix} 143.88 \\ 148.27 \\ 152.65 \end{pmatrix}$	17.786
$\hat{\beta}_{tm}^*(0.2)$	$\begin{pmatrix} 0.072 \\ 4.364 \end{pmatrix}$		$\begin{pmatrix} 144.10 \\ 148.47 \\ 152.83 \end{pmatrix}$	16.302
$\hat{\beta}_{tm}^*(0.3)$	$\begin{pmatrix} 0.051 \\ 4.336 \end{pmatrix}$		$\begin{pmatrix} 143.15 \\ 147.49 \\ 151.83 \end{pmatrix}$	24.775
$\hat{\beta}_{FG\epsilon_1}$	$\begin{pmatrix} 0.341 \\ 4.258 \end{pmatrix}$		$\begin{pmatrix} 141.06 \\ 145.32 \\ 149.58 \end{pmatrix}$	21.343

important indicator in accuracy of forecasting. Data collected on a firm's yearly sales revenue (1000s of dollars) with sample size  $n=35$  has been analyzed by Mendenhall and Sincich (1993). Since the scatter plot of the data revealed a linearly increasing trend, so a simple linear regression model

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i, \quad i = 1, \dots, 35$$

seems to be reasonable to describe the trend, a simple. They first analyzed it with the least squares method that yields  $R^2=0.98$  which indicates that it is appropriate to be formulated as a linear regression model. They further displayed a plot of the residuals that revealed the existence of AR(1) errors, and then the Durbin and Watson test was performed, rejecting the null hypothesis  $\rho = 0$ . They also computed the prediction 95% confidence intervals for yearly revenues for years, 36–40, however, the interval estimates are wide, which makes the prediction of future observations less certain (see this point in Mendenhall and Sincich, 1993, p. 481). We expect to have better analysis, based on the feasible generalized trimmed mean, in some sense.

We follow their idea in evaluating the prediction for the yearly revenues for years 36–40. Since the observations of these are available, we may compute the following prediction MSE,

$$MSE = \frac{1}{3} \sum_{i=33}^{35} (y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i))^2,$$



where  $\begin{pmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{pmatrix}$  is the estimate of  $\begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$  corresponding the estimator. The MSE, in this design, provides a numerical measure for the performance of future observation prediction. For this example, estimators considered include LSE  $\hat{\beta}_{ls}$ , feasible GLS  $\hat{\beta}_{FG}$ ,  $\ell_1$ - norm estimator  $\hat{\beta}_{\ell_1}$ , feasible generalized trimmed mean  $\hat{\beta}_{tm}(\alpha)$  and feasible generalized  $\ell_1$ - norm estimator  $\hat{\beta}_{FG\ell_1}$  and their evaluated MSE's are listed in Table 3.

There are several comments can be drawn from Table 3:

- (a) Without implement of the information of AR(1) errors, the least squares estimate  $\hat{\beta}_{ls}$  is really not appropriate in prediction since it not only gives confidence intervals too wide for future observations but also leads to large MSE in our design of prediction.
- (b) The performance of  $\ell_1$ - norm estimator  $\hat{\beta}_{\ell_1}$  also suffers from that it does not introduce the correlation between error variables into its estimation.
- (c) Although the feasible generalized LSE  $\hat{\beta}_{FG}$  considers the correlation between error variables, its performance is still poorer than feasible generalized robust estimators.
- (d) Surprisingly the feasible generalized trimmed means for several symmetric trimming proportions have MSE's that are all smaller than those of the other three estimators. The feasible generalized trimmed mean not only has asymptotic optimal properties in the class of linear trimmed means but also shows an interesting fact in the prediction of future observations. This interesting result imply that the feasible generalized trimmed means are more capable in detection of the main trend showing in the data.
- (e) The feasible generalized  $\ell_1$ - norm estimator is much more efficient than the  $\ell_1$ - norm estimator  $\hat{\beta}_{\ell_1}$  since it considers the correlation between error variables. This estimator is also competitive with the feasible generalized trimmed mean.

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### Appendix A

Let  $\varepsilon$  have distribution function  $F$  with probability density function  $f$ . Let  $z_{ij}$  represent the  $j$ th element of vector  $z_i$ . The following conditions are similar to the standard ones for linear regression models as given in Ruppert and Carroll (1980) and Koenker and Portnoy (1987):

- (a3)  $n^{-1} \sum_{i=1}^n z_{ij}^A = O(1)$ ,
- (a4)  $n^{-1} Z'Z = Q_z + o(1)$ ,  $n^{-1} H_0'Z = Q_{hz} + o(1)$  and  $n^{-1} H_0'H_0 = Q_h + o(1)$  where  $Q_z$  and  $Q_h$  are positive definite matrices and  $Q_{hz}$  is a full rank matrix.
- (a5)  $n^{-1} \sum_{i=1}^n h_i = \theta_h + o(1)$ , where  $\theta_h$  is a finite vector.
- (a6) The probability density function and its derivative are both bounded and bounded away from 0 in a neighborhood of  $F^{-1}(\alpha)$  for  $\alpha \in (0, 1)$ .
- (a7)  $n^{1/2}(\hat{\beta}_0 - \beta) = O_p(1)$ .

**Proof of Theorem 3.1.** From condition (a2) and (A.10) of Ruppert and Carroll (1980),  $HH_0'A_nZ\beta = \beta + o_p(n^{-1/2})$ . Inserting (1.1) in Eq. (2.7), we have

$$n^{1/2}(\hat{\beta}_{lt} - \beta) = n^{1/2}HH_0'Ae, \tag{A.1}$$

where we replace  $(1-\rho^2)^{1/2}\varepsilon_1$  by  $e_1$  that have the same asymptotic representation. Now we develop a representation of  $n^{-1/2}H_0'Ae$ . Let  $U_j(\alpha, T_n) = n^{-1/2} \sum_{i=1}^n h_{ij}e_i I(e_i < F^{-1}(\alpha) + n^{-1/2}z_i'T_n)$  and  $U(\alpha, T_n) = (U_1(\alpha, T_n), \dots, U_p(\alpha, T_n))$ . Also, let  $T_n^*(\alpha) = n^{1/2}[\hat{\beta}(\alpha) - \beta(\alpha)]$ . Then  $n^{-1/2}H_0'A_n e = U(\alpha_2, T_n^*(\alpha_2)) - U(\alpha_1, T_n^*(\alpha_1))$ . By conditions (a3) and (a6) and from Jureckova and Sen's (1987) extension of Billingsley's Theorem (see also Koul, 1992), we have

$$\left| U_j(\alpha, T_n) - U_j(\alpha, 0) - n^{-1}F^{-1}(\alpha)f(F^{-1}(\alpha)) \sum_{i=1}^n h_{ij}z_i'T_n \right| = o_p(1) \tag{A.2}$$

for  $j=1, \dots, p$  and  $T_n = O_p(1)$ . We know that, from Lai et al. (2003),

$$n^{1/2}(\hat{\beta}(\alpha) - \beta(\alpha)) = Q_z^{-1} f^{-1}(F^{-1}(\alpha)) n^{-1/2} \sum_{i=1}^n z_i (\alpha - I(e_i \leq F^{-1}(\alpha))) + o_p(1). \quad (\text{A.3})$$

By condition (a4) and from (6.2) and (6.3)

$$\begin{aligned} n^{-1/2} H'_0 A_n e &= n^{-1/2} \sum_{i=1}^n h_i e_i I(F^{-1}(\alpha_1) \leq e_i \leq F^{-1}(\alpha_2)) \\ &+ F^{-1}(\alpha_2) Q_{hz} Q_z^{-1} n^{-1/2} \sum_{i=1}^n z_i (\alpha_2 - I(e_i \leq F^{-1}(\alpha_2))) \\ &+ F^{-1}(\alpha_1) Q_{hz} Q_z^{-1} n^{-1/2} \sum_{i=1}^n z_i (\alpha_1 - I(e_i \leq F^{-1}(\alpha_1))). \end{aligned} \quad (\text{A.4})$$

Then the theorem follows from (A.1) and (A.4).

The proof of Theorem 3.5 is analogous as it for the above and then is skipped.  $\square$

**Proof of Lemma 3.3.** Denote by  $\text{plim}(B_n) = B$  if  $B_n$  converges to  $B$  in probability. Let

$$C = HH_0 - (Z' A_n Z)^{-1} Z'.$$

With this,  $\text{plim}(CZ) = \text{plim}(HH_0 Z) - \text{plim}(Z' A_n Z)^{-1} Z' Z = 0$ .

Then

$$\begin{aligned} \hat{H} Q_h \hat{H}' &= \text{plim}(HH_0(HH_0)') \\ &= \text{plim}((C + (Z' A_n Z)^{-1} Z')(C + (Z' A_n Z)^{-1} Z)') \\ &= \text{plim}(CC') + \text{plim}((Z' A_n Z)^{-1} Z' Z (Z' A_n Z)^{-1}) \\ &= \text{plim}(CC') + (\alpha_2 - \alpha_1)^{-2} \text{plim}(Z' Z)^{-1} \\ &\geq (\alpha_2 - \alpha_1)^{-2} Q_z^{-1}. \quad \square \end{aligned}$$

**Proof of Theorem 4.2.** We here only briefly sketch a proof of the theorem. For detailed references, see Chen et al. (2001) and Lai et al. (2003). With the fact that  $n^{1/2}(\hat{\rho} - \rho) = O_p(1)$  and conditions (a1), (a3) and (a6), we may see that

$$n^{1/2}(\hat{\beta}_{\text{trim}}^* - \beta) = n^{1/2} H H'_0 \hat{A} e + o_p(1). \quad (\text{A.5})$$

By letting  $M(t_1, t_2, \alpha) = n^{-1/2} \sum_{i=1}^n h_i e_i I(e_i - n^{-1/2} t_1 \varepsilon_{i-1} \leq F^{-1}(\alpha) + n^{-1/2} (z_i + n^{-1/2} t_1 x_{i-1})' t_2 + n^{-1/2} t_1 F^{-1}(\alpha))$ , we see that

$$n^{-1/2} \hat{Z}' A_n e = M(T_1^*(\alpha_2), T_2^*, \alpha_2) - M(T_1^*(\alpha_1), T_2^*, \alpha_1), \quad (\text{A.6})$$

with  $T_1^*(\alpha) = n^{1/2}(\hat{\beta}^*(\alpha) - \beta(\alpha))$  and  $T_2^* = n^{1/2}(\hat{\rho} - \rho)$ . However, using the same methods in the proof of Lemma 3.5 and by (a3) and (a6), we can see that

$$m(T_1, T_2, \alpha) - M(0, 0, \alpha) = F^{-1}(\alpha) f(F^{-1}(\alpha)) n^{-1/2} \sum_{i=1}^n h_i (z_i' T_2 - T_1 F^{-1}(\alpha)) + o_p(1) \quad (\text{A.7})$$

for any sequences  $T_1 = O_p(1)$  and  $T_2 = O_p(1)$ . Then, from (A.6) and (A.7), we see that  $n^{-1/2} H'_0 \hat{A}_n e$  has the same representation of (A.4). Then (a1) and (A.5) further implies the theorem.  $\square$

**Proof of Theorem 4.5.** The proof can be derived similarly with it for Theorem 3.1 where a representation of  $\hat{\eta}(\alpha)$  may be applied that can be seen in Ruppert and Carroll (1980). Hence, it is skipped.  $\square$

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