國立交通大學

應用數學系 碩士論文

Numerical Ranges of Companion Matrices and Normal Operators

研究生 : 陳育慈指導老師: 吳培元 教授

中華民國 九十六 年 六 月

友矩陣和規範算子的數值域 Numerical Ranges of Companion Matrices and Normal Operators

研究生:陳育慈

Student: Yu-Tzu Chen

指導教授:吴培元

Advisor: Dr. Pei Yuan Wu

國立交通大學



Submitted to Department of Applied Mathematics

College of Science

National Chiao Tung University

In partial Fulfillment of the Requirements

For the Degree of Master

In

Applied Mathematics June 2007 Hsinchu, Taiwan, Republic of China

中華民國九十六年六月

友矩陣和規範算子 的數值域

研究生:陳育慈 指導老師:吳培元 教授

國立交通大學



在本篇論文中,我們研究兩類算子的數值域。針對友矩陣部分,我們 證明3×3可分解友矩陣的數值域會包含相對應的2×2友矩陣的數值域的 充要調件為3×3可分解友矩陣的行列式值的絕對值會大於1。然而,相對 應的結果在一般的n×n可分友矩陣並不正確。針對規範算子的部份,我 們將數值域以乘積算子的表現函數來表示。

中華民國九十六年六月

Numerical Ranges of Companion Matrices and Normal Operators

Student: Yu-Tzu Chen Advisor

Advisor: Pei Yuan Wu

Department of Applied Mathematics National Chiao Tung University



In this thesis, we study the numerical ranges of two kinds of operators. For companion matrices, we show that the numerical range of a 3-by-3 reducible companion matrix C(p) contains the numerical range of the 2-by-2 companion matrix C((1/3)p') if and only if the absolute value of its determinant is greater than 1. However, the corresponding assertion for *n*-by-*n* reducible companion matrices is false. For a normal operator, we express its numerical range in terms of the function in its multiplication operator representation.

致 謝

我的論文得以完成,要感謝許多人在我碩士班期間給予 我的支持與幫忙,不論是學業上或是生活上。

首先要感謝的是我的指導老師吳培元教授,他是一個嚴 肅,有要求的人,在求學期間,我跟他學習到了非常多有用 的知識,並感謝老師不厭其煩的修正我的論文內容。另外, 要感謝的是博士班學長蔡明誠,經常與我討論論文的內容與 可能需要用到的背景知識。感謝跟我同研究室的劉筱凡,張 雁婷,容忍我寫論文遇到瓶頸的壞脾氣以及幫助我在論文內 文的修辭。感謝陳宜廷同學,常常講笑話調劑我的身心。

最後要感謝我的父母與家人,謝謝他們長久以來的支持,讓我可以無後顧之憂的專心於完成論文。

iii

Contents

Abstract (in Chinese)	i
Abstract (in English)	ii
Acknowledgement	iii
1 Introduction	1
2 Companion Matrices	3
3 Normal Operators	15
References	20

References



1 Introduction

Let A be a bounded linear operator on the complex Hilbert space H. The numerical range of A is the set of complex numbers of the form $\langle Ax, x \rangle$, where x is any unit vector in H and $\langle \cdot, \cdot \rangle$ denotes the inner product in H. We denote it by W(A). Namely,

$$W(A) = \{ \langle Ax, x \rangle : x \in H, \|x\| = 1 \}.$$

If H is an n-dimensional space, then A can be seen as an $n \times n$ complex matrix.

The information about the numerical range of an $n \times n$ complex matrix has been quite well known. The shape of W(A) for a 2×2 matrix A is known to be a (possibly degenerate) elliptic disc. More generally, the numerical range of an $n \times n$ ($n \ge 3$) matrix can be expressed in terms of an algebraic curve associated with the matrix [6]. Consider a 3×3 reducible companion matrix A associated with a monic polynomial p and the companion matrix B associated with the monic polynomial (1/3)p'. In Section 2, we will discuss the relation between W(A) and W(B). We prove that W(A)contains W(B) if and only if $|\det A| \ge 1$. We will also show that the corresponding result does not hold for a 4×4 reducible companion matrix.

If A is a normal operator on the Hilbert space H, it is known that the numerical range of A can be expressed by its spectral measure [2]. If H is separable, then there exists a σ -finite measure space (X, Ω, μ) and a function f in $L^{\infty}(\mu)$ such that A is unitarily equivalent to the multiplication operator M_f . In Section 3, we will show that W(A) can be described by the behavior of f.

We now introduce the notations to be used in the following sections. The boundary of a subset \triangle in the plane is denoted by $\partial \triangle$. The convex hull of a set \triangle , denoted by \triangle^{\wedge} , is the smallest convex set including \triangle . The interior of \triangle is denoted by Int \triangle . The closure of \triangle is denoted by $\overline{\triangle}$. A^* is the adjoint operator of A. Next, we list properties of the numerical range of an operator.

Proposition 1.1. Let A be an operator on H. Then the following hold:

(1) W(A) is bounded. Moreover, if A acts on a finite-dimensional space, then

W(A) is compact.

- (2) W(A + aI) = W(A) + a for any complex number a.
- (3) W(bA) = bW(A) for any complex number b.
- (4) W(A) is a convex subset of \mathbb{C} .

(1), (2) and (3) are easily obtained from the definition. (4) appeared in [4, p. 315].

It follows from the definition of the numerical range that the diagonal entries a_{ii} of a matrix A are all in W(A).

Theorem 1.2. Let A and B be operators (on possibly different spaces).

- (1) If A is unitarily equivalent to B, then W(A) = W(B).
- (2) If B dilates to A, then W(B) is contained in W(A).
- (3) If $A = A_1 \bigoplus A_2$, then W(A) equals the convex hull of $W(A_1) \bigcup W(A_2)$.

Recall that *B* is said to dilate to *A* if *A* is unitarily equivalent to an operator matrix of the form $\begin{bmatrix} B & * \\ * & * \end{bmatrix}$. Both (1) and (2) can be derived directly from the definition. The proof of (3) can be found in [4, p. 116].

In what follows, we explore the relations between the numerical range and the spectrum of an operator. The spectrum of an operator A, denoted by $\sigma(A)$, is the set of scalars z for which A - zI is not invertible. The point spectrum $\sigma_p(A)$ of A is the set of eigenvalues of A.

Theorem 1.3. For an arbitrary operator A, we have

- (1) $\sigma_p(A) \subseteq W(A)$, and
- (2) $\sigma(A) \subseteq \overline{W(A)}$.

(1) can be proved from the definition, and (2) is justified in [4, Problem 214].

2 Companion Matrices

Recall that for every complex monic polynomial $p(z) = z^n + a_1 z^{n-1} + ... + a_n$ of degree *n*, there is associated an $n \times n$ matrix

(2.1)
$$C(p) = \begin{pmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & & \ddots & \ddots & \\ & & & 0 & 1 \\ -a_n & -a_{n-1} & \dots & -a_2 & -a_1 \end{pmatrix}$$

called the companion matrix of p. Note that the characteristic polynomial and minimal polynomial of C(p) are both equal to p. We say that a matrix is reducible if it is unitarily equivalent to the direct sum of two other matrices. The numerical ranges of 2-by-2 and 3-by-3 matrices have been known before. Here we give a brief sketch.

Proposition 2.1. Let A be a 2×2 matrix unitarily equivalent to $\begin{vmatrix} a & b \\ 0 & c \end{vmatrix}$.

(1) If b = 0, then W(A) is the line segment with endpoints a and c.

(2) If $b \neq 0$ and a = c, then W(A) is the circular disc centered at a with radius |b|/2.

(3) If $b \neq 0$ and $a \neq c$, then W(A) is the elliptic disc with foci a and c and with the length of minor axis |b|.

The proof of this proposition is provided in [5, pp. 20–23].

To describe the numerical ranges of 3×3 matrices, we need some extra notions. A point in homogeneous coordinates is an ordered triple

of complex numbers x, y and z which are not all zero. Two such points (x_1, y_1, z_1) and (x_2, y_2, z_2) are equivalent if and only if $x_2 = ax_1$, $y_2 = ay_1$, $z_2 = az_1$ for some $a \neq 0$. Then the complex projective plane is the set of all the equivalence classes [x, y, z]. That is,

$$\mathbb{CP}^2 = \{ [x, y, z] : (x, y, z) \in \mathbb{C}^3 - \{0\} \}.$$

The point [x, y, z] in \mathbb{CP}^2 with $z \neq 0$ can be mapped to the point (x/z, y/z) in nonhomogeneous coordinates. On the other hand, the point (x, y) in nonhomogeneous coordinates becomes [x, y, 1] in \mathbb{CP}^2 . The points [x, y, 0] in \mathbb{CP}^2 are points at infinity. If C is an algebraic curve in \mathbb{CP}^2 given by p(x, y, z) = 0, where p is a homogeneous polynomial in x, y and z, then its dual curve C^* is given by

$$\{[u, v, w] \in \mathbb{CP}^2 : ux + vy + wz = 0 \text{ is a tangent line of } C\}$$

For an $n \times n$ matrix A, Re $A = (A + A^*)/2$ and Im $A = (A - A^*)/(2i)$ denote the real and imaginary parts of A, respectively. Define the degree-n homogeneous polynomial p_A in x, y and z by

(2.2)
$$p_A(x, y, z) = \det(x \operatorname{Re} A + y \operatorname{Im} A + z I_n).$$

Kippenhahn [6] proved that the numerical range of an $n \times n$ matrix A can be described in terms of p_A as follows.

Theorem 2.2. The numerical range of A equals the convex hull of the real points of the dual curve of $p_A(x, y, z) = 0$.

Next we state the classification for the numerical ranges of 3×3 matrices, which is also given by Kippenhahn [6].

Proposition 2.3. If A is a 3×3 matrix and p_A is defined as in (2,2), then W(A) can be classified into four classes:

(1) If p_A is the product of three linear factors:

$$p_A(x, y, z) = \prod_{j=1}^3 (z + a_j x + b_j y),$$

then A is normal and W(A) is the closed triangular region with vertices $(a_j, b_j), j = 1, 2, 3$ (it may degenerate to a line segment or a point).

(2) If p_A is the product of a linear and an irreducible quadratic factor:

$$p_A(x, y, z) = (z + ax + by)q(x, y, z)$$

then W(A) is the convex hull of the point (a, b) and the ellipse given by the dual curve of q(x, y, z) = 0. Hence W(A) is an elliptic disc possibly with a cone added to it; in the latter case, A is reducible.

(3) If p_A is irreducible and the dual curve of $p_A = 0$ has degree four, then W(A) has a line segment on the boundary.

(4) If p_A is irreducible and the dual curve of $p_A = 0$ has degree six, then W(A) is an oval set.

We now start to consider our problem on the numerical ranges of companion matrices. The next two results are from [3].

Proposition 2.4. If A is a companion matrix, then λA is unitarily equivalent to a companion matrix for any λ , $|\lambda| = 1$.

This proposition says that if A is of the form

then λA is unitarily equivalent to the companion matrix

$$\begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ \lambda^{n}a_{n} & \lambda^{n-1}a_{n-1} & \dots & \lambda a_{1} \end{bmatrix}$$

The detailed proof can be found in [3, Lemma 2.8].

Theorem 2.5. An $n \times n$ $(n \ge 2)$ companion matrix A is reducible if and only if its eigenvalues are of the form:

$$a\omega_n^{j_1},\ldots,a\omega_n^{j_p},(\frac{1}{\bar{a}})\omega_n^{j_{p+1}},\ldots,(\frac{1}{\bar{a}})\omega_n^{j_n},$$

where $a \neq 0$, $\omega_n = \exp(2\pi i/n)$ denotes the nth primitive root of 1, $1 \leq p < n$, and $\{j_1, \ldots, j_p\}$ and $\{j_{p+1}, \ldots, j_n\}$ form a partition of $\{0, 1, \ldots, n-1\}$. In this case, A is unitarily equivalent to $A_1 \bigoplus A_2$ with $\sigma(A_1) = \{a\omega_n^{j_1}, \ldots, a\omega_n^{j_p}\}$ and $\sigma(A_2) =$ $\{(1/\bar{a})\omega_n^{j_{p+1}}, \ldots, (1/\bar{a})\omega_n^{j_n}\}.$

This theorem is verified in [3, Theorem 1.1].

The next theorem is our main result in this section. It partially solves a question posed by J. Zemánek.

Theorem 2.6. Let A be a 3×3 reducible companion matrix and p be its associated polynomial. For the monic polynomial (1/3)p', there is associated a 2×2 companion matrix B. Then their numerical ranges W(A) and W(B) have the following containment relations:

- (1) $W(A) \cap W(B) \neq \emptyset$.
- (2) If $|\det A| < 1$, then $W(B) \nsubseteq W(A)$.

(3) If $|\det A| \ge 1$, then $W(B) \subseteq W(A)$. Moreover, $\partial W(A) \bigcap \partial W(B) = \emptyset$ if $|\det A| > 1$, and $\partial W(A)$ intersects $\partial W(B)$ at exactly three points if $|\det A| = 1$.

Proof. Since A and B are companion matrices, 0 is in both W(A) and W(B). This proves (1).

For (2) and (3), we may assume by Theorem 2.5 that the eigenvalues of A are

$$a, \frac{1}{\overline{a}}\omega, \frac{1}{\overline{a}}\omega^2,$$

where $\omega = \exp(2\pi i/3)$ is the 3rd primitive root of 1. Let $e^{-i\theta}$ be such that $ae^{-i\theta} =$ t > 0. Since the characteristic polynomial of A is

$$p(z) = (z - a)(z - \frac{1}{\overline{a}}\omega)(z - \frac{1}{\overline{a}}\omega^2)$$

= $z^3 - (a - \frac{1}{\overline{a}})z^2 - (\frac{a}{\overline{a}} - \frac{1}{\overline{a}^2})z - \frac{a}{\overline{a}^2}$
= $z^3 - (t - \frac{1}{t})e^{i\theta}z^2 - (1 - \frac{1}{t^2})e^{2i\theta}z - \frac{1}{t}e^{3i\theta},$

the 3×3 reducible companion matrix A is of the form

$$\left[\begin{array}{cccc} 0 & 1 & 0 \\ 0 & 0 & 1 \\ \frac{1}{t}e^{3i\theta} & (1-\frac{1}{t^2})e^{2i\theta} & (t-\frac{1}{t})e^{i\theta} \end{array} \right].$$

A direct computation shows that

$$\frac{1}{3}p'(z) = z^2 - \frac{2}{3}(t - \frac{1}{t})e^{i\theta}z - \frac{1}{3}(1 - \frac{1}{t^2})e^{2i\theta},$$
 form

and thus B is of the form

$$\left[\begin{array}{cc} 0 & 1 \\ \frac{1}{3}(1-\frac{1}{t^2})e^{2i\theta} & \frac{2}{3}(t-\frac{1}{t})e^{i\theta} \end{array} \right].$$

It follows from Proposition 2.4 that $e^{-i\theta}A$ is unitarily equivalent to

. 3

$$\left[\begin{array}{ccc} 0 & 1 & 0 \\ 0 & 0 & 1 \\ \frac{1}{t} & 1 - \frac{1}{t^2} & t - \frac{1}{t} \end{array} \right].$$

Similarly, $e^{-i\theta}B$ is unitarily equivalent to

$$\begin{bmatrix} 0 & 1 \\ \frac{1}{3}(1-\frac{1}{t^2}) & \frac{2}{3}(t-\frac{1}{t}) \end{bmatrix}.$$

Hence we can assume that a > 0. Under this assumption, det A = 1/a > 0. Obviously,

$$det A > 1 \Leftrightarrow a < 1,$$

$$det A = 1 \Leftrightarrow a = 1,$$

$$det A < 1 \Leftrightarrow a > 1.$$

Using Theorem 2.5, we derive that the reducible companion matrix A is unitarily equivalent to

$$A_1 \bigoplus A_2 = \left[\begin{array}{c} a \end{array} \right] \bigoplus \left[\begin{array}{c} \frac{1}{a} \omega & b \\ 0 & \frac{1}{a} \omega^2 \end{array} \right]$$

where the entry b satisfies

$$a^{2} + \left|\frac{1}{a}\omega\right|^{2} + \left|b\right|^{2} + \left|\frac{1}{a}\omega^{2}\right|^{2} = 1 + 1 + \left(\frac{1}{a}\right)^{2} + \left(1 - \frac{1}{a^{2}}\right)^{2} + \left(a - \frac{1}{a}\right)^{2},$$

and can be taken to be nonnegative. A simple computation yields

$$b = |1 - \frac{1}{a^2}|.$$

Clearly, if a = 1, then b = 0. In this case, A is normal and W(A) is the regular triangular region with vertices $1, \omega$ and ω^2 . When $a \neq 1$, the numerical range of A_1 is the singleton $\{a\}$, and the numerical range of A_2 is the elliptic disc with foci ω/a and ω^2/a and with the length of minor axis $|1 - 1/a^2|$ by Proposition 2.1. Therefore the boundary of $W(A_2)$ is given by the equation

$$\frac{(x+\frac{1}{2a})^2}{\frac{1}{4}(1-\frac{1}{a^2})^2} + \frac{\frac{1}{1296}y^2}{\frac{1}{4}(\frac{a^4+a^2+1}{a^4})} = 1,$$

which we call Γ_A . Note that the center of Γ_A , labeled c_A , is at -1/(2a). It is easy to see that when a = 1, $B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ and W(B) is the circular disc centered at 0 with radius 1/2. In this case, W(A) contains W(B) and their boundaries intersect at exactly three points. If $a \neq 1$, by a brief computation, B is unitarily equivalent to

$$\begin{bmatrix} \frac{a^2 - 1 + \sqrt{a^4 + a^2 - 2}}{3a} & c\\ 0 & \frac{a^2 - 1 - \sqrt{a^4 + a^2 - 2}}{3a} \end{bmatrix}$$

,

where the nonnegative c satisfies

$$\left|\frac{a^{2}-1+\sqrt{a^{4}+a^{2}-2}}{3a}\right|^{2}+\left|\frac{a^{2}-1-\sqrt{a^{4}+a^{2}-2}}{3a}\right|^{2}+c^{2}=1+\left(\frac{1}{3}\left(1-\frac{1}{a^{2}}\right)\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{1}{a}\right)^{2}+\left(\frac{2}{3}\left(a-\frac{$$

Hence the preceding equation yields

$$c = \frac{2a^2 + 1}{3a^2}$$
 if $a > 1$,

and

$$c = \sqrt{\frac{4}{9}a^2 + \frac{8}{9} - \frac{4}{9a^2} + \frac{1}{9a^4}}$$
 if $a < 1$.

Again, Proposition 2.1 says that the numerical range of B is an elliptic disc and the boundary of W(B) is given by the equation

$$\frac{(x - \frac{a^2 - 1}{3a})^2}{(\frac{2}{9} - \frac{1}{9a^2} + \frac{1}{36a^4} + \frac{a^2}{9})} + \frac{y^2}{(\frac{2a^2 + 1}{6a^2})^2} = 1,$$

which we call Γ_B . Note that the center of Γ_B , labeled c_B , is at $(a^2-1)/(3a)$. Obviously, the points a, c_A and c_B are on the x-axis and satisfy $a > c_B > c_A$. As the point a may be in or out of $(\Gamma_A)^{\wedge}$, we have two different cases to consider. These are illustrated in the following figures.



Figure 1: a is in $(\Gamma_A)^{\wedge}$.



Figure 2: a is not in $(\Gamma_A)^{\wedge}$.

If a is in $(\Gamma_A)^{\wedge}$, then we need only check that Γ_B is in the interior of $(\Gamma_A)^{\wedge}$. This can be observed from Figure 1 visually. If a is not in $(\Gamma_A)^{\wedge}$, then let m_A (resp., m_B) denote the slope of the tangent line from point a to Γ_A (resp., Γ_B). Since $W(B) \subseteq W(A)$ if and only if $m_A^2 \ge m_B^2$, to complete the proof, we need compare the magnitudes of m_A^2 and m_B^2 . This can be observed from Figure 2. For convenience, let b_1 and b_2 denote one half of the lengths of the minor axis of Γ_A and Γ_B , respectively.

Our discussion is now divided into two cases:

(a) If a is in $(\Gamma_A)^{\wedge}$, then $d(a, c_A) \leq b_1$, that is,

$$a - \frac{-1}{2a}| \le \frac{1}{2}|1 - \frac{1}{a^2}|.$$

By computation, this holds if and only if $a \leq 1/2$. We claim that in this case

(2.3)
$$b_1 > d(c_A, c_B) + b_2,$$

that means

(2.4)
$$\frac{1}{2}(\frac{1}{a^2}-1) > \frac{a}{3} + \frac{1}{6a} + \sqrt{\frac{2}{9} - \frac{1}{9a^2} + \frac{1}{36a^4} + \frac{a^2}{9}},$$

and the point at the major axis of Γ_B

(2.5)
$$(\frac{a^2-1}{3a}, \frac{2a^2+1}{6a^2})$$
 is in $(\Gamma_A)^{\wedge}$,

that means

(2.6)
$$\frac{\left(\frac{a^2-1}{3a}+\frac{1}{2a}\right)^2}{\frac{1}{4}\left(1-\frac{1}{a^2}\right)^2}+\frac{\left(\frac{2a^2+1}{6a^2}\right)^2}{\frac{1}{4}\left(\frac{a^4+a^2+1}{a^4}\right)} \leqslant 1.$$

For $a \leq 1/2$, (2,4) and (2.6) are easily seen to be true. From (2.3) and (2.5), it implies that Γ_B is contained in the interior of $(\Gamma_A)^{\wedge}$, and hence $W(B) \subseteq W(A)$.

(b) Assume that a is not in $(\Gamma_A)^{\wedge}$. The tangent lines from a to $\partial \Gamma_A$ are given by

$$y - 0 = m_A(x - (-\frac{1}{2a})) \pm \sqrt{m_A^2(\frac{1}{4}(1 - \frac{1}{a^2})^2) + (\frac{a^4 + a^2 + 1}{4a^4})}$$

Since they pass through the point (a, 0), a calculation shows that

$$m_A{}^2 = \frac{a^4 + a^2 + 1}{4a^6 + 3a^4 + 3a^2 - 1}.$$

Applying this formula to B, one can get

$$m_B{}^2 = \frac{4a^4 + 4a^2 + 1}{12a^6 + 8a^4 + 8a^2 - 1}.$$

$$\frac{m_A{}^2}{m_B{}^2} = \frac{(a^4 + a^2 + 1)(12a^6 + 8a^4 + 8a^2 - 1)}{(4a^4 + 4a^2 + 1)(4a^6 + 3a^4 + 3a^2 - 1)}$$

Noting that

Thereby it leads to

$$(a^4 + a^2 + 1)(12a^6 + 8a^4 + 8a^2 - 1) - (4a^4 + 4a^2 + 1)(4a^6 + 3a^4 + 3a^2 - 1)$$

= 4a²(-a⁶ + 1)(a² + 2)

is positive when 0 < a < 1 and negative when a > 1, we have $m_A^2 < m_B^2$ when a > 1and $m_A^2 > m_B^2$ when a < 1. Notice that $m_A^2 > m_B^2$ means that the boundary of W(A) intersects W(B) at no point.

As a conclusion, we have $W(B) \subseteq W(A)$ when a < 1 and $W(B) \nsubseteq W(A)$ when a > 1. Our proof is completed.

For $n \times n$ $(n \ge 4)$ reducible companion matrices, assertion (2) in Theorem 2.6 is in general false.

Example 2.7. Let p(z) = (z-20)(z+1/20)(z-i/20)(z+i/20) be a monic polynomial. Then

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1/400 & 399/8000 & 399/400 & 399/20 \end{bmatrix}$$

is the associated 4×4 reducible companion matrix. The 3×3 companion matrix *B* associated with the monic polynomial (1/4)p' is

$$B = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 399/32000 & 399/800 & 1197/80 \end{bmatrix}$$

Although det A = 1/400 < 1, the numerical range of B is contained in the numerical range of A. We prove this via Theorem 2.2. First, we calculate the homogeneous polynomial p_A as follows.

$$p_A(x, y, z)$$

$$= \det \begin{pmatrix} x \begin{bmatrix} 0 & 1/2 & 0 & 1/800 \\ 1/2 & 0 & 1/2 & 399/16000 \\ 0 & 1/2 & 0 & 799/800 \\ 1/800 & 399/16000 & 799/800 & 399/20 \end{bmatrix}$$

$$+y \begin{bmatrix} 0 & -i/2 & 0 & i/800 \\ i/2 & 0 & -i/2 & 399i/16000 \\ 0 & i/2 & 0 & -i/800 \\ -i/800 & -399i/16000 & i/800 & 0 \end{bmatrix} + z \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{pmatrix}$$

$$= \det \begin{bmatrix} z & (x-iy)/2 & 0 & (x+iy)/800 \\ (x+iy)/2 & z & (x-iy)/2 & 399(x+iy)/16000 \\ 0 & (x+iy)/2 & z & (799x-iy)/800 \\ (x-iy)/800 & 399(x-iy)/16000 & (799x+iy)/800 & z+399x/20 \end{bmatrix}$$

$$= z^{4} + \frac{399}{20}xz^{3} - (\frac{383520001}{256 \times 10^{6}}x^{2} + \frac{128160001}{256 \times 10^{6}}y^{2})z^{2} \\ - (\frac{159201}{16 \times 10^{3}}x^{3} + \frac{159999}{16 \times 10^{3}}xy^{2})z + \frac{159201}{64 \times 10^{4}}x^{4} + \frac{160801}{64 \times 10^{4}}x^{2}y^{2} \\ = (z+20x)(z^{3} - \frac{1}{20}z^{2}x - \frac{128160001}{256 \times 10^{6}}z^{2}y - \frac{127520001}{256 \times 10^{6}}zx^{2} + \frac{160801}{128 \times 10^{5}}y^{2}x + \frac{159201}{128 \times 10^{5}}x^{3}).$$

Similarly, $p_B(x, y, z) =$

$$z^{3} + \frac{1197}{80}xz^{2} - (\frac{1281440801}{4096 \times 10^{6}}y^{2} + \frac{3324320801}{4096 \times 10^{6}}x^{2})z - \frac{383838399}{1024 \times 10^{5}}y^{2}x - \frac{382561599}{1024 \times 10^{5}}x^{3}z^{2} + \frac{3324320801}{1024 \times 10^{5}}x^{2}z^{2} + \frac{3324320801}{1024 \times 10^{5}}x^{2} + \frac{3324320801}{1024 \times$$

Hence W(A) is the convex hull of the point (20, 0) plus the dual curve of the polynomial

$$z^{3} - \frac{1}{20}z^{2}x - \frac{128160001}{256 \times 10^{6}}z^{2}y - \frac{127520001}{256 \times 10^{6}}zx^{2} + \frac{160801}{128 \times 10^{5}}y^{2}x + \frac{159201}{128 \times 10^{5}}x^{3}.$$

W(B) is the convex hull of the dual curve of the polynomial

$$z^{3} + \frac{1197}{80}xz^{2} - (\frac{1281440801}{4096 \times 10^{6}}y^{2} + \frac{3324320801}{4096 \times 10^{6}}x^{2})z - \frac{383838399}{1024 \times 10^{5}}y^{2}x - \frac{382561599}{1024 \times 10^{5}}x^{3}.$$
 Their figures are sketched as follows.



We believe that Theorem 2.6(3) should be true for $n \times n$ reducible companion matrices A, but its proof is too complicated to be written down explicitly here.

3 Normal Operators

Let A be a bounded linear operator on the complex Hilbert space H. The numerical range of an operator A is closely related to its spectrum. In fact, we have $\overline{W(A)} \supseteq \sigma(A)^{\wedge}$. Recall that A is normal if $AA^* = A^*A$. For such an A, $\overline{W(A)}$ and $\sigma(A)^{\wedge}$ are even equal.

Theorem 3.1. If A is a normal operator, then $\overline{W(A)} = \sigma(A)^{\wedge}$.

Its proof can be found in [4, pp. 115–116].

Instead of its closure, the numerical range of a normal A can be expressed more precisely in terms of its spectral measure. We introduce the spectral measure and its properties first. Let X be a set, Ω be a σ -algebra of subsets of X, and H be a Hilbert space. B(H) denotes the algebra of bounded operators on H.

 $E:\Omega \to B(H)$

Definition 3.2. A spectral measure for (X, Ω, H) is a function

such that

- (1) $E(\Delta)$ is an (orthogonal) projection for $\Delta \in \Omega$;
- (2) $E(\emptyset) = 0$ and E(X) = I;
- (3) $E(\triangle_1 \cap \triangle_2) = E(\triangle_1)E(\triangle_2)$ for all \triangle_1 and \triangle_2 in Ω ;
- (4) if $\{\Delta_n\}$ is a sequence of disjoint sets in Ω , then

$$E\left(\bigcup_{n} \triangle_{n}\right) = \sum_{n} E(\triangle_{n}),$$

where $\sum_{n} E(\Delta_n)$ denotes the convergence in strong operator topology.

Theorem 3.3. If A is normal on H, then there exists a unique spectral measure

$$E_A: \{Borel \ subsets \ of \ \mathbb{C}\} \to B(H)$$

such that

(1) $E_A(\sigma(A)) = I;$ (2) $A = \int_{\sigma(A)} z dE_A(z).$

This theorem is verified in [1, pp. 263–264]. This unique measure E_A is called the spectral measure for A.

Next we describe W(A) in terms of its spectral measure.

Theorem 3.4. If A is normal, then the numerical range of A equals the interior of $\sigma(A)^{\wedge}$ plus the points z on the boundary $\partial\sigma(A)^{\wedge}$ for which the longest interval $[z_1, z_2]$ in $\partial\sigma(A)^{\wedge}$ containing z is such that both $E_A([z_1, z])$ and $E_A([z, z_2])$ are nonzero. Namely, $W(A) = (Int \ \sigma(A)^{\wedge}) \bigcup \{z \in \partial(\sigma(A)^{\wedge}) : [z_1, z_2] \text{ is the longest interval in } \partial(\sigma(A)^{\wedge}) \text{ containing } z \text{ such that } E_A([z_1, z]) \neq 0 \text{ and } E_A([z, z_2]) \neq 0\}.$

Corollary 3.5. If A is normal, then the numerical range of A equals the intersection of all convex Borel subsets \triangle of \mathbb{C} with $E_A(\triangle) = I$. Namely,

$$W(A) = \bigcap \{ \Delta \subseteq \mathbb{C} : \Delta \text{ Borel convex}, \ E_A(\Delta) = I \}.$$

Both this theorem and its corollary appeared in [2].

There is another representation for normal operators on a separable Hilbert space. In the following, we will express the numerical range of such a normal operator in terms of the ingredients in its representation. Let Ω be a σ -algebra of subsets of Xand μ be a positive measure on Ω . For any f in $L^{\infty}(\mu)$, M_f denotes the multiplication operator $M_f g = fg$ for g in $L^2(\mu)$.

Theorem 3.6. If A is normal on a separable Hilbert space, then there exists a σ -finite measure space (X, Ω, μ) and a function f in $L^{\infty}(\mu)$ such that A is unitarily equivalent to M_f on $L^2(\mu)$. In this situation, $\sigma(A) = \sigma(M_f) = essential$ range of f.

Recall that the essential range of f is defined as

ess. ran.
$$(f) = \bigcap \{ \overline{f(\Delta)} : \Delta \in \Omega \text{ and } \mu(X \setminus \Delta) = 0 \}.$$

The proof of this theorem is provided in [1, p. 265, and pp. 272–273].

The next two results are the expressions of the numerical range of a normal A in terms of the function f in the above representation.

Theorem 3.7. If A is normal on a separable Hilbert space and f is the function as in Theorem 3.6, then the numerical range of A equals the interior of $\sigma(A)^{\wedge}$ plus the points z on the boundary $\partial(\sigma(A)^{\wedge})$ for which the longest interval $[z_1, z_2]$ in $\partial\sigma(A)^{\wedge}$ containing z is such that both $\mu(f^{-1}([z_1, z]))$ and $\mu(f^{-1}([z, z_2]))$ are positive. Namely, $W(A) = (Int \ \sigma(A)^{\wedge}) \bigcup \{z \in \partial(\sigma(A)^{\wedge}) : [z_1, z_2] \text{ is the longest interval in } \partial\sigma(A)^{\wedge}$ containing z such that $\mu(f^{-1}([z_1, z])) > 0$ and $\mu(f^{-1}([z, z_2])) > 0\}$.

The following lemma is useful in proving the theorem.

Lemma 3.8. Let \triangle be a convex subset of \mathbb{C} and ν be a probability measure on \triangle . Then we have



11111

The lemma is trivially the consequence of the theorem in [7].

Proof of Theorem 3.7. According to Theorem 3.6, we may assume that $A = M_f$ on $L^2(\mu)$. If z is a point in the interior of W(A), then, by Theorem 3.1, z is in the interior of $\sigma(A)^{\wedge}$.

Let z be a point on $\partial \sigma(A)^{\wedge}$ for which the longest interval $[z_1, z_2]$ containing z is such that $\mu(f^{-1}([z_1, z])) = 0$. Assume that z is in W(A), that is, $z = \langle Ag, g \rangle$ for some unit vector g in $L^2(\mu)$. We have

$$\begin{split} z &= \langle M_f g, g \rangle \\ &= \int_X f |g|^2 d\mu \\ &= \int_{X \setminus f^{-1}([z_1, z])} f |g|^2 d\mu \\ &= \int_{f^{-1}(\sigma(A)^{\wedge} \setminus [z_1, z])} f |g|^2 d\mu. \end{split}$$

Define the measure ν by

$$u(\triangle) = \int_{\triangle} |g|^2 d\mu \quad \text{for } \triangle \text{ in } \Omega.$$

Then ν is a probability measure and

$$z = \int_{\sigma(A)^{\wedge} \setminus [z_1, z]} w d\nu$$

by the Randon-Nikodym theorem. Since $\sigma(A)^{\wedge} \setminus [z_1, z]$ is convex, Lemma 3.8 implies that z is in $\sigma(A)^{\wedge} \setminus [z_1, z]$, a contradiction. Therefore, $\mu(f^{-1}([z_1, z])) > 0$. Similarly, $\mu(f^{-1}([z, z_2])) > 0$. This proves one direction of the containment.

For the converse, if z is in the interior of $\sigma(A)^{\wedge}$, then trivially z is in W(A). Let z be in $\partial \sigma(A)^{\wedge}$ satisfying the asserted condition. Let g be a unit vector in $L^{2}(\mu)$ with g = 0 on $X \setminus f^{-1}([z_{1}, z])$. Then

$$\langle Ag, g \rangle$$

$$= \int_X f|g|^2 d\mu$$

$$= \int_{f^{-1}([z_1, z])} f|g|^2 d\mu,$$

which belongs to $[z_1, z]$ by Lemma 3.8. This shows that $[z_1, z] \cap W(A)$ is nonempty. In the same way, we also have $[z, z_2] \cap W(A)$ is nonempty. Thus z is in W(A) by the convexity of W(A). **Corollary 3.9.** If A is normal on a separable Hilbert space and f is the function as in Theorem 3.6, then the numerical range of A equals the intersection of all convex Borel subsets \triangle of \mathbb{C} with $\mu(X \setminus f^{-1}(\triangle)) = 0$. Namely,

$$W(A) = \bigcap \{ \Delta \subseteq \mathbb{C} : \Delta \text{ Borel convex}, \ \mu(X \setminus f^{-1}(\Delta)) = 0 \}.$$

Proof. Let \triangle be a convex Borel subset of \mathbb{C} with $\mu(X \setminus f^{-1}(\triangle)) = 0$. For any unit vector g in $L^2(\mu)$, we have

$$egin{aligned} z &= \langle Ag,g
angle \ &= \int_X f|g|^2 d\mu \ &= \int_{f^{-1}(\Delta)} f|g|^2 d\mu, \end{aligned}$$

which is in \triangle by Lemma 3.8. Therefore we conclude that $W(A) \subseteq \triangle$. This implies that

$$W(A) \subseteq \bigcap \{ \Delta \subseteq \mathbb{C} : \Delta \text{ Borel convex}, \ \mu(X \setminus f^{-1}(\Delta)) = 0 \}.$$

Conversely, let $B \equiv \bigcap \{ \Delta \subseteq \mathbb{C} : \Delta \text{ Borel convex}, \ \mu(X \setminus f^{-1}(\Delta)) = 0 \}$. We claim that B is contained in $(\text{Int } \sigma(A)^{\wedge}) \bigcup \{z \in \partial(\sigma(A)^{\wedge}) : [z_1, z_2] \text{ is the longest interval in } \partial\sigma(A)^{\wedge} \text{ containing } z \text{ such that } \mu(f^{-1}([z_1, z])) > 0 \text{ and } \mu(f^{-1}([z, z_2])) > 0 \}$. If z is in the interior of B, then z is in the interior of $\sigma(A)^{\wedge}$. For the other case, z is in Band also on the boundary ∂B of B. Let $[z_1, z_2]$ be the longest interval in $\partial(\sigma(A)^{\wedge})$ containing z. If $\mu(f^{-1}([z_1, z])) = 0$, then $\Delta \equiv \sigma(A)^{\wedge} \setminus [z_1, z]$ is Borel convex and

$$\mu(X \setminus f^{-1}(\triangle)) = \mu(X \setminus (f^{-1}(\sigma(A)^{\wedge}) \setminus f^{-1}([z_1, z]))) = 0.$$

Then $B \subseteq \Delta$ and hence z is in Δ , a contradiction. Therefore, we must have $\mu(f^{-1}([z_1, z])) > 0$. Similarly, $\mu(f^{-1}([z, z_2])) > 0$. We conclude from Theorem 3.7 that z is in W(A), completing the proof.

References

- J. B. Conway, A Course in Functional Analysis, 2nd ed., Springer, New York, 1990.
- [2] E. Durszt, On the numerical range of normal operators, Acta Sci. Math. (Szeged)
 25 (1964), 262–265.
- [3] H.-L. Gau, P. Y. Wu, Companion matrices: reducibility, numerical ranges and similarity to contractions, *Linear Algebra Appl.* 383 (2004), 127–142.
- [4] P. R. Halmos, A Hilbert Space Problem Book, 2nd ed., Spinger, New York, 1982.
- [5] R. A. Horn, C. R. Johnson, *Topics in Matrix Analysis*, Cambridge University Press, Cambridge, 1991.
- [6] R. Kippenhahn, Über den Wertevorrat einer Matrix, Math. Nachr. 6 (1951), 193–228.
- [7] H. Rubin, O. Wesler, A Note on convexity in Euclidean n-space, Proc. Amer. Math. Soc. 9 (1958), 522–523.

4000