LIST OF FIGURES

Figure 2.1. An orthogonal rotation in two dimensions 13

Figure 2.2. An orthogonal rotation in three dimensions 14

Figure 2.3. Spacecraft on the orbit 16

Figure 2.4. Transformation representation 19

Figure 2.5. FDD configuration 20

Figure 2.6. Passive control when normal operation (design for u_2 outage)

(a) states (b) input torques 29

Figure 2.7. Passive control when u_1 fail (design for u_2 outage)

(a) states (b) input torques 30

Figure 2.8. Passive control when u_2 fail (design for u_2 outage)

(a) states (b) input torques 31

Figure 2.9. Passive control when u_3 fail (design for u_2 outage)

(a) states (b) input torques 32

Figure 2.10. Passive control when u_4 fail (design for u_2 outage)

(a) states (b) input torques 33

Figure 2.11. Active control when normal operation

(a) states (b) input torques (c) alarms and residuals 34

Figure 2.12. Active control when u_1 fail

(a) states (b) input torques (c) alarms and residuals 35

Figure 2.13. Active control when u_2 fail

(a) states (b) input torques (c) alarms and residuals 36

Figure 2.14. Active control when u_3 fail

(a) states (b) input torques (c) alarms and residuals 37

Figure 2.15. Active control when u_4 fail

(a) states (b) input torques (c) alarms and residuals 38

LIST OF TABLES

Table 2.1. Performance of passive control (design for u2 fail) 28

Table 2.2. Performances of active control 28

Table 3.1. Energy required to transfer stat 45

Table 3.2. Distance to uncontrollable 50

Table 3.3. Mobility of spacecraft system 59