安全巡邏自動車之路徑規劃與遠端呈現

Path Planning and Telepresence for

Patrolling Mobile Robot

研究生:李彥慶 Student: Yang-Ching Li

指導教授:楊谷洋 博士 Advisor: Dr. Kuu-Young Young



A Thesis

Submitted to Department of Electrical and Control Engineering
College of Electrical Engineering and Computer Science
National Chiao Tung University
in Partial Fulfillment of the Requirements
of the Degree of Master

in

Electrical and Control Engineering
July 2005
Hsinchu, Taiwan, Republic of China

中華民國 九十四 年 七 月