

國立交通大學

環境工程研究所

碩士論文

L 型邊界且為非均質非等向水層的半解析解

Transient groundwater flow in heterogeneous and
anisotropic aquifers with L-shaped boundaries

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中華民國一〇一年六月

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摘要

瞭解地下水層的水位空間分佈與水文地質參數，是評估地下水資源的開發量或整治地下水污染的重要課題。以新竹含水層為案例，此含水層被斷層及河流圍繞，其形狀近似為L形。本研究係建立數學模型，在定水頭邊界(河流)及不透水邊界(斷層)侷限下的L形含水層，模擬地下水經多口井抽水後的暫態水力水頭分佈，此模型將考慮含水層的異質性和非等向性。首先透過區域分割法建立數學模型，將該含水層分割成兩個子區域。此模式考慮每個子區域各有不同的水力傳導係數，且各區域含水層皆具非等向性。藉由分離變數法及考慮子區域間水位與流通量的連續條件，推導出Laplace域的半解析解。所求得的解用來模擬L形含水層在抽水下的暫態水力水頭分佈；若L形含水層受污染時，此解可提供地下水流況資料，協助規劃地下水污染物控制。此半解析解可更進一步描述梯形含水層經抽水後的洩降分佈，本解亦可作為數值模式的驗核工具，分析數值模式在L形凹角邊界處計算上可能產生的水位誤差。

關鍵詞：不規則邊界、非等向、沖積扇含水層、水力傳導係數、區域分割法

Transient groundwater flow in heterogeneous and anisotropic aquifers with L-shaped boundaries

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Advisor : Hund-Der Yeh

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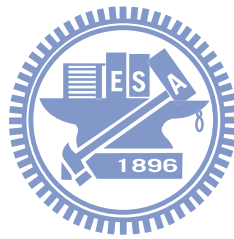
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ABSTRACT

Understanding groundwater flow distribution is important for evaluating groundwater resource and dealing with groundwater pollution problems. This study considers an aquifer bounded by faults and rivers in Hsinchu, Taiwan, and the aquifer can be approximately to have an L-shaped domain. A mathematical model is developed to describe the transient groundwater flow due to multiple pumping in an anisotropic, heterogeneous aquifer with an L-shaped domain with impermeable boundary and constant-head boundary representing the fault and the river, respectively. Method of domain decomposition is used to handle such an irregular boundary by dividing the aquifer into two sub-regions with different hydraulic conductivities. Taking into account the continuity conditions of hydraulic head and flux at the boundary between two sub-regions, the solution of the model in Laplace domain is then derived by the method of separation of variables. The semi-analytical solution can be used to assess the groundwater resources in transient pumping effect and provide flow information for pump-and-treat design if the aquifer has contamination. The solution can also be applied to delineate the hydraulic head distributions in aquifers with trapezoid boundary and to verify

the numerical solutions which might give inaccurate results at the corner of the irregular boundary.

Keywords: irregular boundary, anisotropy, alluvial aquifer, hydraulic conductivity, method of domain decomposition.



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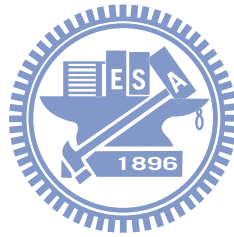
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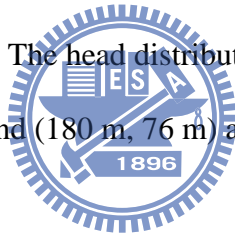
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CHAPTER 1 INTRODUCTION

Groundwater is an important water resource for agricultural, municipal and industrial uses. The planning and management of water resources through investigation of the groundwater flow is one of the major tasks of practicing engineers. The groundwater flow is highly dependent on the type and shape of the boundaries, especially when the aquifer domain has irregular shape. Most literatures dedicated to the development of analytical models for flow in finite aquifers were to investigate the problems with, for example, rectangular boundary [Chan et al., 1976; Chan et al., 1977; Daly and Morel-Seytoux, 1981; Latinopoulos, P., 1982; Corapcioglu et al., 1983; Latinopoulos, P., 1984; Latinopoulos, P., 1985], wedge-shaped boundary [Chan et al., 1978; Falade, 1982; Holzbecher, 2005; Yeh et al., 2006; Yeh et al., 2008; Chen et al., 2009; Sedghi et al., 2009; Sedghi et al., 2010], or triangle boundary [Asadi-Aghbolaghi et al., 2010]. However, it may not be uncommon that the boundaries of finite aquifers are irregular in real world. For irregular aquifer domain with variable boundary conditions, the solutions of the mathematical model are generally developed by numerical approaches such as finite element methods and finite difference methods. Taigbenu [2003] solved the problems for transient flow in multi-aquifer systems with arbitrarily domain geometry based on the Green element method (GEM). Recently, various computer codes based on either finite difference or finite element algorithms, such as AQUIFEM-N, BEMLAP, FEMWATER, FTWORK, MODFLOW, and SUTRA, were adopted to simulate a variety of groundwater flow problems [Loudyi et al., 2007]. When modeling a complex groundwater flow due to pumping/injection in heterogeneous aquifer with irregular domain boundary and various types of boundary conditions, numerical methods are more suitable than analytical models. However, numerical models usually require large amounts of hydrologic information as input data and CPU time for simulating complicated problems.

Besides, some numerical applications are restricted by criteria of spatial and temporal discretization for avoiding stability and/or numerical dispersion problems. Thus, deriving an analytical model for describing the groundwater distribution in an aquifer with irregular domain boundaries is also beneficial from a practical point of view.

Kuo et al. [1994] applied the image well theory and Theis' equation to predict transient drawdown behavior in an aquifer with irregularly shaped boundaries. However, the number of the image wells should be increased if the aquifer has very irregular and asymmetric boundary because insufficient number of the image wells might result in divergence [Matthews et al., 1954]. Read and Volker [1993] presented analytical solutions for steady seepage through hillsides with arbitrarily flow boundaries. They used the least squares method for estimating the coefficients in a series expansion of the Laplace equation. The least squares estimators, nevertheless, are equivalent to those derived using orthogonal function, that is, the basis function must be orthogonal [Carrier and Pearson, 1991]. Li et al. [1996] generalized and extended the results of Read and Volker [1990; 1993] and Read [1993] for Laplacian porous-media flow problems involving arbitrarily boundary conditions. The solution procedure was obtained by means of an infinite series of orthonormal functions, and they introduced a method, called image-recharge method, to establish the recurrence relationship of the series coefficients. Currently, Patel et al. [2011] used the method of decomposition adopted from Adomian [1994] to develop similarly analytical models for simulating groundwater flow in aquifers with irregular boundaries. The magnitude of hydraulic head was however underestimated and some conditional restrictions are still required.

Complication may arise when the boundaries of aquifer domain are irregular. An aquifer in Hsinchu, Taiwan, sketched in Figure 1 is an example. The figure illustrates the plan view of faults and rivers within the aquifer, which may be considered as an L-shaped

aquifer. More detailed description about this aquifer is given in section 2.1. The shading area in this schema designates the study area, which is adjacent to the Hsinchu Science Park (HSP). There are many semiconductor, optoelectronics, and LCD (liquid crystal display) panel factories in the HSP. It was reported that the HSP had the problem of DNAPL (dense non-aqueous phase liquid) contamination in groundwater in the past. The purpose of study is to provide an analytical tool for simulating the flow field if the pump-and-treat method is adopted for pollution remediation. To simplify this problem, the shape of the aquifer within the study area is approximated by a region delineated in Figure 2. This thesis aims at developing an analytical model to describe the groundwater flow in such an aquifer with anisotropic and non-homogeneous hydraulic conductivities. The L-shaped aquifer is divided into two sub-regions that each has a rectangular domain with homogeneous hydraulic conductivity. In addition, two types of boundary conditions, i.e., constant-head boundaries and no-flow boundaries, are used to represent the physical reality and constrain the problem domain. The Laplace-domain solution of the model is obtained after solving the governing equation along with boundary and continuity conditions via the Fourier finite cosine transform and the Laplace transform. A steady-state solution before pumping is first developed to obtain the initial hydraulic head distribution in this L-shaped aquifer. Gaver-Stehfest algorithm is then taken to inverse Laplace-domain solution, and a series of transient hydraulic head distributions in time domain within the problem domain are obtained. These semi-analytical solutions can be used to predict various groundwater flow fields if different pump-and-treat schemes are considered in the remedial design for the L-shaped aquifer.

CHAPTER 2 MATHEMATICAL MODEL

2.1 Conceptual model

Figure 1 shows a schema for an aquifer in Hsinchu, which is situated in the northwest of Taiwan. The study area is confined by the Hsinchu fault in the north, the Hsincheng fault in the west, the Shihtan fault in the southeast, the Touchien River in the east, and the Jhonggang River in the south. Physically, faults and perennial rivers can be considered as impermeable boundaries and constant-head boundaries, respectively. To simplify this problem, the domain of the study area is approximated to be L-shaped, as delineated in Figure 2. The origin of the coordinate is at the intersection of boundary AB and boundary BC. The Hsincheng fault, the Hsinchu fault, and the Shihtan fault, which are separately represented as boundaries AB, BC, and DE, are considered as impermeable boundaries. The Jhonggang River and the Touchien River, which are respectively expressed as boundaries S_1 and S_2 , are considered as constant-head boundaries. This L-shaped aquifer is divided into two sub-regions, named regions 1 and 2 and the hydraulic heads in these two regions are expressed as $\phi_1 = \phi_1(x, y, t)$ and $\phi_2 = \phi_2(x, y, t)$.

2.2 Governing equation and related boundary and initial condition

The governing equation describing the hydraulic head distribution in region 1 for the k th well located at (x_{1k}, y_{1k}) with a pumping rate per unit width of Q_{1k} [L^2/T] is expressed as

$$K_{x1} \frac{\partial^2 \phi_1}{\partial x^2} + K_{y1} \frac{\partial^2 \phi_1}{\partial y^2} = S_{s1} \frac{\partial \phi_1}{\partial t} - \sum_{k=1}^M Q_{1k} \delta(x - x_{1k}) \delta(y - y_{1k}),$$

$$0 \leq x \leq l_1, \quad 0 \leq y \leq b_1 \quad (1)$$

and the hydraulic head distribution in region 2 for the k th well located at (x_{2k}, y_{2k}) with a pumping rate per unit width of Q_{2k} [L^2/T] is

$$K_{x2} \frac{\partial^2 \phi_2}{\partial x^2} + K_{y2} \frac{\partial^2 \phi_2}{\partial y^2} = S_{s2} \frac{\partial \phi_2}{\partial t} - \sum_{k=1}^N Q_{2k} \delta(x - x_{2k}) \delta(y - y_{2k}),$$

$$0 \leq x \leq l_2, \quad b_1 \leq y \leq b_2 \quad (2)$$

where subscripts 1 and 2 denote the regions 1 and 2, respectively, S_s [L^{-1}] is the specific storage, K_x [L/T] and K_y [L/T] are the hydraulic conductivities in x - and y -direction, respectively. The Dirac delta function $\delta(\cdot)$ [L^{-1}] is defined in Table 1.

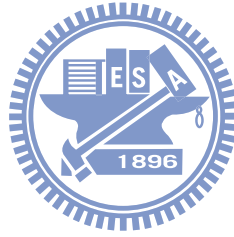
The boundary conditions for region 1 can be expressed as:

$$\phi_1 = h_1, \text{ at } x = l_1, \quad 0 \leq y \leq b_1 \quad (3)$$

$$\frac{\partial \phi_1}{\partial x} = 0, \text{ at } x = 0, \quad 0 \leq y \leq b_1 \quad (4)$$

$$\frac{\partial \phi_1}{\partial y} = 0, \text{ at } y = 0, \quad 0 \leq x \leq l_1 \quad (5)$$

$$\frac{\partial \phi_1}{\partial y} = 0, \text{ at } y = b_1, \quad l_2 \leq x \leq l_1 \quad (6)$$



and the boundary conditions for region 2 are

$$\frac{\partial \phi_2}{\partial x} = 0, \text{ at } x = 0, \quad b_1 \leq y \leq b_2 \quad (7)$$

$$\frac{\partial \phi_2}{\partial x} = 0, \text{ at } x = l_2, \quad b_1 \leq y \leq b_2 \quad (8)$$

$$\phi_2 = h_2, \text{ at } y = b_2, \quad 0 \leq x \leq l_2 \quad (9)$$

The continuity requirements of hydraulic head and flux at $y = b_1$ are, respectively,

$$\phi_1(x, b_1) = \phi_2(x, b_1), \text{ at } 0 \leq x \leq l_2 \quad (10)$$

and

$$K_{y1} \left. \frac{\partial \phi_1}{\partial y} \right|_{y=b_1} = K_{y2} \left. \frac{\partial \phi_2}{\partial y} \right|_{y=b_1}, \text{ at } 0 \leq x \leq l_2 \quad (11)$$

In order to express the solutions in dimensionless form, following dimensionless variables are introduced: $\phi_1^* = (\phi_1 - h_1)/h_1$, $\phi_2^* = (\phi_2 - h_1)/h_2$, $t^* = K_{y1}t/S_{s1}b_2^2$, $\kappa_1 = K_{x1}/K_{y1}$, $\kappa_2 = K_{x2}/K_{y2}$, $x^* = x/l_1$, $y^* = y/b_2$, where ϕ_1^* and ϕ_2^* stand for the dimensionless hydraulic heads for regions 1 and 2, respectively, t^* refers to the dimensionless time during the test, κ_1 and κ_2 represent the anisotropic ratio of hydraulic conductivity in region 1 and 2, respectively, x^* and y^* denote the dimensionless coordinate variables, b_1^* is the dimensionless y-direction distance from the origin to the outer boundary of region 1 (i.e. $b_1^* = b_1/b_2$), and l_2^* is the dimensionless x-direction distance from the origin to the outer boundary of region 2 (i.e. $l_2^* = l_2/l_1$). In addition, Q_{1k}^* and Q_{2k}^* are lumped parameters defined as $b_2^2 Q_{1k} / K_{y1} h_1$ and $b_2^2 Q_{2k} / K_{y2} h_2$, respectively.

A steady-state hydraulic head distribution should be obtained as an initial condition for solving the transient flow equation during Laplace transform. Detailed derivation for steady-state solutions for regions 1 and 2 before pumping are given in Appendix A, and the results are, respectively, expressed as

$$\phi_1^*(x^*, y^*) = \sum_{m=0}^{\infty} \Delta_{1m} C_{1m} E(m, y^*) \cos(\lambda_m x^*) \quad (12)$$

and

$$\phi_2^*(x^*, y^*) = \sum_{n=0}^{\infty} \Delta_{2n} (D_{2n} F(n, y^*) + B(n, y^*)) \cos(\alpha_n x^*) \quad (13)$$

with

$$B(n, y^*) = \Delta_{n,0} l_2^* \frac{h_2 - h_1}{h_2} e^{\Omega_{2n}(y^*-1)} \quad (14)$$

$$E(m, y^*) = e^{\Omega_{1m} y^*} + e^{-\Omega_{1m} y^*} \quad (15)$$

$$F(n, y^*) = e^{-\Omega_{2n} y^*} - e^{\Omega_{2n}(y^*-2)} \quad (16)$$

where the symbols Δ_{1m} , Δ_{2n} , λ_m , α_n , Ω_{1m} , Ω_{2n} , and $\Delta_{n,0}$ are defined in Table 1. The coefficients in C_{1m} and D_{2n} are solved simultaneously from following two equations

$$C_{1m} = \sum_{n=0}^{\infty} D_{2n} \frac{\Delta_{2n} K_{y2} h_2}{\Delta_{1m} K_{y1} h_1} \frac{F'(n, y^*)}{E'(m, y^*)} \bigg|_{y^*=b_1^*} \frac{\int_0^{l_2^*} \cos(\lambda_m x^*) \cos(\alpha_n x^*) dx^*}{\int_0^1 \cos^2(\lambda_m x^*) dx^*} \quad (17)$$

and

$$D_{2n} = \sum_{m=0}^{\infty} C_{1m} \frac{\Delta_{1m} h_1}{\Delta_{2n} h_2} \frac{E(m, b_1^*)}{F(n, b_1^*)} \frac{\int_0^{l_2^*} \cos(\lambda_m x^*) \cos(\alpha_n x^*) dx^*}{\int_0^{b_1^*} \cos^2(\alpha_n x^*) dx^*} - \frac{B(n, b_1^*)}{F(n, b_1^*)} \quad (18)$$

with

$$E'(m, y^*) = \frac{\partial E(m, y^*)}{\partial y^*} \quad (19)$$

$$F'(n, y^*) = \frac{\partial F(n, y^*)}{\partial y^*} \quad (20)$$

Since the initial condition is available, the solution of hydraulic head for a heterogeneous, anisotropic aquifer with L-shaped domain can be obtained via finite cosine transform and Laplace transform. The derivations for transient solutions are given in Appendix B and the results of the dimensionless hydraulic heads in Laplace-domain for regions 1 and 2 are, respectively,

$$\tilde{\phi}_1^*(x^*, y^*, p) = \sum_{i=0}^{\infty} \Delta_{1i} (T_{1i} E_1(i, y^*, p) + \bar{\phi}_{1p}^*(i, y^*, p)) \cos(\lambda_i x^*) \quad (21)$$

and

$$\tilde{\phi}_2^*(x^*, y^*, p) = \sum_{j=0}^{\infty} \Delta_{2j} (T_{2j} E_2(j, y^*, p) + F_2(j, y^*, p)) \cos(\alpha_j x^*) \quad (22)$$

with

$$E_1(i, y^*, p) = e^{\mu_i y^*} + e^{-\mu_i y^*} \quad (23)$$

$$E_2(j, y^*, p) = e^{-\theta_j y^*} - e^{\theta_j (y^* - 2)} \quad (24)$$

$$\begin{aligned} \bar{\phi}_{1p}^*(i, y^*, p) &= \frac{1}{2} \sum_{m=0}^{\infty} \frac{\Delta_{1m} \Lambda_{m,i} C_{1m} E(m, y^*)}{\mu_i^2 - \Omega_{1m}^2} \\ &+ \frac{1}{\mu_i p} \sum_{k=1}^M Q_{1k}^* \cos(\lambda_i x_{1k}^*) \sinh(\mu_i (y_{1k}^* - y^*)) H(y^* - y_{1k}^*) \end{aligned} \quad (25)$$

$$F_2(j, y^*, p) = -\bar{\phi}_{2p}^*(j, 1, p) e^{\theta_j (1 - y^*)} + \Delta_{j,0} \frac{l_2^* h_2 - h_1}{p h_2} e^{\theta_j (y^* - 1)} + \bar{\phi}_{2p}^*(j, y^*, p) \quad (26)$$

$$\begin{aligned} \bar{\phi}_{2p}^*(j, y^*, p) &= \Delta_{j,0} \left(\frac{S_{s2}}{S_{s1}} \frac{K_{y1}}{K_{y2}} \frac{h_2 - h_1}{h_2} \frac{l_2^*}{\theta_j^2} (1 - e^{\theta_j (y^* - 1)}) + \frac{l_2^* h_2 - h_1}{p h_2} e^{\theta_j (y^* - 1)} \right) \\ &+ \sum_{n=0}^{\infty} \frac{\Delta_{2j} \Lambda_{n,j}}{2} l_2^* \frac{S_{s2}}{S_{s1}} \frac{K_{y1}}{K_{y2}} \frac{D_{2n}}{\theta_j^2 - \Omega_{2n}^2} \frac{F(n, y^*)}{F(n, b_1^*)} \\ &+ \frac{1}{\theta_j p} \sum_{k=1}^N Q_{2jj}^* \cos(\alpha_j x_{2k}^*) \sinh(\theta_j (y_{2k}^* - y^*)) H(y^* - y_{2jj}^*) \end{aligned} \quad (27)$$

where p is the Laplace variable and the symbols α_j , λ_i , μ_i , θ_j , $\Delta_{j,0}$, Δ_{1i} , Δ_{2j} , $\Lambda_{m,i}$, $\Lambda_{n,j}$, and $H(\cdot)$ are described in Table 1.

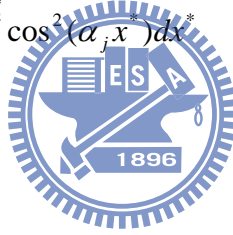
The coefficients in Eqs. (21) and (22) are obtained via continuity conditions of hydraulic head and flux. They can be solved by following two equations simultaneously

$$\begin{aligned}
T_{li} &= \sum_{j=0}^{\infty} T_{2j} \frac{\Delta_{2j}}{\Delta_{li}} \frac{K_{y2}}{K_{y1}} \frac{h_2}{h_1} \frac{E_2'(j, y^*, p)}{E_1'(i, y^*, p)} \bigg|_{y^*=b_1^*} \frac{\int_0^{l_2^*} \cos(\lambda_i x^*) \cos(\alpha_j x^*) dx^*}{\int_0^1 \cos^2(\lambda_i x^*) dx^*} \\
&+ \sum_{j=0}^{\infty} \frac{\Delta_{2j}}{\Delta_{li}} \frac{K_{y2}}{K_{y1}} \frac{h_2}{h_1} \frac{F_2'(j, y^*, p)}{E_1'(i, y^*, p)} \bigg|_{y^*=b_1^*} \frac{\int_0^{l_2^*} \cos(\lambda_i x^*) \cos(\alpha_j x^*) dx^*}{\int_0^1 \cos^2(\lambda_i x^*) dx^*} \\
&- \frac{\bar{\phi}_{1p}^*(i, y^*, p)}{E_1'(i, y^*, p)} \bigg|_{y^*=b_1^*}
\end{aligned} \tag{28}$$

and

$$\begin{aligned}
T_{2j} &= \sum_{i=0}^{\infty} T_{li} \frac{\Delta_{li}}{\Delta_{2j}} \frac{h_1}{h_2} \frac{E_1(i, b_1^*, p)}{E_2(j, b_1^*, p)} \frac{\int_0^{l_2^*} \cos(\lambda_i x^*) \cos(\alpha_j x^*) dx^*}{\int_0^{l_2^*} \cos^2(\alpha_j x^*) dx^*} \\
&+ \sum_{i=0}^{\infty} \frac{h_1}{h_2} \frac{\Delta_{li}}{\Delta_{2j}} \frac{\bar{\phi}_{1p}^*(i, b_1^*, p)}{E_2(j, b_1^*, p)} \frac{\int_0^{l_2^*} \cos(\lambda_i x^*) \cos(\alpha_j x^*) dx^*}{\int_0^{l_2^*} \cos^2(\alpha_j x^*) dx^*} - \frac{F_2(j, b_1^*, p)}{E_2(j, b_1^*, p)}
\end{aligned} \tag{29}$$

with



$$E_1'(i, y^*, p) = \frac{\partial E_1(i, y^*, p)}{\partial y^*} \tag{30}$$

$$E_2'(j, y^*, p) = \frac{\partial E_2(j, y^*, p)}{\partial y^*} \tag{31}$$

$$F_2'(j, y^*, p) = \frac{\partial F_2(j, y^*, p)}{\partial y^*} \tag{32}$$

$$\bar{\phi}_{1p}^*(i, y^*, p) = \frac{\partial \bar{\phi}_{1p}^*(i, y^*, p)}{\partial y^*} \tag{33}$$

CHAPTER 3 NUMERICAL RESULTS

Following sections present the investigations of the head distribution in the L-shaped aquifer, the effect of anisotropy and heterogeneity of the problem domain, and transient pumping effect with multi-well locations in regard to the aquifer parameters for predicting flow field bounded by constant-head and no-flow boundaries.

3.1. Steady-state head distribution

Consider a hypothetical aquifer with two sub-regions. Region 1 has an area of $900\text{ m} \times 300\text{ m}$ while the area of region 2 is $300\text{ m} \times 300\text{ m}$. The heads at boundaries $x=900\text{ m}$ and $y=600\text{ m}$ are respectively kept at $h_1=85\text{ m}$ and $h_2=80\text{ m}$, specific storage is 10^{-4} for those two regions, and the aquifer thickness is 80 m . Figure 3 shows the steady-state hydraulic head distribution, predicted by Eqs. (12) and (13), in the aquifer before pumping. Three different anisotropic ratios of hydraulic conductivity values, 1, 2, and 0.5, are considered in cases (a) - (c) listed in Table 2 and the simulated head distributions are shown in Figures 3a – 3c. The aquifer shown in Figure 3a is isotropic (i.e., $K_{x1} = K_{y1} = K_{x2} = K_{y2} = 520\text{ m/day}$). This figure displays that the groundwater flows from right to left, because the hydraulic head at boundary $x=900\text{ m}$ is higher than that at boundary $y=600\text{ m}$. The flow field schematic diagram is obtained by Darcy's law with hydraulic head distribution in order to express direction and magnitude of flow velocity. The result illustrates that the flow field in region 1 is mainly in x -direction while that in region 2 is in y -direction. This is because the shape of the aquifer and the no-flow boundaries constrain flow paths. The effect of anisotropy on the groundwater flow is demonstrated in Figures 3b and 3c. These three figures indicate that the flow velocity in x -direction increases with anisotropic ratio.

3.2. Spatial and temporal head distribution

Since the transient solution developed in this study is in Laplace domain, Laplace inversion technique is required to obtain the hydraulic head distributions in real time. Stehfest algorithm [Stehfest, 1970; Chang et al., 2010] is used to numerically inverse the transient solution. The hydraulic head distributions at three different times, i.e., $t = 2$ hrs, 2 days, and 7 days are shown in Figures 4a – 4c, respectively. Two wells are installed at $(850\text{ m}, 150\text{ m})$ and $(150\text{ m}, 550\text{ m})$ with a pumping rate $16\text{ m}^3/\text{day}$ and the conductivities K_x and K_y are 520 m/day for both regions 1 and 2. Those figures show that the aquifer drawdown increases with pumping time. The differences in hydraulic heads shown in Figures 4b and 4c is very small, indicating that the groundwater flow becomes steady after 2 days pumping in this simulated scenario.

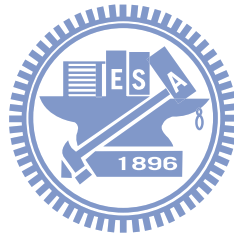


3.3. Effect of heterogeneity

Figure 5 demonstrates the effect of heterogeneity on the groundwater distribution. Two types of aquifer formation materials, coarse sand and fine sand, are considered for the present aquifer system. In Figure 5a, the aquifer in region 1 with coarse sand medium has hydraulic conductivity of 520 m/day while that in region 2 with fine sand medium has hydraulic conductivity of 50 m/day . In contrast to Figure 5a, the aquifer shown in Figure 5b is considered to be homogeneous with coarse sand medium. The well with pumping rate of $8\text{ m}^3/\text{day}$ is located at $(x, y) = (700\text{ m}, 140\text{ m})$. The hydraulic head distribution shown in these two figures are significantly different at $t = 7$ days. The drawdown shown in Figure 5a is much larger than that in Figure 5b because the aquifer in region 2 is relatively low permeable.

3.4. Multi-pumping/injection wells

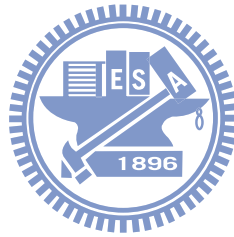
The effect of the well locations upon the hydraulic head distribution in an aquifer with irregular boundary is investigated in Figure 6. The conductivities K_x and K_y are 520 m/day for the whole region. One pumping well with a rate of $6m^3/day$ is located at (100 m , 100 m) and two injection wells with a rate of $3m^3/day$ are placed at (400 m , 150 m) and (150 m , 400 m). Figure 6 illustrates that the groundwater flow within the contaminated area can be restrained by those three wells. As demonstrated here, the semi-analytical solution can be used to predict the flow field induced by multi-wells in an L-shaped aquifer. Coupled with an optimization algorithm, this solution can be used to determine the well number, well locations, and their pumping rates for pump-and-treat design in an L-shaped aquifer if it has been contaminated.



3.5. Trapezoid aquifer

The present solutions can also be used to predict the flow induced by pumping in a trapezoid aquifer with 45 degree at the acute angle as shown in Figure 7. Following two conditions must be met if employing the present solution to predict the flow in a trapezoid aquifer. They are the aquifer must be isotropic and homogeneous and the hydraulic heads at two constant-head boundaries have to be equal. A dashed line can be drawn between two re-entrant angles as shown in Figure 7b and an imaginary pumping well should be placed at the location which is symmetric to the pumping well with respect to the dashed line. Thus, the dashed line can be considered as an impermeable boundary for the trapezoid aquifer. Figure 7b demonstrates the transient drawdown distribution at $t = 2$ days for the pumping well located at (180 m , 76 m) and (76 m , 180 m) with the rate of 40 m^3/day . The

conductivities K_x and K_y are $2 \times 10^{-2} \text{ m/s}$ and specific storage S_s is $1 \times 10^{-5} \text{ m}^{-1}$ for the whole region, and the hydraulic heads at the boundaries ($x = 200 \text{ m}$ and $y = 200 \text{ m}$) are equal to 30 m . The aquifer thickness is 20 m . As a result, a symmetric pattern of the hydraulic head distribution can be observed in the figure. The hydraulic head distribution in the right trapezoid aquifer with a pumping well shown in Figure 7a can therefore be simulated as a part of hydraulic head distribution in Figure 7b. To our knowledge, the semi-analytical solution describing the flow induced by pumping in trapezoid aquifers has never before been presented. The solution derived herein for an L-shaped aquifer can accordingly be applied to solve the flow problems in trapezoid aquifers.



CHAPTER 4 CONCLUDING REMARKS

A new semi-analytical model has been developed to analyze the hydraulic head distributions induced by pumping in a heterogeneous and anisotropic aquifer with an L-shaped domain. Method of domain decomposition is used to divide the aquifer into two sub-regions with different hydraulic conductivities. Steady-state solution is first derived and used as the initial condition before pumping in the L-shaped aquifer system. The Laplace-domain solution of the model is derived using the Fourier finite cosine transform and the Laplace transform. The Stehfest algorithm is then adopted to evaluate the time-domain results. The effects of anisotropy, heterogeneity, and boundary conditions due to pumping are investigated. The present solutions can describe the steady-state and transient distribution of hydraulic head induced by pumping in L-shaped aquifers. Following conclusions can be drawn from this study:

1. The steady-state hydraulic head distributions indicate that the flow in region 1 is mainly in x -direction and in region 2 is in y -direction.
2. The anisotropic ratio has a significant effect on the flow pattern. The flow velocity in x -direction increases with anisotropic ratio.
3. The developed solution can be used to assess the effects of heterogeneity and multi-well locations on the head distribution. In addition, it can also be used to solve the flow problems in trapezoid aquifers.



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APPENDIX A: STEADY STATE SOLUTIONS FOR AN L-SHAPED AQUIFER WITHOUT PUMPING

In accordance with the dimensionless variables defined in section 2.2, Eqs. (1) and (2) can be written, respectively, as

$$\kappa_1 \frac{b_2^2}{l_1^2} \frac{\partial^2 \phi_1^*}{\partial x^{*2}} + \frac{\partial^2 \phi_1^*}{\partial y^{*2}} = \frac{\partial \phi_1^*}{\partial t^*} - \sum_{k=1}^M Q_{1k}^* \delta(x^* - x_{1k}^*) \delta(y^* - y_{1k}^*),$$

$$0 \leq x^* \leq 1, \quad 0 \leq y^* \leq b_1^* \tag{A1}$$

and

$$\kappa_2 \frac{b_2^2}{l_1^2} \frac{\partial^2 \phi_2^*}{\partial x^{*2}} + \frac{\partial^2 \phi_2^*}{\partial y^{*2}} = \frac{S_{s2}}{S_{s1}} \frac{K_{y1}}{K_{y2}} \frac{\partial \phi_2^*}{\partial t^*} - \sum_{k=1}^N Q_{2k}^* \delta(x^* - x_{2k}^*) \delta(y^* - y_{2k}^*),$$

$$0 \leq x^* \leq l_2^*, \quad b_1^* \leq y^* \leq 1 \tag{A2}$$

The dimensionless boundary conditions for region 1 can be expressed as:

$$\phi_1^* = 0, \text{ at } x^* = 1, \quad 0 \leq y^* \leq b_1^* \tag{A3}$$

$$\frac{\partial \phi_1^*}{\partial x^*} = 0, \text{ at } x^* = 0, \quad 0 \leq y^* \leq b_1^* \tag{A4}$$

$$\frac{\partial \phi_1^*}{\partial y^*} = 0, \text{ at } y^* = 0, \quad 0 \leq x^* \leq 1 \tag{A5}$$

$$\frac{\partial \phi_1^*}{\partial y^*} = 0, \text{ at } y^* = b_1^*, \quad l_2^* \leq x^* \leq 1 \tag{A6}$$

Similarly, the dimensionless boundary conditions for region 2 are

$$\frac{\partial \phi_2^*}{\partial x^*} = 0, \text{ at } x^* = 0, \quad b_1^* \leq y^* \leq 1 \tag{A7}$$

$$\frac{\partial \phi_2^*}{\partial x^*} = 0, \text{ at } x^* = l_2^*, \quad b_1^* \leq y^* \leq 1 \tag{A8}$$

$$\phi_2^* = \frac{h_2 - h_1}{h_1}, \text{ at } y^* = 1, \quad 0 \leq x^* \leq l_2^* \quad (\text{A9})$$

The continuity conditions of hydraulic head and flux in dimensionless form are, respectively,

$$h_1 \phi_1^*(x^*, b_1^*) = h_2 \phi_2^*(x^*, b_1^*), \text{ at } 0 \leq x^* \leq l_2^* \quad (\text{A10})$$

and

$$K_{y1} h_1 \left. \frac{\partial \phi_1^*}{\partial y^*} \right|_{y^*=b_1^*} = K_{y2} h_2 \left. \frac{\partial \phi_2^*}{\partial y^*} \right|_{y^*=b_1^*}, \text{ at } 0 \leq x^* \leq l_2^* \quad (\text{A11})$$

Without the pumping, the steady-state solution for groundwater flow can be solved after removing all the right-hand side terms in Eqs. (A1) and (A2). Multiplying Eq. (A1) by $\cos(\lambda_m x^*)$ and integrating it from $x^* = 0$ to $x^* = 1$ in region 1 with boundary conditions Eqs. (A3) and (A4), Eq. (A1) is then transformed to

$$\Omega_{1m}^2 \bar{\phi}_1^* - \frac{\partial^2 \bar{\phi}_1^*}{\partial y^{*2}} = 0 \quad (\text{A12})$$

with

$$\bar{\phi}_1^* = \int_0^1 \phi_1^* \cos(\lambda_m x^*) dx^*$$

where $\lambda_m = (m + 1/2)\pi$, $m = 0, 1, 2, 3, \dots$

Similarly, Eq. (A2) can be transformed via multiplying Eq. (A2) by $\cos(\alpha_n x^*)$ and integrating it from $x^* = 0$ to $x^* = l_2^*$ in region 2 with boundary conditions Eqs. (A7) and (A8). The result is

$$\Omega_{2n}^2 \bar{\phi}_2^* - \frac{\partial^2 \bar{\phi}_2^*}{\partial y^{*2}} = 0 \quad (\text{A13})$$

with

$$\bar{\phi}_2^* = \int_0^{l_2^*} \phi_2^* \cos(\alpha_n x^*) dx^*$$

where $\alpha_n = n\pi/l_2^*$, $n = 0, 1, 2, 3, \dots$

The general solutions of Eqs. (A12) and (A13) are

$$\bar{\phi}_1^*(m, y^*) = C_{1m} e^{\Omega_{1m} y^*} + C_{2m} e^{-\Omega_{1m} y^*} \quad (\text{A14})$$

and

$$\bar{\phi}_2^*(n, y^*) = D_{1n} e^{\Omega_{2n} y^*} + D_{2n} e^{-\Omega_{2n} y^*} \quad (\text{A15})$$

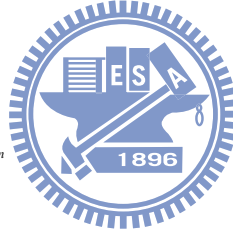
where $\Omega_{1m} = \lambda_m \sqrt{\kappa_1} b_2/l_1$ and $\Omega_{2n} = \alpha_n \sqrt{\kappa_2} b_2/l_1$. The coefficients C_{1m} , C_{2m} , D_{1n} and D_{2n} are unknowns and to be determined. Using boundary conditions Eqs. (A5) and (A9),

the following relation can be obtained

$$C_{1m} = C_{2m} \quad (\text{A16})$$

and

$$D_{1n} = \Delta_{n,0} \frac{h_2 - h_1}{h_2} l_2^* e^{-\Omega_{2n}} - D_{2n} e^{-2\Omega_{2n}} \quad (\text{A17})$$



$$\text{where } \Delta_{n,0} = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

Substituting Eqs. (A16) and (A17) into Eqs. (A14) and (A15), the inversions of $\bar{\phi}_1^*$ and $\bar{\phi}_2^*$ lead to Eqs. (12) and (13). The Fourier finite cosine inversions for regions 1 and 2 are

$$\phi_1^*(m, y^*) = \sum_{m=0}^{\infty} \Delta_{1m} \bar{\phi}_1^*(m, y) \cos(\lambda_m x) \quad (\text{A18})$$

$$\phi_2^*(n, y^*) = \sum_{n=0}^{\infty} \Delta_{2n} \bar{\phi}_2^*(n, y) \cos(\alpha_n x) \quad (\text{A19})$$

The coefficients of C_{1m} and D_{2n} obtained by using the boundary condition Eq. (A6) and the continuity conditions Eqs. (A10) and (A11) are given in Eqs. (17) and (18), respectively.

APPENDIX B: TRANSIENT STATE SOLUTIONS

Multiplying Eq. (A1) by $\cos(\lambda_i x^*)$ and integrating it from $x^* = 0$ to $x^* = 1$ in region 1 with boundary conditions Eqs. (A3) and (A4), Eq. (A1) can be transformed as

$$-\Omega_{1i}^2 \bar{\phi}_1^* + \frac{\partial^2 \bar{\phi}_1^*}{\partial y^{*2}} = \frac{\partial \bar{\phi}_1^*}{\partial t^*} - \sum_{k=1}^M Q_{1k}^* \cos(\lambda_i x_{1k}^*) \delta(y^* - y_{1k}^*) \quad (\text{B1})$$

with

$$\bar{\phi}_1^* = \int_0^1 \phi_1^* \cos(\lambda_i x^*) dx^*$$

where $\lambda_i = (i+1/2)\pi/l_1^*$, $i = 0,1,2,3,\dots$, and $\Omega_{1i} = \lambda_i \sqrt{\kappa_1} b_2/l_1$.

Similarly, Eq. (A2) can be transformed via multiplying Eq. (A2) by $\cos(\alpha_j x^*)$ and integrating it from $x^* = 0$ to $x^* = l_2^*$ in region 2 with boundary conditions Eqs. (A7) and (A8). The result is

$$-\Omega_{2j}^2 \bar{\phi}_2^* + \frac{\partial^2 \bar{\phi}_2^*}{\partial y^{*2}} = \frac{K_{y1}}{K_{y2}} \frac{S_{s2}}{S_{s1}} \frac{\partial \bar{\phi}_2^*}{\partial t^*} - \sum_{k=1}^N Q_{2k}^* \cos(\alpha_j x_{2k}^*) \delta(y^* - y_{2k}^*) \quad (\text{B2})$$

with

$$\bar{\phi}_2^* = \int_0^{l_2^*} \phi_2^* \cos(\alpha_j x^*) dx^*$$

where $\alpha_j = j\pi/l_2^*$, $j = 0,1,2,3,\dots$, and $\Omega_{2j} = \alpha_j \sqrt{\kappa_2} b_2/l_1$.

Then, taking Laplace transforms with respect to t of Eqs. (B1) and (B2) with the initial conditions Eqs. (12) and (13), respectively, results in

$$-\mu_i^2 \bar{\tilde{\phi}}_1^* + \frac{\partial^2 \bar{\tilde{\phi}}_1^*}{\partial y^{*2}} = -\frac{1}{2} \sum_{m=0}^{\infty} \Delta_{1m} \Lambda_{m,i} C_{1m} E(m, y^*) - \frac{1}{p} \sum_{k=1}^M Q_{1k}^* \cos(\lambda_i x_{1k}^*) \delta(y^* - y_{1k}^*) \quad (\text{B3})$$

and

$$-\theta_j^2 \bar{\phi}_2^* + \frac{\partial^2 \bar{\phi}_2^*}{\partial y^{*2}} = -\frac{l_2^* K_{y1} S_{s2}}{2 K_{y2} S_{s1}} \sum_{n=0}^{\infty} \Delta_{2n} \Lambda_{n,j} (D_{2n} F(n, y^*) + B(n, y^*)) - \frac{1}{p} \sum_{k=1}^N Q_{2k}^* \cos(\alpha_j x_{2k}^*) \delta(y^* - y_{2k}^*) \quad (\text{B4})$$

with

$$\bar{\phi}^*(i, y^*, p) = \int_0^{\infty} \bar{\phi}^*(i, y^*, t) e^{-pt} dt$$

The general solutions of Eqs. (B3) and (B4) can be expressed as

$$\bar{\phi}_1^*(i, y^*, p) = T_{1i} e^{\mu_i y^*} + T_{2i} e^{-\mu_i y^*} + \bar{\phi}_{1p}^*(i, y^*, p) \quad (\text{B5})$$

and

$$\bar{\phi}_2^*(j, y^*, p) = T_{1j} e^{\theta_j y^*} + T_{2j} e^{-\theta_j y^*} + \bar{\phi}_{2p}^*(j, y^*, p) \quad (\text{B6})$$

The particular solutions $\bar{\phi}_{1p}^*(i, y^*, p)$ and $\bar{\phi}_{2p}^*(j, y^*, p)$ presented as Eqs. (25) and (27)

are, respectively, from

$$\bar{\phi}_{1p}^*(i, y^*, p) = \frac{e^{\mu_i y^*}}{2\mu_i} \int e^{-\mu_i y^*} \Gamma_1(i, y^*, p) dy^* - \frac{e^{-\mu_i y^*}}{2\mu_i} \int e^{\mu_i y^*} \Gamma_1(i, y^*, p) dy^* \quad (\text{B7})$$

and

$$\bar{\phi}_{2p}^*(j, y^*, p) = \frac{e^{\theta_j y^*}}{2\theta_j} \int e^{-\theta_j y^*} \Gamma_2(j, y^*, p) dy^* - \frac{e^{-\theta_j y^*}}{2\theta_j} \int e^{\theta_j y^*} \Gamma_2(j, y^*, p) dy^* \quad (\text{B8})$$

with

$$\Gamma_1(i, y^*, p) = -\frac{1}{2} \sum_{m=0}^{\infty} \Delta_{1m} \Lambda_{m,i} C_{1m} E(m, y^*) - \frac{1}{p} \sum_{k=1}^M Q_{1k}^* \cos(\lambda_i x_{1k}^*) \delta(y^* - y_{1k}^*) \quad (\text{B9})$$

$$\Gamma_2(j, y^*, p) = -\frac{l_2^* K_{y1} S_{s2}}{2 K_{y2} S_{s1}} \sum_{n=0}^{\infty} \Delta_{2n} \Lambda_{n,j} (D_{2n} F(n, y^*) + B(n, y^*)) - \frac{1}{p} \sum_{k=1}^N Q_{2k}^* \cos(\alpha_j x_{2k}^*) \delta(y^* - y_{2k}^*) \quad (\text{B10})$$

In addition, T_{1i} , T_{2i} , T_{1j} and T_{2j} are unknown coefficients to be determined. Using

boundary conditions Eqs. (A5) and (A9), the following relations can be obtained

$$T_{2i} = T_{1i} \quad (\text{B11})$$

and

$$T_{1j} = -T_{2j}e^{-2\theta_j} + e^{-\theta_j} \left(\Delta_{j,0} \frac{l_2^* h_2 - h_1}{p h_2} - \bar{\phi}_{2p}^*(j, b_2^*, p) \right) \quad (\text{B12})$$

$$\text{where } \Delta_{j,0} = \begin{cases} 1, & j = 0 \\ 0, & j \neq 0 \end{cases}.$$

Substituting Eqs. (B11) and (B12) into Eqs. (B5) and (B6), respectively, the inversions of $\bar{\phi}_1^*$ and $\bar{\phi}_2^*$ lead to Eqs. (21) and (22). The Fourier finite cosine inversions for regions 1 and 2 are

$$\tilde{\phi}_1^*(i, y^*, p) = \sum_{i=0}^{\infty} \Delta_{1i} \bar{\phi}_1^*(i, y, p) \cos(\lambda_i x) \quad (\text{B13})$$

$$\tilde{\phi}_2^*(j, y^*, p) = \sum_{j=0}^{\infty} \Delta_{2j} \bar{\phi}_2^*(j, y, p) \cos(\alpha_j x) \quad (\text{B14})$$

The coefficients of T_{1i} and T_{2j} obtained by using the boundary condition Eq. (A6) and the continuity conditions Eqs. (A10) and (A11) are presented as Eqs. (28) and (29), respectively.

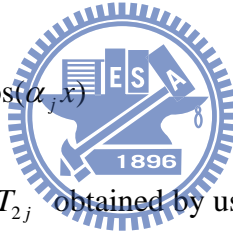


Table 1. Notations.

Ω_{1v}	:	$\lambda_v \sqrt{\kappa_1} b_2 / l_1, \quad v = m, i$
Ω_{2w}	:	$\alpha_w \sqrt{\kappa_2} b_2 / l_1, \quad w = n, j$
$\alpha_{w=n,j}$:	$w\pi / l_2^*, \quad w = 0, 1, 2, 3, \dots, \quad w = n, j$
$\lambda_{v=m,i}$:	$(v + 1/2)\pi / l_1^*, \quad v = 0, 1, 2, 3, \dots, \quad v = m, i$
μ_i	:	$\sqrt{\kappa_1 (b_2^2 / l_1^2) \lambda_i^2 + p}$
θ_j	:	$\sqrt{\kappa_2 (b_2^2 / l_1^2) \alpha_j^2 + \kappa_2 (S_{s2} / S_{s1}) p}$
$\delta(x^* - x_{1ii}^*)$:	$\begin{cases} \infty, & x^* = x_{1ii}^* \\ 0, & x^* \neq x_{1ii}^* \end{cases}$
$\delta(y^* - y_{2jj}^*)$:	$\begin{cases} \infty, & y^* = y_{2jj}^* \\ 0, & y^* \neq y_{2jj}^* \end{cases}$
Δ_{1q}	:	$\begin{cases} 2/l_1^*, & q = 0 \\ 2/l_1^*, & q \neq 0 \end{cases}, \quad q = m, i$
Δ_{2r}	:	$\begin{cases} 1/l_2^*, & r = 0 \\ 2/l_2^*, & r \neq 0 \end{cases}, \quad r = n, j$
$\Delta_{w,0}$:	$\begin{cases} 1, & w = 0 \\ 0, & w \neq 0 \end{cases}, \quad w = n, j$
$\Lambda_{n,j}$:	$\begin{cases} 2, & n = j = 0 \\ 1, & n = j \neq 0 \\ 0, & n \neq j \end{cases}$



$$\Lambda_{m,i} \quad : \quad \begin{cases} 1, & m = i \\ 0, & m \neq i \end{cases}$$

$$H(y^* - y_{1ii}^*) \quad : \quad \begin{cases} 1, & y^* > y_{1ii}^* \\ 0, & y^* < y_{1ii}^* \end{cases}$$

$$H(y^* - y_{2jj}^*) \quad : \quad \begin{cases} 1, & y^* > y_{2jj}^* \\ 0, & y^* < y_{2jj}^* \end{cases}$$

Table 2. The constant-head boundaries and the anisotropic ratio of the hydraulic conductivities for cases (a) – (c)

Case	constant-head boundary (m)		hydraulic conductivity (m/s)				anisotropic ratio of hydraulic conductivity	
	h_1	h_2	K_{x1}	K_{y1}	K_{x2}	K_{y2}	${}^a\kappa_1$	${}^a\kappa_2$
a	85	80	0.003	0.003	0.003	0.003	1	1
b	85	80	0.006	0.003	0.006	0.003	2	2
c	85	80	0.0015	0.003	0.0015	0.003	0.5	0.5

${}^a\kappa_1$ represents the anisotropic ratio of the hydraulic conductivity in region 1

${}^b\kappa_2$ represents the anisotropic ratio of the hydraulic conductivity in region 2

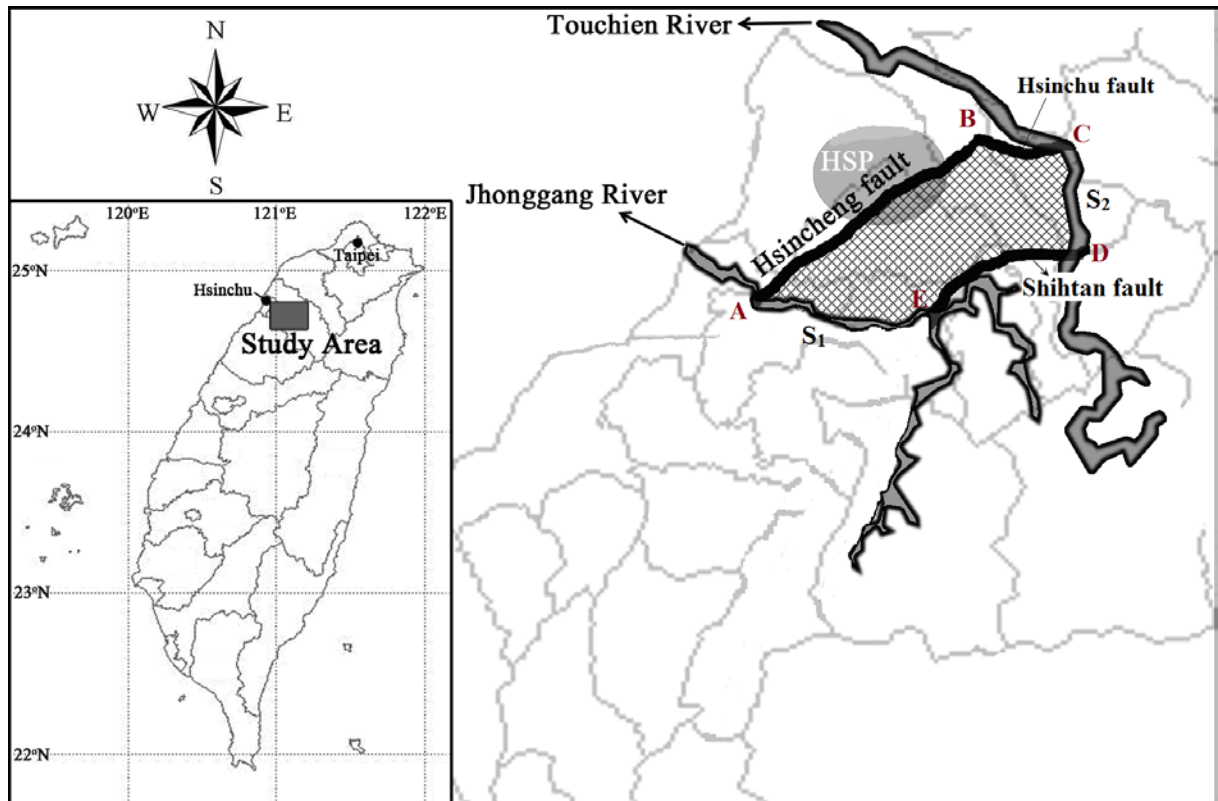


Figure 1. Map of an aquifer in Hsinchu, Taiwan. The study area is shaded. (modified from Hydrological year book of Taiwan, 2010, Part II-River stage and discharge, and Taiwan Active Fault Information System)

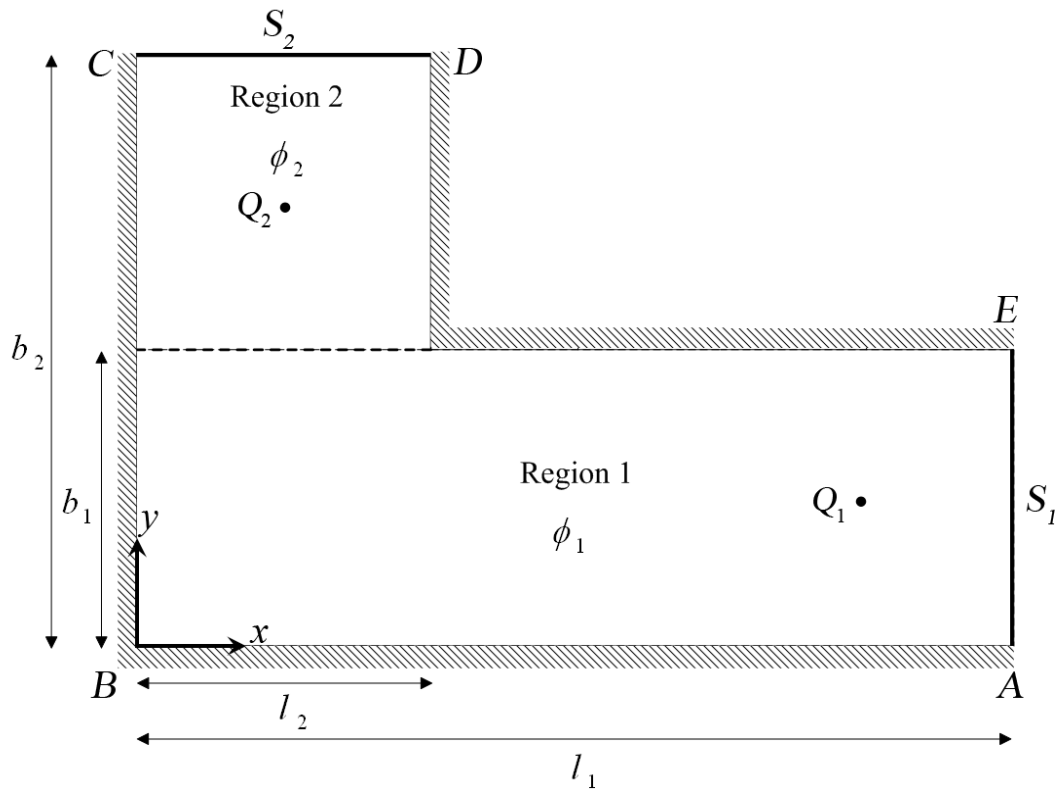
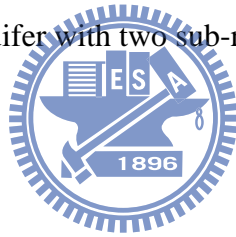
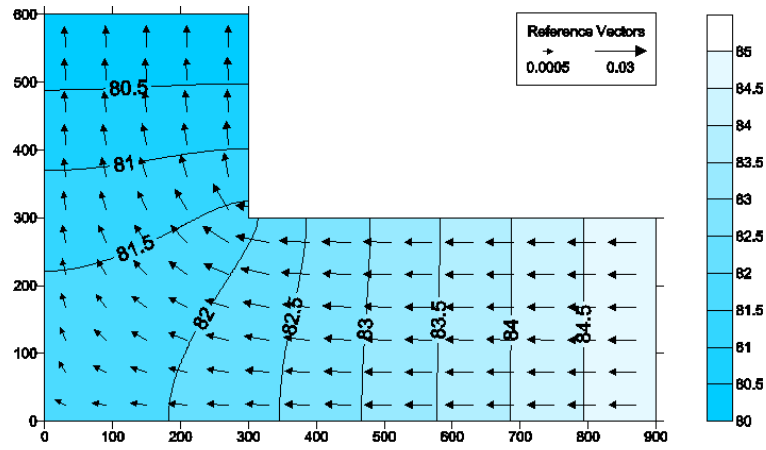
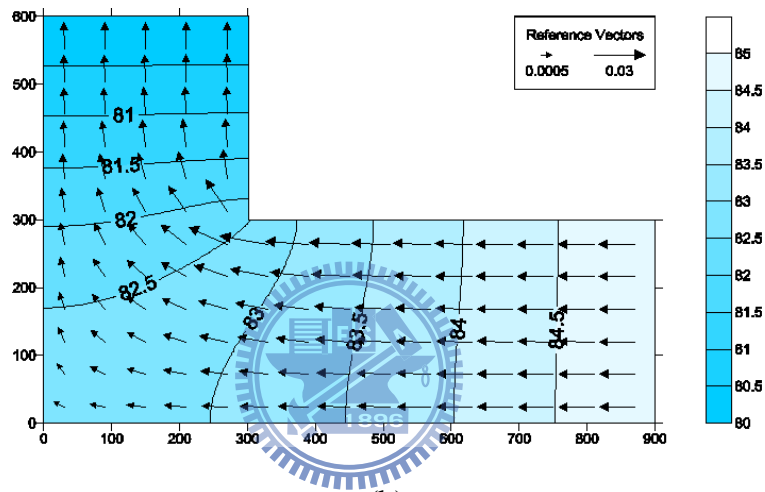


Figure 2. An L-shaped alluvial aquifer with two sub-regions.

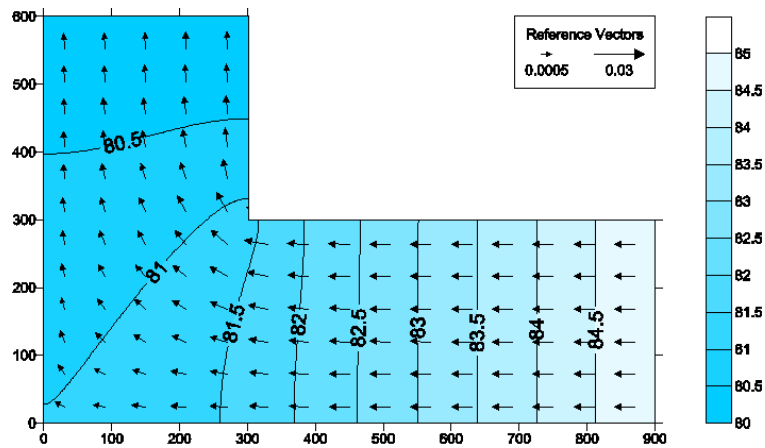




(a)

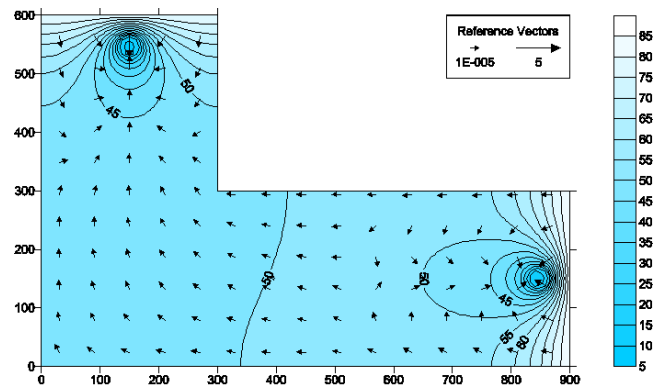


(b)

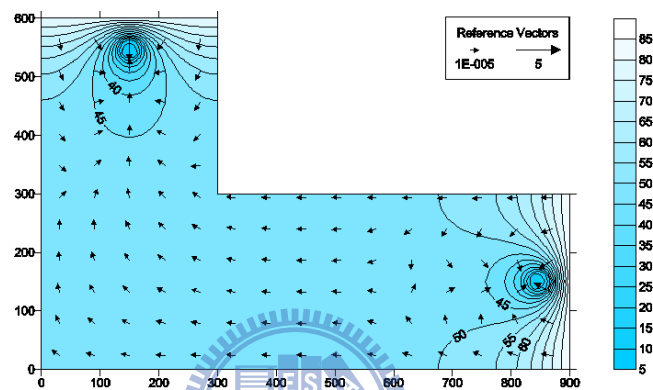


(c)

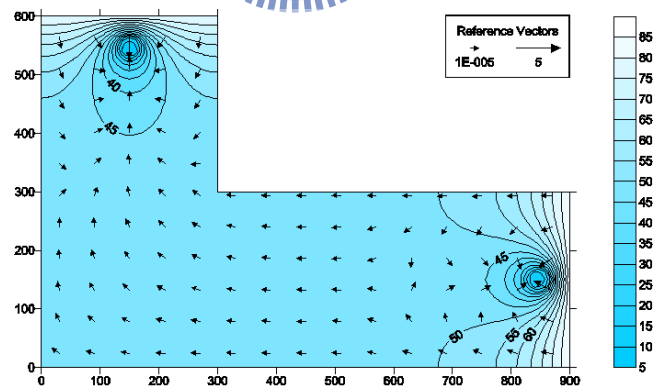
Figure 3. Steady-state hydraulic head distribution in the aquifer with anisotropic ratio of (a) 1, (b) 2, (c) 0.5.



(a) $t = 2$ hrs

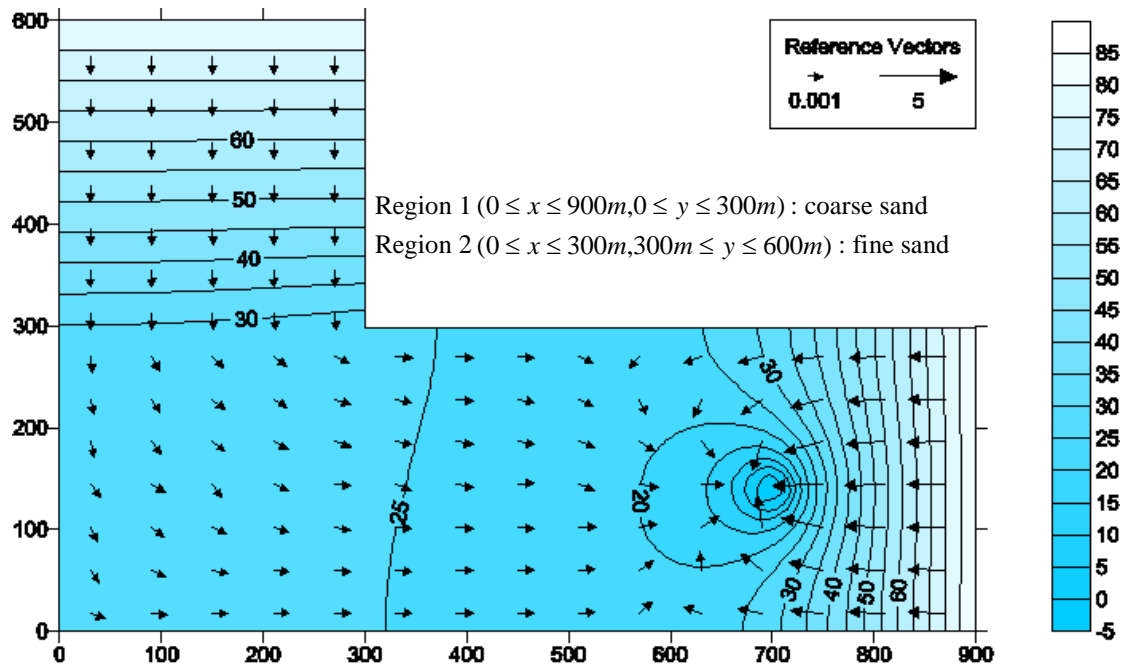


(b) $t = 2$ days

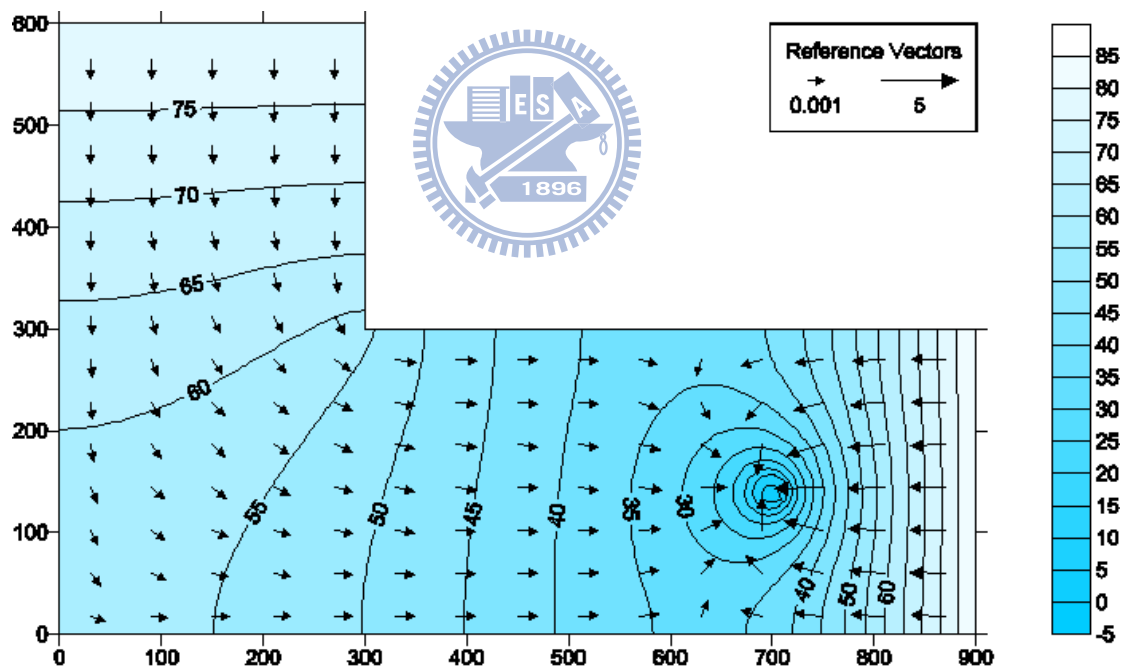


(c) $t = 7$ days

Figure 4. Hydraulic head distributions in aquifers with $K_x = K_y = 520$ m/day at time (a) 2 hrs, (b) 2 days, (c) 7 days.



(a)



(b)

Figure 5. Transient hydraulic head distributions induce by pumping at $t = 7$ days in

(a) heterogeneous aquifer and (b) homogeneous aquifer.

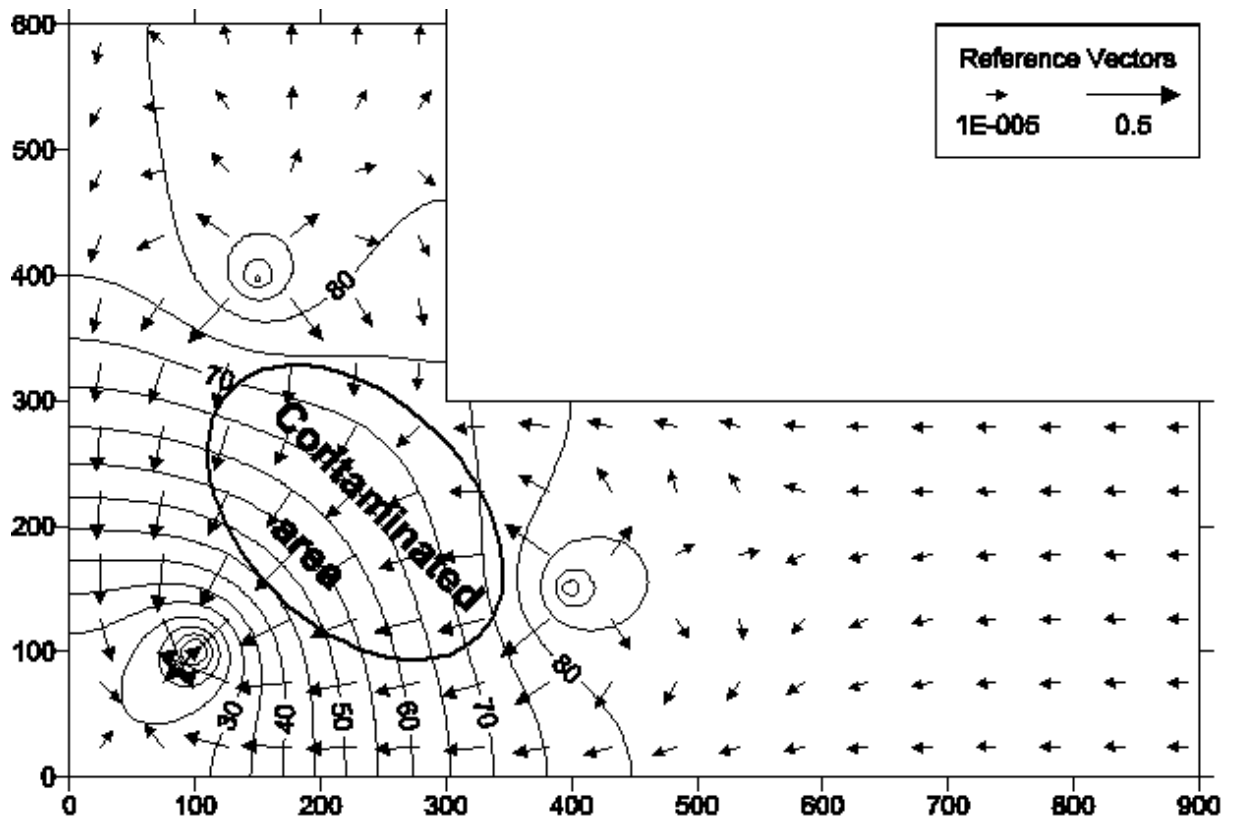
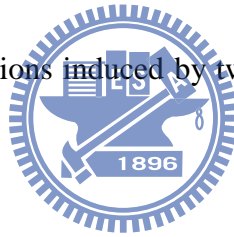
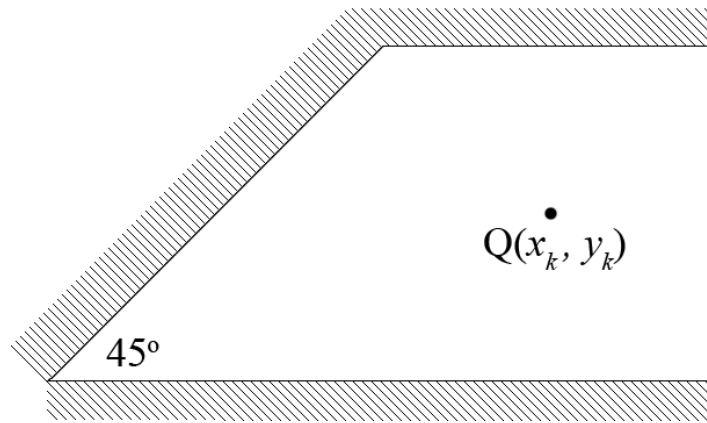
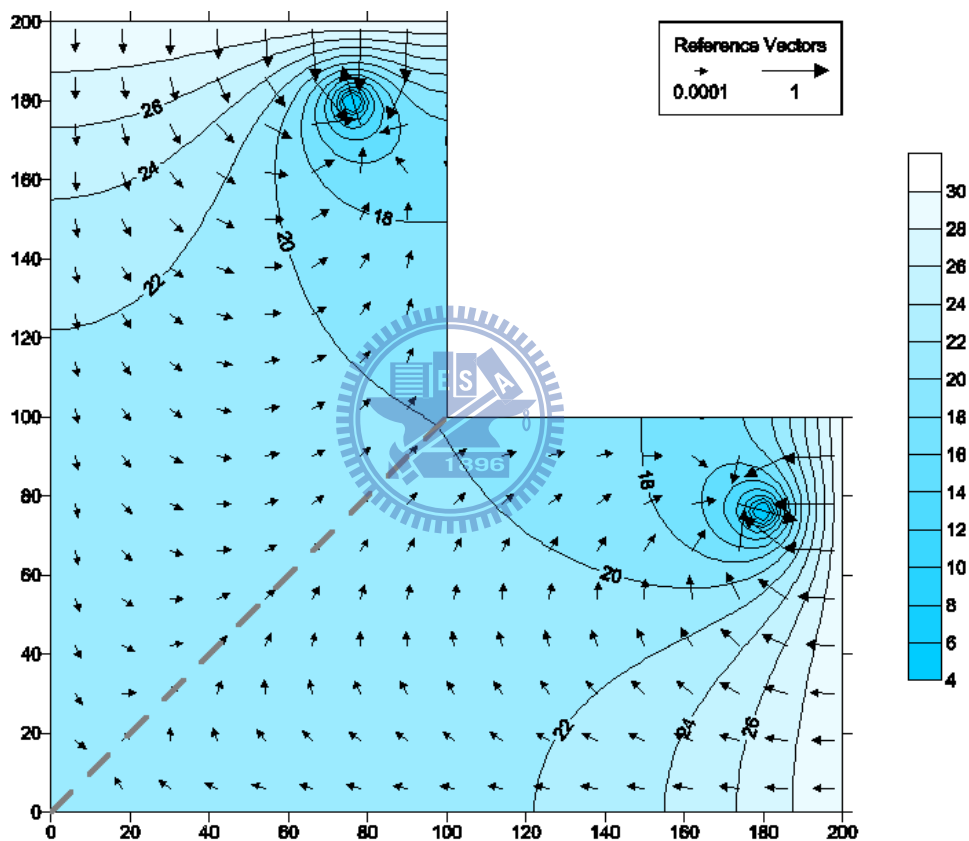


Figure 6. Hydraulic head distributions induced by two injection wells and one pumping well at $t = 1$ day.





(a)



(b)

Figure 7. (a) A trapezoid aquifer (b) The head distribution induced by two pumping wells located at $(76\text{ m}, 180\text{ m})$ and $(180\text{ m}, 76\text{ m})$ at $t = 2$ days.