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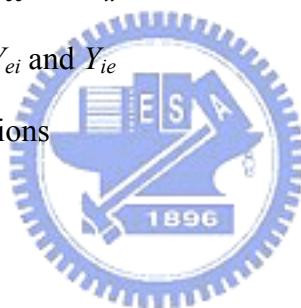
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Chapter 4

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Chapter 5

Fig. 5.1 Estimated error ε_i for the proposed method. The lines designated by ε_L and ε_M , represent the corresponding error function used in the conventional method [1], [2], respectively.

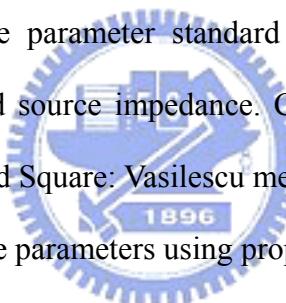
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Chapter 6

Fig. 6.1 Illustration of a general four-port structure. The two extrinsic ports of the DUT are denoted ports 1 and 2, and the two ports of intrinsic device (INT) are denoted ports 3 and 4.

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Fig. 6.8 Extracted collector current noise versus collector current.

Fig. 6.9 Extracted collector current noise versus collector current.

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