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一個有效解決日本益智遊戲「發現小花」的演算法

An Efficient Algorithm for Solving Japanese Puzzles

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摘要

日本益智遊戲「發現小花」是風行於日本與荷蘭的邏輯遊戲之一,而 「該謎題是否能解」是一個難以回答的問題,甚至是一個非決定性多項式 時間-完全(NP-complete)問題。目前已有一些相關論文提出,有的是利 用基因演算法解決,但是可能造成錯誤的答案出現;而有的是利用深先搜 尋演算法,該演算法是一種暴力搜尋法,所以執行速度很慢;因此,在這 篇論文裡,我們想要提出一種演算法來盡可能快速的解決所有謎題,這個 演算法不只加速了深先搜尋法的速度,更確保了謎題解答的正確性。在這 個遊戲裡,很多謎題是緊密而連續的圖形,我們可因此推導出一些邏輯規 則,按照這些規則去填出那些可以馬上決定位置的格子;然而,並非所有 謎題都可以依邏輯規則完全解出,像是有些隨意產生的謎題需要另一種方 法來輔助,在這種情況下,我們使用深先搜尋演算法,但為了加快執行速 度,分支界限法的觀念被引進,其目的是提早終止那些不合法的路徑。實 驗的結果顯示,我們的演算法成功地解決日本益智遊戲「發現小花」,而 執行速度也比一般的深先搜尋法來得快速。

I

An Efficient Algorithm for Solving Japanese Puzzles

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ABSTRACT

Japanese puzzle is one of logical games popular in Japan and Netherlands. The question "Is this puzzle solvable?" is difficult to answer, even is an NP-complete problem. At present, there have been some related papers proposed. Some use genetic algorithm (GA), but the solution may be wrong. Some use depth first search (DFS) algorithm. The DFS algorithm is an exhaustive search, so the execution speed is slow. Hence, in this thesis, we want to propose an algorithm to solve puzzles as quickly as possible. The algorithm not only accelerates the speed of DFS but also ensures the correctness of the solution of a puzzle. In this puzzle game, many puzzles are compact and contiguous pictures. Based on this, we can deduce some logical rules, and use these rules to paint those cells whose positions can be determined immediately. However, not all puzzles can be solved completely by logical rules. In this situation, we use the DFS algorithm to complete the puzzle solving. In order to speed up the process, the "branch and bound" technique is used to do early termination for those impossible paths. Experimental results show that our algorithm can solve Japanese puzzles successfully, and the processing speed is significantly faster than that of DFS.

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CHAPTER 1 INTRODUCTION

1.1 Motivation

Japanese puzzle, also known as nonogram, is one of logical games popular in Japan and Netherlands. The game is recommended to Taiwan recently, but few papers are concerned with this topic – Japanese nonograms. In addition, some related papers solved this problem by non-logical algorithms, and the execution speed is slow. On the other hand, the question "Is this puzzle solvable?" turns out to be very hard to answer in general, even is a NP-complete problem [1-2]. In this thesis, we will present a fast method to solve this problem. First, we will provide some logical rules to solve most part of a puzzle, and then use DFS with branch and bound scheme to solve the remaining part. The detail of our proposed method will be described in Chapter 2.



1.2 Japanese Puzzles

Japanese puzzles will be described in this section. Fig. 1.1 (a) is a simple puzzle and Fig. 1.1 (b) is the solution of Fig. 1.1 (a). Ignoring the numbers, the solution can be considered as a black-white (1-and-0) picture. Here, we use \blacksquare as a colored (black) cell, \square as an empty (white) cell, and \blacksquare as an unknown cell (i.e. an undetermined cell).

The positive integers alongside the rows and columns give the information about the lengths of black runs (a black run: contiguous black cells) in that row or column respectively. The goal is to paint the cells to form a picture that satisfies the following constraints:

- 1. Each cell must be colored (black) or left empty (white).
- 2. If a row or column has k numbers: $s_1, s_2, ..., s_k$, then it must contain k black runs the first (leftmost for rows / topmost for columns) black run with the length s_1 , the second black run with the length s_2 , and so on.
- 3. There should be at least one empty cell between two consecutive black runs.



Fig. 1.1 Japanese puzzle. (a) A simple puzzle. (b) The solution of (a).

It is evident that the puzzle in Fig. 1.1 (a) has a unique solution. However, the puzzle in Fig. 1.2 has two solutions, and the puzzle in Fig. 1.3 has no solution (i.e. no corresponding picture). Hence, there may be no, exact one, or more than one solution for given integral numbers.

	1	2	1	2	1
1					
1					
3					
2					

Fig. 1.2 A puzzle with two solutions.

				1		1		1
				1	3	1	2	1
		1						
1	1	1						
		5						
	1	1						
		1						

Fig. 1.3 A puzzle with no solution.

1.3 Previous Works

In 2004, Batenburg [3] described an evolutionary algorithm for discrete tomography (DT). And then Batenburg Kosters [4] provided a method to solve Japanese puzzle. By modifying the fitness function in [3], the evolutionary algorithm can be used to solve Japanese puzzle. DT is concerned with the reconstruction of a discrete image from its projections [4]. Japanese puzzles can be considered as a special form of the DT problem. Fig. 1.4 shows an example to explain the difference between them. Since the evolutionary algorithm in [3] will converge to a local optimum, the obtained solution may be incorrect.





Fig. 1.4 DT problem and Japanese puzzle. (a) DT problem. (b) Japanese puzzle.

In 2004, Wiggers [4] proposed a genetic algorithm (GA) and a depth first search (DFS) algorithm to solve Japanese puzzles. He also compared the performance of these two algorithms. For a puzzle of small size, DFS algorithm is faster than GA; otherwise, GA is faster. However, both methods are slow. In the following, we will give a brief description for the DFS algorithm, since it will also be used in our proposed method.

[Depth First Search (DFS)]

It is a straightforward idea to solve the Japanese nonogram by DFS. The author generates all possible solutions of each row. Taking Fig. 1.5 as an example, Fig. 1.6 is its corresponding DFS tree and Fig. 1.7 shows all possible solutions in the tree. Each possible solution corresponds to a path from root to a leaf node, find all paths using DFS and then use the column information of the puzzle to verify each possible solution. A possible solution will be considered as a true solution, if it satisfies all columns' restrictions. Fig. 1.8 (c) is the only correct solution after the verification process. Note that the symbol "X" in Fig. 1.8 stands for the column's restriction not satisfied.



Fig. 1.5 A puzzle problem.



Fig. 1.6 The DFS tree of Fig. 1.5.



Fig. 1.7 Six possible solutions in the DFS tree.



Fig. 1.8 Verification process for the different cases.

Whether the evolutionary algorithm presented in [4] or the genetic algorithm (GA) described in [5], both of them will converge to a local optimum, so sometimes the obtained solution may not be correct. Besides, the depth first search (DFS) algorithm proposed in [5] takes longer time than GA when solving large puzzles. However, DFS will always find correct solutions. In this thesis, some logical rules (LR) are provided to determine the unknown cells in a Japanese puzzle as many as possible, and then DFS is used to solve those remaining unknown cells. In order to speed up the process, the "branch and bound" technique is used to do early termination for those impossible paths.

1.4 Organization of the Thesis

This thesis is composed of five chapters. In Chapter 1, Japanese puzzles and previous works are introduced. And then, the remainder of this thesis is organized as follows. Our proposed algorithm for solving Japanese puzzles will be presented in Chapter 2. In Chapter 3, several experimental results will be shown. Finally, conclusions and future works will be given in the last two chapters.

CHAPTER 2 PROPOSED METHOD

In general Japanese puzzle game, we usually paint those cells which can be determined immediately at first. Then, the rest of undetermined cells will be solved by guess. Based on this fact, we will propose a method to solve Japanese puzzles automatically. The method contains two phases. In the first phase, some logical rules are deduced and used to determine some cells; in the second phase, another method, the depth first search will be applied to solve those remaining unknown cells. Furthermore, the "branch and bound" technique is used to accelerate the searching speed of the general DFS. These two phases will be presented in Sections 2.1 and 2.2. Fig. 2.1 is the flowchart of the proposed method. The conditions in the decision boxes will also be described in Section 2.1.



Fig. 2.1 The flowchart of the proposed method.

2.1 The first phase: Logical rules (LR)

One may also use some skills to solve Japanese puzzles, like the rules described in [6]. In this phase, eleven rules are proposed but we present a new concept of range of a black run ("range" will be explained later). These rules can be divided into three main parts. The first part is to determine which cells should be colored or left empty, the second part is to refine the ranges of black runs, and the third is not only to determine which cells should be colored or left empty but also to refine the ranges of black runs. The first five rules belong to part I, the following three rules belong to part II, and the last three rules belong to part III. Each rule will be applied in each row and then in each column. The total eleven rules are executed sequentially and iteratively.

In the beginning, all cells in the puzzle are considered as unknown. In some iterations, some unknown cells will be determined as colored cells or empty ones. However, in some iterations, maybe only the ranges of some possible black runs are refined. That is, there are not always some unknown cells determined in each iteration. Thus, if no unknown cell is determined and no black run's range is changed, we will stop using logical rules because there will be no changes in later iterations.

Note that, the rules applied in a row are the same as those applied in a column, so we only take a row as an example to explain our algorithm.

Preliminary

The position where a black run may be placed plays an important role. An idea about the range (r_{js}, r_{je}) of a black run j is proposed, where r_{js} stands for the left-most starting position of the run, and r_{je} stands for the right-most ending position of the run. That is, black run j can only be placed between r_{js} and r_{je} . If the range of each black run is precisely estimated, these ranges information can help us to solve puzzles quickly. In the beginning, the initial range of a black run in a row is set between the left-most possible position and the right-most possible position. For each black run, it must reserve some cells for the former black runs and the later ones. Fig. 2.2 shows an example. Fig. 2.2 (a) shows a special row of a puzzle, in this row, there are three black runs with lengths 1, 3, and 2, respectively. Fig. 2.2 (b) shows the left-most possible solution of Fig. 2.2 (a) for each run, the first cell is colored and there is only one empty cell between every two neighboring black runs. Fig. 2.2 (c) shows the right-most possible solution of Fig. 2.2 (a) for each run, the last cell is colored and there is only one empty cell between every two neighboring black runs. Now, we take the second run as an example to do more detail explanation. In Fig. 2.2 (b), the left-most position, at which the first cell of the second black run can start, is the third position. The reason is that there must reserve at least two cells in the head, one cell is reserved for the first black run and the other is reserved for the empty cell between the first and second black runs. Similarly, the right-most position, at which ALLENN the last cell of the second black run can appear, is the seventh position. That is due to that there must reserve at least three cells in the tail, two cells are reserved for the third black run and one cell is reserved for the empty cell between the second and third black runs.

Initial run range estimating

We let the size of each row with k black runs be n and the cells in a row with index (0, ..., n-1), we can use the following formula to determine the initial range of each black run. Specially, r_{js} of the first black run is initialized 0 and r_{je} of the last black run is initialized (n-1).

$$\begin{aligned} r_{js} &= \sum_{i=1}^{j-1} (LB_i + 1), \\ r_{je} &= (n-1) - \sum_{i=j+1}^{k} (LB_i + 1), \end{aligned} \qquad \forall \ j = 1, \dots, k. \end{aligned}$$

where LB_i is the length of black run *i*.

Using the above formula, we can get the initial ranges of the three black runs in Fig. 2.2 (a), which are (0, 2), (2, 6), and (6, 9), respectively.



Fig. 2.2 An illustration of range. (a) A special row of a puzzle. (b) The left-most case

of (a). (c) The right-most case of (a).



Part I

There are five rules in this part, all of them are used to determine which cells should be colored (black) or left empty (white).

Rule 1.1

For each black run, some cells must be colored if all the possible solutions of the black run have the intersection. Actually, the intersection of all possible solutions is also the intersection of the left-most case of the black run and the right-most case of the black run. It is obvious that the intersection exists when the length of the black run's range is less than two times the actual length of a black run. Fig. 2.3 is an example. Consequently, we provide Rule 1.1 to paint the cells sure to be colored. In the rule, c_i is the cell with index i.



Fig. 2.3 An example of Rule 1.1.

For each black run j, cell c_i will be colored when $r_{js} + u \le i \le r_{je} - u$, where $u = (r_{je} - r_{js} + 1) - LB_j$

Rule 1.2

In the beginning, each cell belongs to one or more than one black run. However, after some iterations, many black runs' ranges will be refined, this may make some cells not belong to any black run, and these cells should be left empty. Rule 1.2 is provided to do this work. Fig. 2.4 shows that cells c_0 and c_4 should be left empty because they do not belong to any black run.

Rule 1.2

For each cell c_i , it will be left empty, if one of the following three conditions is satisfied (1) $0 \le i < r_{1s}$, (2) $r_{ke} < i < n$, (3) $r_{je} < i < r_{(j+1)s}$ for some $j, 1 \le j < k$.



Fig. 2.4 An example of Rule 1.2. (a) One row of a puzzle with a partial painting result. (b) The result of applying Rule 1.2 to (a).

For each black run j, when the first cell $c_{r_{j\mu}}$ of its range is colored, we will check $c_{r_{j\mu}}$ covered by what other black runs. If the lengths of those covering black runs are all one, the cell $c_{r_{j\mu}\cdot 1}$ should be left empty. In the similar way, when the last cell $c_{r_{j\mu}}$ of its range is colored, we will check $c_{r_{j\mu}}$ covered by what other black runs. If the lengths of those covering black runs are all one, the cell $c_{r_{j\mu}+1}$ should be left empty. We provide Rule 1.3 to determine whether cells $c_{r_{j\mu}-1}$ and $c_{r_{j\mu}+1}$ should be left empty. Taking Fig. 2.5 as an example, the colored cell $c_{r_{j\mu}}$ in Fig. 2.5 (a) is the first cell of the range of the last black run with length 3. It is also covered by the third black run with length 1. Thus, it must be the third black run with length 1 (see Fig. 2.5 (b)) or the head cell of the last black run (see Fig. 2.5 (c)). No matter what case, the cell $c_{r_{j\mu}-1}$ should be left empty.

Rule 1.3

For each black run j, j = 1, ..., k

(1) If the lengths of all black run *i* covering $c_{r_{js}}$ with $i \neq j$ are all one, cell $c_{r_{js}-1}$ will be left empty.

(2) If the lengths of all black run *i* covering $c_{r_{je}}$ with $i \neq j$ are all one, cell $c_{r_{ie}+1}$ will be left empty.



Fig. 2.5 An example of Rule 1.3. (a) One row of a puzzle with a partial painting result. (b) The cell $c_{r_{js}}$ belongs to the third black run with length one. (c) The cell $c_{r_{js}}$ is the head cell of the last black run.

There may be some short black segments existing in a row. If any two consecutive black segments with an unknown cell between them are combined into a new black segment with length larger than the maximal length of all black runs containing part of this new segment, the unknown cell should be left empty. Rule 1.4 is provided to deal with this situation. Fig. 2.6 shows an example. From Fig. 2.6 (b), we can see that by coloring c_i , the length of the new black segment is 4. Since the new black segment is covered by two runs with length 1 and 3 and 4 is larger than 3, so we set the unknown cell c_i as empty.

Rule 1.4 For any three consecutive cells c_{i-1}, c_i, and c_{i+1}, i=1,...,n-2 Constraint: cells c_{i-1} and c_{i+1} must be black, and cell c_i must be unknown 1. Let maxL be the maximal length of all the black runs containing the three cells. 2. If we color c_i and find that the length of the black segment containing c_i is larger than maxL, c_i should be left empty.



Fig. 2.6 An example of Rule 1.4. (a) One row of a puzzle with a partial painting result (maxL=3). (b) The new black segment's length after coloring c_i is 4. (c) The cell c_i should be left empty.

Some empty cells like walls may obstruct some black segments expand, we want to color more cells based on this property. For a black segment belonging to series of black runs, which have the same length but the ranges of them overlap each other, if the length of the black segment equals to the length of those black runs covering the black segment, we can set the two cells closest to the black segment as empty. Rule 1.5 is proposed to solve the above problems.

Fig. 2.7 is a detailed description. In Fig. 2.7(a), we do not know c_i belonging to which black run. However, an empty cell c_{i-2} obstructs the black segment containing c_i to expand to the left side of c_{i-2} . Hence, no matter c_i belongs to the run with length 3 or the run with length 4, the cell next to c_i should be colored. On the other hand, Fig. 2.7 (b) is a special case, all black runs containing c_i have the same length. Thus, we are quite sure that the two cells c_{s+1} and e_{e+1} closest to the black segment should be left empty.

Rule 1.5

For any two consecutive cells c_{i-1} and c_i , i = 1, ..., n-1

Constraint: cell c_{i-1} must be empty or unknown, and cell c_i must be black

- 1. Let *minL* be the minimal length of all the black runs containing c_i .
- 2. Find an empty cell c_m closest to c_i , $\forall m = i minL + 1, ..., i 1$ If c_m exists, color cell c_p when $i + 1 \le p \le m + minL$.
- 3. Find an empty cell c_n closest to c_i , $\forall n = i+1, ..., i+minL-1$ If c_n exists, color cell c_p when $n-minL \le p \le i-1$.
- 4. If all black runs containing c_i have the same length.
 - (1) Let s and e be the start and end indices of the black segment containing c_i
 - (2) If e-s+1 = minL, leave cells c_{s-1} and c_{e+1} empty.



Fig. 2.7 An example of Rule 1.5. (a) Top: one row of a puzzle with a partial painting result. Middle: all possible solutions for c_i . Bottom: the result of applying Rule 1.5 to top figure. (b) Top: a special case (all black runs containing c_i have the same length). Bottom: the result of applying Rule 1.5 to top figure.

Part II

Three rules are contained in this part. They are designed to refine the ranges of black runs.

Rule 2.1

Two consecutive black runs can not have the same r_{js} or r_{je} , because it is impossible that they are placed in the same start position or end position. We use Rule 2.1 to update the range of each black run j when it has the same r_{js} with black run j-1 or the same r_{je} with black run j+1.

Rule 2.1

For each black run j, $\begin{cases}
r_{js} \text{ will be refined to } (r_{(j-1)s} + LB_{j-1} + 1), & \text{if } r_{js} \leq r_{(j-1)s} \\
r_{je} \text{ will be refined to } (r_{(j+1)e} - LB_{j+1} - 1), & \text{if } r_{je} \geq r_{(j+1)e}
\end{cases}$

Rule 2.2

There should be one empty cell between two consecutive black runs, so we should update the range of black run j if the cell $C_{r_{js}-1}$ or $C_{r_{je}+1}$ is colored. The cells $C_{r_{is}-1}$ and $C_{r_{ie}+1}$ do not belong to black run *j* because they are not in the range (r_{is}, r_{je}) . It means that the colored cell must belong to the previous or the next black run when it is painted. Therefore, Rule 2.2 is proposed to solve this problem.

Rule 2.2

For each black run j,

 r_{js} will be refined to $(r_{js} + 1)$, if the cell $c_{r_{js}-1}$ is colored r_{je} will be refined to $(r_{je} - 1)$, if the cell $c_{r_{je}+1}$ is colored



Rule 2.3

In the range of a black run, maybe one or more than one black segment exist. Some of black segments have the lengths larger than LB_i , but some not. We try to determine each black segment with length larger than LB_i belongs to the former black runs or the later ones. If a black segment belongs to both of them, we can not do anything. But if no, then we update the range of black run j. We provide Rule 2.3 to do this work. In Fig. 2.8, the original range of the second black run is (4, 11). In the range of the second black run, the length of the first black segment is 3 which is larger than 2, and the black segment belongs to the first black run not the last, so we update the range of the second black run from (4, 11) to (8, 11). But the length of the second black segment is 1 and is less than 2, so we ignore it.

Rule 2.3

For each black run *j*, find out all black segments in (r_{js}, r_{je}) . We denote the class of these black segments by B.

For each black segment *i* in B with start index *i*s and end index *ie*,

If the length (ie - is + 1) of black segment *i* is larger than LB_j ,

 $(r_{js} \text{ will be refined to } (ie+2), \text{ if black segment } i \text{ only belongs to the former black runs}$ $r_{je} \text{ will be refined to } (is-2), \text{ if black segment } i \text{ only belongs to the later black runs}$



Fig. 2.8 An example of Rule 2.3.

Part III

This part is also composed of three rules. The purpose of each rule is not only to determine which cells should be colored or left empty but also to refine the ranges of some black runs.

Rule 3.1

In solving process, we met a problem as shown in Fig. 2.9 (a) – several colored cells belong to the same black run but they are scattered. It means that all cells between them should be colored to form a new black segment. Rule 3.1 is presented to solve this problem and Fig. 2.9 (b) is the result of applying Rule 3.1 to Fig 2.9 (a).



Fig. 2.9 An example of Rule 3.1. (a) One row of a puzzle with a partial painting result. (b) The result of applying Rule 3.1 to (a).

Rule 3.1

For each black run j, find the first colored cell C_m after $r_{(j-1)e}$ and the last colored cell C_n before $r_{(j+1)s}$ 1. Color all cells between C_m and C_n 2. $\begin{cases} r_{js} & \text{will be refined to } (m-u) \\ r_{je} & \text{will be refined to } (n+u) \\ \text{where } u = LB_j - (n - m + 1) \end{cases}$

Rule 3.2

As shown in Fig. 2.10 (a), some scattered empty cells are distributed over the range of black run j, so there will be several segments bounded by these empty cells. The lengths of some segments may be less than LB_j , so they can be ignored to consider. We propose Rule 3.2 to solve this problem. Fig. 2.10 (a) shows that there are six segments in 3's range. The first two and the last segments will be skipped and then the range is adjusted. Since the length of the forth segment is less than 3 and is covered only by one black run with length 3, we can set it as empty. Fig. 2.10 (b) shows the result of applying Rule 3.2 to Fig. 2.10 (a).



Fig. 2.10 An example of Rule 3.2. (a) One row of a puzzle with a partial painting result. (b) The result of applying Rule 3.2 to (a).

Rule 3.2

```
For each black run j, find out all segments bounded by empty cells in (r_{is}, r_{ie}).
We denote the class of these segments by B with size b.
step 1. set i = 0
step 2. If the length of segment i is less than LB_i,
         i = i + 1 and go to step 2.
      Otherwise,
         r_{is} will be refined to the start index of segment i,
         stop and go to step 3.
step 3. set i = b-1
step 4. If the length of segment i is less than LB_i,
         i = i - 1 and go to step 4.
      Otherwise,
         r_{ie} will be refined to the end index of segment i,
         stop and go to step 5.
                                        a sulling
step 5. If there still remain some segments with lengths less than LB_i,
      (we denote the class of these segments by R)
      for each segment in R,
         if the segment does not belong to other black runs,
         all cells in this segment should be left empty.
```

Rule 3.3

This rule is designed for solving the case of the range of black run j not overlapping the range of black run j-1 or j+1. We take the case "not overlapping black run j-1" as an example, another case "not overlapping black run j+1" is treated by the same idea but the conditions are reversed. It will be explained at the end of this section.

1. The cell $c_{r_{is}}$ is black (see Fig. 2.11 (a))

Because the black run j does not overlap the black run j-1, so when the head cell of black run j has been colored, we can finish this black run by Rule 3.3-1. Fig.2.11 (b) is the result of applying Rule 3.3-1 to Fig. 2.11 (a).

Rule 3.3-1

For each black run j with $c_{r_{ir}}$ colored,

and its range not overlapping the range of black run j-1,

- (1) Color cell c_i when $r_{js} + 1 \le i \le r_{js} + LB_j$ -1 and leave cell $c_{r_{is}+LB_j}$ empty
- (2) r_{je} should be refined to $(r_{js} + LB_j 1)$
- (3) If black run j+1 overlaps black run j originally, $r_{(j+1)s}$ should be refined to $(r_{js} + LB_j + 1)$



Fig. 2.11 An example of Rule 3.3-1. (a) One row of a puzzle with a partial painting result. (b) The result of applying Rule 3.3-1 to (a).

2. An empty cell c_w appears after a black cell c_b (see Fig. 2.12 (a))

It should be true that each cell after c_w will not belong to black run j. Thus, we can use Rule 3.3-2 to refine the range of black run j as shown in Fig. 2.12 (b).





Rule 3.3-2

For each black run j with its range not overlapping the range of black run j-1, Constraint: an empty cell c_w appears after a black cell c_b with c_w and c_b in the range of black run j r_{je} will be refined to (w-1)

3. There is more than one black segment in the range (see Fig. 2.13 (a))

In (r_{js}, r_{je}) , we find the first black cell c_s in the first black segment and the first black cell c_e in the second black segment. If the length of the new run after merging the first and second black segments by coloring those cells between these two cells is larger than LB_j , this means that c_e will not belong to the same run as c_s . Otherwise, we proceed to find the first black cell c_e in the third black segment and also check the length of the new run after merging the first and third black segments. The process starts all over again until all black segments in (r_{js}, r_{je}) have been checked or a black segment *i* has been found and the length after merging the first black segment and black segment *i* is larger than LB_j . Thus we provide Rule 3.3-3 to deal with this situation. The length after merging two black runs shown in Fig. 2.13 (a) is 5 (see Fig. 2.13(b)) and is larger than 4, thus we can update the range as shown in Fig. 2.13 (c).



Fig. 2.13 An example of Rule 3.3-3. (a) One row of a puzzle with a partial painting result. (b) The length of coloring those cells between c_s and c_e is 5. (c) The result of applying Rule 3.3-3 to (a).

Rule 3.3-3

For each black run j with its range not overlapping the range of black run j-1, Constraint: there is more than one black segment in the range

Find out all black segments in (r_{js}, r_{je}) . We denote the class of these black segments by B with size b.

step 1. set i=0

step 2. find the first black cell c_s in black segment *i*

step 3. set m = i + 1

step 4. if m < b, find the first black cell c_e in black segment m,

If (e-s+1) is larger than LB_j , stop and r_{je} will be refined to (e-2).

Otherwise, m = m + 1 and go to step 4.

The above three conditions are suitable for the case "not overlapping black run j-1". To treat the case "not overlapping black run j+1", we just need to reverse the above three conditions as follows:

1. The cell $c_{r_{in}}$ is black

(1) Color cell c_i when $r_{je} - LB_j + 1 \le i \le r_{je} - 1$ and leave cell $c_{r_{je}-LB_j}$ empty

(2) r_{is} should be refined to $(r_{ie} - LB_i + 1)$

(3) If black run j-1 overlaps black run j originally,

 $r_{(j-1)e}$ should be refined to $(r_{je} - LB_j - 1)$

2. An empty cell c_w appears before a black cell c_b

(1) r_{is} will be refined to (w+1)

3. There is more than one black segment in the range

the last black cell c_s in the last black segment

the last black cell c_e in the other black segments

(1) If (s-e+1) is larger LB_i , r_{is} will be refined to (e+2)

2.2 The second phase: DFS with branch and bound

After the first phase, a puzzle is not always solved completely. If some cells in the puzzle are still unknown, we will enter the second phase. Depth first search (DFS) is an exhaustive search, thus it will find out the solution of puzzle eventually. For this reason, we use DFS method to solve the unsolved puzzle. Since the general DFS is time-consuming, we will provide a "branch and bound" scheme to improve the processing speed.

One thing should be mentioned at first, we choose the row information to build a search tree and use the column information to do verification as the method used in [3]. It means that every layer of tree is composed of row information and all nodes of each layer are the possible solutions (PS) for the row. The following figures will provide more detailed description. Fig. 2.14 (a) is a given puzzle and Figs. 2.14 (b) and (c) are all possible solutions for row 1 and row 2, respectively. There are three possible solutions for row 1, two possible solutions for row 2, and two possible solutions for row 3, etc. Fig. 2.14 (d) is a rough tree of Fig. 2.14 (a).

At a start, we try the first possible solution of row 1 and use column information to deduce that some cells in row 2 should be colored or left empty. Then we check all possible solutions of row 2 to refine which possible solutions we want. Fig. 2.15 (a) shows the deduced result based on the first possible solution of row 1: in row 2, the cells c_0 and c_1 should be left empty, and then the cells c_2 and c_4 should be colored. It is evident that there is no possible solution in row 2 for this situation. Hence, we reject this possible solution and do not search the following rows. Then we try the next possible solution of row 1 as shown in Fig. 2.15 (b) and the same result is obtained. Thus, we proceed to try the last possible solution of row 1 and then we find the first possible solution of row 2 suitable as shown in Figs. 2.15 (c) and (d). We go on like this and then the answer, Fig. 2.15 (e), is found. The above deduction and rejection process is called branch and bound scheme. Note that the symbol " \triangle " in Fig. 2.15 stands for the cell determined.



Fig. 2.14 An example of DFS. (a) A given puzzle. (b) The possible solutions of row 1.(c) The possible solutions of row 2. (d) A rough tree of (a).

There are 72 $(3 \times 2 \times 2 \times 1 \times 6 = 72)$ leaf nodes in DFS tree for the puzzle in Fig. 2.14 (a) we must check, but we do not need to check all leaf nodes based on the branch and bound scheme. The main reason is that some columns restrictions will bound cells' types in the next row after the current row being built. This will make some branches be cut if a certain possible solution of the next row can not fit the restrictions. In other words, we need not waste time to test those possible solutions of the following rows we have known they are wrong.



Fig. 2.15 The process of DFS with branch and bound. (a) The deduced result of row 2 based on the first possible solution of row 1. (b) The deduced result of row 2 based on the second possible solution of row 1. (c) The deduced result of row 2 based on the third possible solution of row 1. (d) The first possible solution of row 2. (e) The final solution.

Note that the DFS with branch and bound scheme is used after using logical rules, the size of searching tree will be reduced significantly. Fig. 2.16 gives an example to do illustration. There are 21 possible solutions for the first row in Fig. 2.16 (a) originally. After applying the logical rules to Fig. 2.16 (a), we obtain the result shown in Fig. 2.16 (b). From Fig. 2.16 (b), we can find that only 2 possible solutions are left because the first black run has been solved completely by LR. In addition, although the range of the last black run is (5, 8) now, we only need to check c_5 and c_8 not c_5-c_8 . Checking c_6 and c_7 is useless because we have known they are empty cells.



Fig. 2.16 An example before using DFS. (a) The original puzzle. (b) The resulting puzzle executed by LR.



CHAPTER 3 EXPERIMENTAL RESULTS

In our database, there are about 260 puzzles. Most of them come from [4-5, 7] and a little are created by us. There are two links being contained in [7], one is for playing Japanese puzzles online and another is a book of Japanese puzzles, we get the puzzles from here. A PC (CPU: AMD Athlon 2600+ 1.92GHz) and a NB (CPU: Intel Pentium M 2.00GHz) are used to run this program.

Because most Japanese puzzles are meaningful, they can be solved quickly and completely only by LR. The execution time is less than 1 second. If the puzzle is not solved totally, the unknown part left is also solved successfully by DFS with branch and bound scheme. Fig. 3.1 are the test images; Figs. 3.1 (a) – (c) come from [4], Fig. 3.1 (d) comes from [5], and Figs. 3.1 (e) and (f) are created by us. The first two images and the forth one are solved completely and quickly only by logical rules. The three images take more than 20 minutes to get the solutions even an incorrect solution in [4-5], but we only spend about 0.1 second to solve them by using logical rules. However, Fig. 3.1 (c), a random image (50% black), is solved completely using about 36 hours which is three times the execution time of [4]. If the black pattern in a puzzle scatters everywhere, like Figs. 3.1 (c) and (e), this will lead LR to fail and make lengths of most black runs shorter and many of black runs in a row. It means that a black run may be placed in many possible positions and we should check many possible solutions of each row as shown in Fig. 3.2. Thus, DFS will take a longer time to solve the puzzle.

However, we can see Fig. 3.1 (f), the puzzle is also a random one (50% black), it is solved successfully within 22 minutes because it is more compact (i.e. most black cells are connected together). Although most of the lengths of black runs are shorter like Fig. 3.1 (c), they have a "chain relation", that is, some black cells in row 1

connect to some black cells in row 2, some black cells in row 2 connect to some black cells in row 3, and so forth. Fig. 3.3 gives a more detailed illustration. Note that the symbol " \bigcirc " in Fig. 3.3 stands for the connection.



Fig. 3.1 Test images. (a) Sheep (25x25). (b) Airplane (25x25). (c) Random_1 (30x30). (d) Monkey (15x15). (e) Sunflower (25x25). (f) Random_2 (30x30).



Fig. 3.2 An illustration of scattering. (a) 10 possible solutions. (b) 21 possible solutions. (c) 36 possible solutions. (d) 56 possible solutions.



Fig. 3.3 An illustration of chain relation. More "O" means the puzzle is more connected. (a) The magnified picture of part of Fig. 3.1 (c). (b) The magnified picture of part of Fig. 3.1 (f).

Fig. 3.4 from [4] is a puzzle with two solutions. After applying our algorithm, all the solutions will be found out. Fig. 3.5 is a puzzle with no solution. GA can not detect it and will give a wrong answer like Fig. 3.6. However, our method can detect it quickly because there must be a contradiction in logic of a valid puzzle with no solution. Hence, when we determine one cell should be colored or left empty, we will check at first whether the cell has been colored or left empty. If one cell is determined as a colored cell but it has been left empty, we will detect that the puzzle has no solution. Similarly, if one cell is determined as an empty cell but it has been colored, it also means that the puzzle has no solution.



Fig. 3.4 A 7x8 puzzle with many solutions. (a) The result after LR. (b) The first solution. (c) The second solution.





Fig. 3.5 A puzzle with no solution.

Fig. 3.6 GA gives a wrong answer of Fig. 3.5.

Finally, Fig. 3.7 shows some other test images and Table 1 shows the comparison of the experimental results between surveyed paper [5] and our algorithm. From Table 1, there are over 93% puzzles being solved more than 1 minute whether by using GA or DFS. However, after applying our proposed method, there are over 98% puzzles being solved about 0.1 second. All puzzles in our database are solved successfully and there is no doubt about the correctness of solutions.



Fig. 3.7 Test images. (a) Flower_word (10x10). (b) Hippo (20x20). (c) Formosa (25x25). (d) Snoopy (25x25). (e) Owl (30x25). (f) Skating (30x25).

Puzzle Type: Num	ber	Time				
(264 puzzles tota	lly)	GA	DFS	Our Method		
5x5: 1 5x6: 1		wrong answer more than 1 min.	no solution 0.0 sec. 0.062 sec.	no solution detected		
10x10: 2, 30x40: 1	(akaua f	wrong answer more than 1 min.	no solution more than 1 min.			
	(above fi	ive puzzies nave no	solution)			
size≦6x6: 7		0.5 sec. <time <5 sec.</time 	0.0 sec.≦time <0.6 sec.	0.0 sec.≦time <0.1 sec.		
6x6 <size<10x10: 9<="" td=""><td></td><td>about 30 sec.: 1 >1 min.: 8</td><td>0.01 sec.<time <1 min.: 7 >1 min.: 2</time </td><td>about 0.1 sec.</td></size<10x10:>		about 30 sec.: 1 >1 min.: 8	0.01 sec. <time <1 min.: 7 >1 min.: 2</time 	about 0.1 sec.		
	Random_1	more than 2 days	more than 2 days	about 36 hr.		
10x10≦size≦15x15: 33 15x15 <size<25x25: 110<="" td=""><td>Sunflower Random_2</td><td>more than 1 hr.</td><td>more than 1 hr.</td><td>about 20 min.</td></size<25x25:>	Sunflower Random_2	more than 1 hr.	more than 1 hr.	about 20 min.		
size≧25x25: 100	Others	more than 1 min.	more than 1 min.	Owl: 2 sec. Skating: 16 sec. Others: about 0.1 sec.		

Table 1 The comparison of the experimental results between surveyed paper and our algorithm.

CHAPTER 4 CONCLUSIONS

In this thesis, we have proposed a fast method to solve Japanese puzzles. The method contains two phases, the first phase used logical rules to solve cells in a puzzle as many as possible. In the second phase, based on column information, DFS with branch and bound scheme is used to solve those unknown cells remaining after the first phase.

Since DFS is an exhaustive search, it is very time-consuming. When the size of puzzle or the possible solutions of each row becomes larger, the time complexity also rises. Consequently, using LR at first is necessary because some cells can be solved easily by logic. If some cells are solved successfully at first, the size of tree will be reduced. However, not all puzzles can be solved completely by LR if the black pattern in a puzzle is distributed randomly, like Figs, 3.1 (c), (e), and (f). For this situation, we use branch and bound scheme to assist in solving Japanese puzzles. The experimental results show that our method can solve those puzzles with compact black patterns quickly. For those puzzles with random black patterns, the method can also raise the speed of DFS using branch and bound scheme. Furthermore, our method always provides correct solutions.

CHAPTER 5 FUTURE WORKS

Japanese puzzle, a pencil-and-paper game, is very popular in some countries, like Japan and Netherlands. It is as interesting as Sudoku because both of them are logical games. Logical games let people to use their brain when they are playing. Thinking and learning in playing is a good thing. Either adults or children will be attracted by Japanese puzzles deeply.

At present, Sudoku has been developed as online gaming and mobile gaming, we think the Japanese puzzle could also be designed like Sudoku. A complete Japanese puzzle game may consist of three parts: generator, solver, and helper. Using a puzzle generator, the player can create what puzzle he wants by inputting a picture. In this thesis, a simple generator is created for any type pictures but it works better in black-white pictures than colorful ones. Fig. 5.1 is an illustration. The size of puzzle can be decided arbitrarily. As for the solver, it is the main part of this game. As the previous chapters mentioned, the solver is to solve all Japanese puzzles. Finally, the helper can give the player several hints based on the solver when he needs.

Combining what proposed above, we use the times of hints given and the time spent to calculate the score, and then rank all players according to their scores. Consequently, Japanese puzzle will become a game full of challenge and excitation.



Fig. 5.1 Generator. (a) The input image. (b) The puzzle generated. (c) The result of the puzzle.

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