

仿生四足機器人在障礙路面的步伐規劃與實驗
Gait Design and Experiment of a Bionic Quadruped Robot Walking on Irregular Terrain

研究生：王證凱

Student : Chen-Kai Wang

指導教授：鄭璧瑩 博士

Advisor : Dr. Pi-Ying Cheng

國立交通大學
機械工程學系
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