# 國 立 交 通 大 學 統計學研究所

## 碩 士 論 文

Copula 模式之下 雙變元存活資料之統計推論

Statistical Inference for Bivariate Survival Data Based on Copula Models

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# Statistical Inference for Bivariate Survival Data Based on

## Copula Models



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## Copula 模式之下 雙變元存活資料之統計推論 學生: 花文妤 指導教授: 王維菁 博士

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本論文主要是考慮在 Copula 模式之下,雙變元存活資料受限於右設限之半 母數推論.目前存在許多估計相關性參數之半母數推論方法.我們比較三 種推論方法針對不存在解釋變數之同質性資料.並利用迴歸的概念將現有 的方法延伸至處理邊際異質的資料.最後,藉由模擬結果檢視上述方法之 有限樣本的表現.

關鍵字 : 雙變元存活資料 ;Cox 比例風險模式;相關存活時間;Clayton 模 式;Copula 模式;半母數推論;二階段估計式;2×2 表格

## Statistical Inference for Bivariate Survival Data

## Based on Copula Models

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### **Abstract**

**CALLING** 

 The thesis considers semi-parametric inference based on Copula models for bivariate survival data subject to right censoring. There exist several semi-parametric inference approaches to estimating the association parameter. We examine and compare three approaches developed for homogeneous data in absence of covariates. Then we extend these methods to a regression setting that accounts for marginal heterogeneity explained by the covariates. Finite-sample performances are examined by simulations.

**Key words:** Bivariate survival data; Cox proportional hazard model; Correlated failure times; Clayton model; Copula model; Semi-parametric inference; Two-stage estimation; Two-by-two tables.

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#### 文妤

#### 2007 年 6 月 交大統計所

## **Table of Content**







#### **Chapter 1 Introduction**

#### **1.1 Background**

Multivariate survival analysis has wide applications in various fields. Consider an application in the study of familial aggregation for age onset data. The outcomes of age-at-onset within families may be correlated due to genetic and shared environmental risk factors among family members. Understanding the pattern of association may shed light on the disease etiology and is an important step useful for further scientific investigation.

Let  $(T_1,...,T_n)$  be the failure time variables for *k* members in a family. Note that  $T_i$  and *T<sub>j</sub>* for  $i \neq j$  are often correlated. To simplify the analysis we let  $k = 2$ . In the thesis, we assume that  $(T_1, T_2)$  follows a copula model. The major goal is to estimate the association parameter of the imposed model assumption based on right censored data. The situation for homogeneous data (i.e. without covariate information) will be discussed first. We will review existing methods and present our proposal. Then we will discuss a more complicated situation that includes the covariate information. Extension of the former inference methods will be discussed.

#### **1.2 Notations and Outline of the Thesis**

The failure times,  $T_1, ..., T_n$ , are subject to censoring by  $C_1, ..., C_n$ . Denoted the observed data by  $\{(X_{1i}, X_{2i}, \delta_{1i}, \delta_{2i}, Z_{1i}, Z_{2i})\}$ ;  $j = 1, 2, ..., n$ }, where, for an individual *i*,  $X_i$  is the observed time and  $\delta_i$  indicates the corresponding censoring status. If  $\delta_i = 1$ ,  $X_i$  is actually the observed failure time,  $T_i$ . Otherwise if  $\delta_i = 0$ ,  $X_i$  is the censoring time,  $C_i$ . Let  $Z_i : (p \times 1)$  be a vector of covariates for  $i = 1, 2$ . It is assumed that  $T_i$  and  $C_i$  are independent.

In Chapter 2, we briefly review properties of copula models and introduce Archimedean copula models which constitutes a useful sub-family of copula models. Chapter 3 discusses

semi-parametric inference approaches to estimating the association parameter of a copula model in absence of covariates. Three methods will be examined in Section 3.1~3.3. In Section 3.4, we compare the three approaches.

In Chapter 4, we consider a more general situation in presence of covariates. Assuming that the covariates only affect the marginal distributions, we will extend the previous methods to account for marginal heterogeneity. In Chapter 5, we examine finite-sample performances of the methods via simulation studies. In Chapter 6, we give some concluding remarks. The appendix contains our further analysis about the estimator proposed by Hsu and Prentice (1996). Since this estimator does not have satisfactory performance in our simulations, we examine its computation algorithm in more detail to investigate the problem.



#### **Chapter 2 Literature Review**

#### **2.1 Copula Models**

Suppose that *C* is the joint survival function of two correlated  $U(0,1)$  random variables defined on the unit square  $[0,1]^2$ . Let  $(T_1,T_2)$  be a pair of positive failure variables with marginal survival functions  $(S_1, S_2)$  respectively. Note that if  $(T_1, T_2)$  are continuous, both of  $S_i(T_i)$  for  $i=1,2$  are distributed as  $U(0,1)$ . Hence, the joint survival distribution function of  $(T_1, T_2)$  can be expressed as:

$$
S(t_1, t_2) = \Pr(T_1 \ge t_1, T_2 \ge t_2)
$$
  
=  $\Pr(S_1(T_1) \ge S_1(t_1), S_2(T_2) \ge S_2(t_2))$   
=  $\Pr(U_1 \ge S_1(t_1), U_2 \ge S_2(t_2))$   
=  $C\{S_1(t_1), S_2(t_2)\}.$  (2.1)

The above expression was names as a "copula model" by Sklar (1959). Notice that via the copula modeling, the space of joint analysis is transferred from  $[0,\infty)^2$  to  $[0,1]^2$ . Hence copula models have been frequently used for describing the association between two failure variables which are often skewed. From the viewpoint of statistical inference, copula models have the nice feature that the dependence structure can be studied separately from the marginal distributions.

Usually the function  $C(u_1, u_2)$  is parameterized and denoted by  $C_\alpha(u_1, u_2)$ , where the parameter  $\alpha$  measures the association between  $(T_1, T_2)$ . Kendall's  $\tau$  is a rank-invariant association measurement, defined as

$$
\tau = \Pr\{(T_1^* - T_1)(T_2^* - T_2) \ge 0\} - \Pr\{(T_1^* - T_1)(T_2^* - T_2) < 0\},\tag{2.2}
$$

where  $(T_1, T_2)$  and  $(T_1^*, T_2^*)$ 2  $T_1^*, T_2^*$ ) are independent but have the same distribution. The copula parameter  $\alpha$  is related to Kendall's  $\tau$  such that

$$
\tau = 4 \int \int C_{\alpha}(u_1, u_2) \frac{\partial^2 C_{\alpha}(u_1, u_2)}{\partial u_1 \partial u_2} du_1 du_2 - 1.
$$
 (2.3)

By equation (2.3), we see that there is a direct relationship between  $\alpha$  and  $\tau$ . For many well-known copula models, such a relationship has a nice one-to-one correspondence.

#### **2.2 Archimedean Copula Models**

 The family of copula models has a useful sub-class, called the Archimedean copula (AC) family, in which  $C_{\alpha}(u_1, u_2)$  can be further simplified as

$$
C_{\alpha}\{u_1, u_2\} = \varphi_{\alpha}^{-1}\{\varphi_{\alpha}(u_1) + \varphi_{\alpha}(u_2)\},
$$
 (2.4)

where  $\varphi_{\alpha}(u_1) + \varphi_{\alpha}(u_2) \leq \varphi_{\alpha}(0)$  and  $\varphi_{\alpha}(.) : [0,1] \to [0,\infty]$  is the generating function satisfying  $\varphi_{\alpha}(1) = 0$ ,  $\varphi_{\alpha}(t) = \frac{d\varphi_{\alpha}(t)}{dt} < 0$  and  $\varphi_{\alpha}(t) = \frac{d^2\varphi_{\alpha}(t)}{dt^2} > 0$ *dt*  $t = \frac{d^2 \varphi_\alpha(t)}{dt^2}$ *dt*  $\varphi_{\alpha}(1) = 0$ ,  $\varphi_{\alpha}(t) = \frac{d\varphi_{\alpha}(t)}{dt} < 0$  and  $\varphi_{\alpha}(t) = \frac{d^{2}\varphi_{\alpha}(t)}{dt^{2}} > 0$ . The AC family has nice

analytic properties useful for more detailed investigation.

Three examples of AC models are presented below:

(i) Clayton model (Clayton, 1978)  
\n
$$
C_{\alpha}(u_1, u_2) = \begin{cases} (u_1^{1-\alpha} + u_2^{1-\alpha} - 1)^{1-\alpha} & \text{if } \alpha > 1, \\ u_1 u_2 & \text{if } \alpha = 1 \end{cases}
$$
\nand  
\n
$$
\varphi_{\alpha}(v) = (v^{1-\alpha} - 1)/(1-\alpha).
$$

*(ii) Frank model (Frank, 1979)* 

$$
C_{\alpha}(u_1, u_2) = \begin{cases} \log_{\alpha} \left\{ 1 + \frac{(\alpha^{u_1} - 1)(\alpha^{u_2} - 1)}{\alpha - 1} \right\}, & \text{if } 0 < \alpha < 1 \\ u_1 u_2, & \text{if } \alpha = 1 \end{cases}
$$
, and

$$
\varphi_{\alpha}(v) = \log\{(1-\alpha)/(1-\alpha^{\nu})\}.
$$

*(iii) Positive stable frailty model (Hougaard, 1986)* 

$$
C_{\alpha}(u_1, u_2) = \begin{cases} \exp\{-\{\text{-log}(u_1)^{\frac{1}{\alpha}} + (\text{-log}(u_2))^{\frac{1}{\alpha}}\}\}^{\alpha} \\ u_1 u_2, & \text{if } \alpha = 1 \end{cases}
$$
 and  

$$
\varphi_{\alpha}(v) = \{-\log(v)\}^{\frac{1}{\alpha}}.
$$

#### **Chapter 3 Inference without Covariates**

Consider a pair of failure times  $(T_1, T_2)$  which are assumed to be absolutely continuous. In presence of right censoring, we only observe  $(X_1, X_2, \delta_1, \delta_2)$ , where  $X_i = T_i \wedge C_i$ ,  $\delta_i = I(T_i \le C_i)$  (*i* = 1,2), and (*C*<sub>1</sub>, *C*<sub>2</sub>) are a pair of censoring times independent of  $(T_1, T_2)$ . Observed data can be denoted as {  $(X_{1j}, X_{2j}, \delta_{1j}, \delta_{2j})$ ,  $(j = 1, 2, \ldots, n)$ . We assume that the joint survival function follows copula models:

$$
\Pr(T_1 \ge t_1, T_2 \ge t_2) = C\{S_1(t_1), S_2(t_2)\} = \varphi_\alpha^{-1}\{\varphi_\alpha[S_1(t_1)] + \varphi_\alpha[S_2(t_2)]\} \tag{3.1}
$$

The objective is to estimate  $\alpha$  without specifying the marginal distributions.

 In this chapter, we will review three semi-parametric inference approaches. In Section 3.1, we first review the concept of martingales which has been used by Hsu and Prentice (1996) to construct an estimating equation for estimating  $\alpha$ . In Section 3.2, we review the paper of Shih and Louis (1995) who proposed a two-stage of estimation procedure. Specifically they suggest to estimate the marginal distribution first. Then these marginal estimates are treated as pseudo-observations of  $\{S_1(T_1),S_2(T_2)\}\$  in the likelihood based on  $C_{\alpha}$ (...). In Section 3.3, we apply the idea of the Log-Rank statistic by constructing a series of two-by-two tables to estimate the association parameter. This idea has been used by Day et al. (1997) and Wang (2003) for analyzing semi-competing risks data.

#### **3.1 Estimation based on Martingale Residuals**

#### **3.1.1 Preliminary on Counting Processes and Martingales**

Based on observed variables, one can define  $N(t) = I(X \le t, \delta = 1)$ , which is a counting process and the filtration  $F_t = \sigma[N(u), I(T \le u, \delta = 0); 0 \le u \le t]$ , which describes the history of  $N(t)$  prior to or at time *t*.

Define the cumulative intensity process:

$$
\Lambda(t) = \int_0^t I(X \ge u) \lambda(u) du , \qquad (3.2)
$$

where

$$
\lambda(u) = \lim_{\Delta \to 0} \frac{\Pr(T \in [u, u + \Delta) \mid T \ge u)}{\Delta}
$$

is the hazard of *T* at time *u* . Then define

$$
M(t) = I(X \le t, \delta = 1) - \int_0^t I\{X \ge u\} \lambda(u) du = N(t) - \Lambda(t).
$$
 (3.3)

According to the Doob-Meyer decomposition (Fleming and Harrington, 1991), the expectation of  $M(t)$  is a mean-zero martingale. Now we briefly verify the properties of  $M(t)$ :

(A) Given  $F_t$  which contains the history of the process prior the time of  $t$ , the expectation of  $dN(t)$  be an intensity process, such as:

$$
E(dN(t) | F_t) = I(X \ge t) \Pr(X = t, \delta = 1 | T \ge t) + I(X \le t) \Pr(X = t, \delta = 1 | T \le t)
$$
  
=  $I(X \ge t) \frac{\Pr(X = t, \delta = 1)}{\Pr(X \ge t)}$   
=  $I(X \ge t) \lambda(t) dt$   
=  $d\Lambda(t)$ . (3.4)

(B) By the Doob-Meyer decomposition, the expectation of  $dM(t)$  equals to zero, such that:

$$
E(dM(t) | F_t) = E(dN(t) - dA(t) | F_t) = 0.
$$
\n(3.5)   
\nEstimation of  $\alpha$ 

#### **3.1.2 Estimation of** <sup>α</sup>

For the bivariate case, define

$$
M_{i}(t) = I(X_{i} \le t, \delta_{i} = 1) - \int_{0}^{t} I(X_{i} \ge u) \lambda_{i}(u) du = N_{i}(t) - \Lambda_{i}(t), \tag{3.6}
$$

where  $\lambda_i(u)$  is the hazard of  $T_i$  (*i* = 1,2). When  $T_1$  and  $T_2$  are correlated,  $M_1(t_1)$  and  $M_2(t_2)$  are also correlated. Hsu and Prentice (1996) define the following cumulative covariance function, or the covariance rate, as:

$$
\psi(\tau_1, \tau_2) = \int_0^{\tau_1} \int_0^{\tau_2} \psi(dt_1, dt_2), \qquad (3.7)
$$

where

$$
\psi(dt_1, dt_2) = E\{M_1(dt_1)M_2(dt_2) | T_1 \ge t_1, T_2 \ge t_2\}.
$$

The function  $\psi(\tau_1, \tau_2)$  contains the information of association and can be estimated either non- parametrically or under a specified model.

A nonparametric estimator of  $\psi(dt_1, dt_2)$  is given by

$$
\hat{\psi}(dt_1, dt_2) = \frac{\sum_{j \in R(t_1, t_2)} \hat{M}_{1j}(dt_1) \hat{M}_{2j}(dt_2)}{r(t_1, t_2)},
$$
\n(3.8)

where  $r(t_1, t_2) = \sum_{j=1}^{n} I(X_{1j} \ge t_1, X_{2j} \ge$ *j*  $f(t_1, t_2) = \sum I(X_{1j} \ge t_1, X_{2j} \ge t_1)$ 1  $2(t_1, t_2) = \sum_{i=1}^{n} I(X_{1i} \ge t_1, X_{2i} \ge t_2)$  and  $\hat{M}_i(t_i) = N_i(t_i) - \hat{\Lambda}_i(t_i \wedge T_i)$  (*i* = 1,2).

If  $(T_1, T_2)$  follow a copula model, the model-restricted version of  $\psi(t_1, t_2)$  can be expressed as:

$$
\psi(\tau_1, \tau_2; \alpha) = \int_0^{\tau_1} \int_0^{\tau_2} \psi(dt_1, dt_2; \alpha), \qquad (3.9)
$$

where  $\psi(dt_1, dt_2; \alpha) = \psi_0\{S_1(t_1), S_2(t_2); \alpha\}\Lambda_1(dt_1)\Lambda_2(dt_2)$  and

$$
\psi_0\{u_1, u_2; \alpha\} = \{C_{\alpha}^{(11)}(u_1, u_2) - C_{\alpha}^{(10)}(u_1, u_2) - C_{\alpha}^{(01)}(u_1, u_2) + C_{\alpha}(u_1, u_2)\}C_{\alpha}(u_1, u_2)^{-1},
$$
  

$$
C_{\alpha}^{(11)}(u_1, u_2) = \frac{\partial^2 C_{\alpha}(u_1, u_2)}{\partial u_1 \partial u_2}, C_{\alpha}^{(10)}(u_1, u_2) = \frac{\partial C_{\alpha}(u_1, u_2)}{\partial u_1}
$$
 and  

$$
C_{\alpha}^{(01)}(u_1, u_2) = \frac{\partial C_{\alpha}(u_1, u_2)}{\partial u_2}
$$

We have seen that, besides  $\alpha$ , the model-based expression of the covariance function contains nuisance parameters. If the marginal functions  $S_i(t)$  and  $\Lambda_i(dt)$  ( $i = 1, 2$ ) can be estimated, say by the Kaplan-Meier and Aalen's estimators, respectively. One can estimate  $\psi(dt_1, dt_2)$  by

$$
\psi(dt_1, dt_2; \alpha) = \psi_0 \{ \hat{S}_1(t_1), \hat{S}_2(t_2); \alpha \} \hat{\Lambda}_1(dt_1) \hat{\Lambda}_2(dt_2).
$$
 (3.10)

Hsu and Prentice (1996) suggested the following estimating equation based on the weighted difference between the nonparametric estimator of  $\psi(t_1, t_2)$  and its model-based estimator:

$$
\hat{U}_n(\alpha) = n^{-1} \int_0^{\tau_1} \int_0^{\tau_2} r(t_1, t_2) \{ \hat{\psi}(dt_1, dt_2) - \hat{\psi}(dt_1, dt_2; \alpha) \} = 0. \tag{3.11}
$$

*Example: the Clayton model* 

$$
C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\frac{1}{\alpha-1}}
$$
\n(3.12)

The model-based expression of  $\psi(t_1, t_2)$  is

$$
\psi(t_1, t_2; \alpha) = \int_0^{t_1} \int_0^{t_2} \psi(du_1, du_2; \alpha), \qquad (3.13)
$$

where  $\psi(du_1, du_2; \alpha) = \psi_0\{S_1(u_1), S_2(u_2); \alpha\} \Lambda_1(du_1) \Lambda_2(du_2)$  and

$$
\psi_0\{u_1, u_2; \alpha\} = \alpha u_1^{-\alpha+1} u_2^{-\alpha+1} (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-2} - (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-1}.
$$

#### **3.2 Two-Stage Estimation**

We can view  $C_{\alpha}(u_1, u_2)$  as the joint survival function of  $(U_1, U_2) = (S_1(T_1), S_2(T_2))$ . If one can obtain a random sample of  $(T_1, T_2)$ , denoted as  $\{(T_1, T_2), (j = 1, 2, \ldots, n)\}\$ , and *S* <sup>*i*</sup> (*i* = 1,2) are completely specified, the likelihood of  $\alpha$  can be written as

$$
\prod_{j=1}^{n} C_{\alpha}^{(11)}(u_{1j}, u_{2j}), \qquad (3.14)
$$

where  $u_{ij} = S_i(t_{ij})$  ( $i = 1, 2, j = 1, 2, \dots, n$ ). When  $(T_1, T_2)$  are subject to right censoring, the likelihood of  $\alpha$  can be modified as:

$$
\prod_{j=1}^{n} C_{\alpha}^{10}(u_{1j}, u_{2j})^{\delta_{1j}(1-\delta_{2j})} \times C_{\alpha}^{01}(u_{1j}, u_{2j})^{(1-\delta_{1j})\delta_{2j}} \times C_{\alpha}(u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})}.
$$
 (3.15)

However,  $(S_1(T_1),S_2(T_2))$  cannot be observed directly in practice. Shih and Louis (1995) propose a straightforward method to estimate  $\alpha$ . The ideas are to estimate  $(S_1(T_1), S_2(T_2))$ first and then plug in the likelihood function of  $\alpha$ . There are two methods for estimating the marginal distribution. One is the parametric approach in which the marginal distributions are specified up to some unknown parameters. By applying the maximum likelihood approach for estimating the marginal parameters, one can estimate  $(S_1(X_1),S_2(X_2))$  by  $(\widetilde{S}_1(X_1), \widetilde{S}_2(X_2))$ . The other approach does not assume the form of the marginal distributions, the Kaplan-Meier method can be applied for estimating  $S_i(T_i)(i = 1,2)$ . We illustrate this approach using the Clayton model as an example.

*Example: the Clayton model* 

$$
C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\frac{1}{\alpha-1}}
$$
\n(3.16)

And the likelihood function of  $\alpha$  is:

$$
\prod_{j=1}^{n} C_{\alpha}^{(11)}(u_{1j}, u_{2j})^{\delta_{1j}\delta_{2j}} C_{\alpha}^{(10)}(u_{1j}, u_{2j})^{\delta_{1j}(1-\delta_{2j})}\n\times C_{\alpha}^{(01)}(u_{1j}, u_{2j})^{\delta_{1j}(1-\delta_{2j})} C_{\alpha}(u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})},
$$
\n(3.17)

where

$$
C_{\alpha}^{(11)}(u_1, u_2) = \alpha \times u_1^{-\alpha} u_2^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}2},
$$
  

$$
C_{\alpha}^{(10)}(u_1, u_2) = u_1^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-1}
$$

and

$$
C_{\alpha}^{(01)}(u_1, u_2) = u_2^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-1}.
$$

In presence of censoring, we observe { $(X_{1j}, X_{2j}, \delta_{1j}, \delta_{2j})$   $(j = 1, 2, ..., n)$ }. If the marginal distributions are specified, say  $\exp(\lambda = 1)$ , the maximum likelihood estimator of  $S_i(X_{ij})$  is

$$
\widetilde{S}_{i}(X_{ij}), \text{ where}
$$
\n
$$
\widetilde{S}_{i}(X_{ij}) = \exp(-\frac{\sum_{j=1}^{n} \delta_{ij}}{\sum_{j=1}^{n} X_{ij}}) ; \text{ for } i = 1, 2 \text{ and } j = 1, 2, ..., n.
$$
\n(3.18)

If the marginal form is unknown, we estimate  $S_i(X_i)$  by Kaplan-Meier estimator:

$$
\hat{S}_i(X_{ij}) = \prod_{u \le x_{ij}} \left\{ 1 - \frac{\sum_{j=1}^n I(X_{ij} = u, \delta_{ij} = 1)}{\sum_{j=1}^n I(X_{ij} \ge u)} \right\}; \text{for } i = 1, 2 \text{ and } j = 1, 2, ..., n. \quad (3.19)
$$

#### **3.3 Estimation based on Two-by-Two Tables**

#### **3.3.1 The Proposed Method**

In this section, we propose an estimator of  $\alpha$  for an Archimedean Copula Models of the form:

$$
\Pr(T_1 \ge t_1, T_2 \ge t_2) = C\{S_1(t_1), S_2(t_2)\} = \varphi_\alpha^{-1}\{\varphi_\alpha[S_1(t_1)] + \varphi_\alpha[S_2(t_2)]\}.
$$
 (3.20)

This idea is actually an application of the papers of Day et al. (1997) and Wang (2003) who considered semi-competing risks data. In presence of censoring, we observe  $\{(X_{1j}, X_{2j}, \delta_{1j}, \delta_{2j}) (j = 1,...,n)\}\.$  The proposed estimating procedure is related to the Log-Rank statistic which can be constructed based on a series of two-by-two tables. At an observed failure points  $(t_1, t_2)$ , we can construct the following two-by-two tables as follows:

$$
X_{1} = t_{1}, \delta_{1} = 1 \begin{bmatrix} X_{2} = t_{2}, \delta_{2} = 1 & X_{2} > t_{2} \\ N_{11}(dt_{1}, dt_{2}) & \cdots & N_{10}(dt_{1}, t_{2}) \\ \vdots & \vdots & \ddots & \vdots \\ N_{01}(t_{1}, dt_{2}) & R(t_{1}, t_{2}) \end{bmatrix}
$$

**Table:** *Two-by-Two Tables at time*  $(t_1, t_2)$ 

The cell counts are defined as follows. Let

$$
N_{11}(dt_1, dt_2) = \sum_{j=1}^{n} I(X_{1j} = t_1, \delta_{1j} = 1, X_{2j} = t_2, \delta_{2j} = 1),
$$
  
\n
$$
N_{10}(dt_1, t_2) = \sum_{j=1}^{n} I(X_{1j} = t_1, \delta_{1j} = 1, X_{2j} \ge t_2),
$$
  
\n
$$
N_{01}(t_1, dt_2) = \sum_{j=1}^{n} I(X_{1j} \ge t_1, X_{2j} = t_2, \delta_{2j} = 1)
$$

and

$$
R(t_1,t_2) = \sum_{j=1}^n I(X_{1j} \ge t_1, X_{2j} \ge t_2).
$$

Notice that the odds ratio of the table converges to

$$
\theta(t_1, t_2) = \frac{\frac{\partial^2}{\partial t_1 \partial t_2} \Pr(T_1 \ge t_1, T_2 \ge t_2) \Pr(T_1 \ge t_1, T_2 \ge t_2)}{\frac{\partial}{\partial t_1} \Pr(T_1 \ge t_1, T_2 \ge t_2) \frac{\partial}{\partial t_2} \Pr(T_1 \ge t_1, T_2 \ge t_2)}.
$$
(3.21)

For models in the AC family,  $\theta(t_1, t_2)$  can be simplified as

$$
\theta(t_1, t_2) = \tilde{\theta}_{\alpha} (\Pr(T_1 \ge t_1, T_2 \ge t_2)), \qquad (3.22)
$$

where  $\tilde{\theta}_{\alpha}(\cdot)$  is an univariate function satisfying

$$
\tilde{\theta}_{\alpha}(v) = -v \times \frac{\varphi_{\alpha}''(v)}{\varphi_{\alpha}'(v)}.
$$
\n(3.23)

Conditioning on the marginal counts,  $N_{11}(dt_1, dt_2)$  follows a hypergeometric distribution with **ALLELLIA** mean:

$$
E_{11}(dt_1, dt_2, \alpha) = \frac{\theta(t_1, t_2)N_{10}(dt_1, t_2)N_{01}(t_1, dt_2)}{\theta(t_1, t_2)N_{10}(dt_1, t_2) + R(t_1, t_2) - N_{10}(dt_1, t_2)}
$$
(3.24)  

$$
= \frac{\tilde{\theta}_{\alpha}(\Pr(X_1 \ge t_1, X_2 \ge t_2))N_{10}(dt_1, t_2)N_{01}(t_1, dt_2)}{\tilde{\theta}_{\alpha}(\Pr(X_1 \ge t_1, X_2 \ge t_2)N_{10}(dt_1, t_2) + R(t_1, t_2) - N_{10}(dt_1, t_2)}.
$$

By equating the empirical count with its model-based expected value and combining the tables with different  $(t_1, t_2)$ , we can construct the following estimating equation:

$$
L(\alpha) = n^{-1} \int_0^{\tau_1} \int_0^{\tau_2} W(t_1, t_2) \{ N_{11}(dt_1, dt_2) - E(dt_1, dt_2, \alpha) \} = 0, \quad (3.25)
$$

where  $W(t_1, t_2)$  is the weight function. It has been suggested to use

$$
W(t_1, t_2) = \frac{\dot{\theta}_\alpha(S(t_1, t_2))}{\theta_\alpha(S(t_1, t_2))},
$$
\n(3.26)

where  $S(t_1, t_2) = Pr(T_1 \ge t_1, T_2 \ge t_2)$  and  $\hat{\theta}_\alpha(\nu) = \frac{\partial \sigma_\alpha(\nu)}{\partial \alpha}$  $\dot{\theta}_u(v) = \frac{\partial \theta_a(v)}{\partial x}$  $\alpha$   $\beta$   $\beta$  $\dot{\theta}_{\alpha}(v) = \frac{\partial \theta_{\alpha}(v)}{\partial \alpha}.$ 

*Example: the Clayton model* 

$$
C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\frac{1}{\alpha-1}}
$$
\n(3.27)

For Clayton model with  $\varphi_{\alpha}(t) = t^{-(\alpha-1)} - 1$ ,  $(\alpha > 1)$ , we can obtain the model based expectation of  $N_{11}(dt_1, dt_2)$ :

$$
E_{11}(dt_1, dt_2, \alpha) = \frac{\alpha \times N_{10}(dt_1, t_2)N_{01}(t_1, dt_2)}{\alpha \times N_{10}(dt_1, t_2) + R(t_1, t_2) - N_{10}(dt_1, t_2)}.
$$
(3.28)

#### **3.4 Discussion**

 Shih and Louis (1995) proposed a two-stage estimation procedure. This approach is semi-parametric in the sense that the first stage can be estimated non-parametrically. However in some complicated data structures, such as semi-competing risk, nonparametric estimation in the first stage is not applicable. Hsu and Prentice (1996) constructed their estimating function based on martingale residuals. However the model-based expression involves too many high-dimensional nuisance parameters and therefore the resulting estimating equation becomes very complicated. Practical performance of this estimator heavily depends on the accuracy of the plug-in estimates in all data range. In our simulations, we have found that estimation in the tail region is not satisfactory.

The latter two approaches only use the conditions of the moments. It seems that the approach based on two-by-two tables is a more natural way for describing the dependence structure for AC models. Specifically for the Clayton model  $E_{11}(dt_1, dt_2, \alpha)$  does not even contain any nuisance parameters. The key is that the theoretical odds ratio of the tables can well capture the association information for AC models. In contrast,  $\psi(t_1, t_2; \alpha)$  is much less natural. It involves high-dimensional nuisance parameters that affect the subsequent inference procedure.

#### **Chapter 4 Inference with Covariates**

In this chapter, we discuss the estimation of  $\alpha$  when there exist covariates that may affect the marginal distributions. Let  $(T_1, T_2)$  and  $(C_1, C_2)$  be failure times and censoring times, respectively. Let  $Z_i$ :  $p \times 1$  ( $i = 1,2$ ) be the covariate vectors. In presence of right censoring, observed data can be expressed as  $\{(X_{1j}, X_{2j}, \delta_{1j}, \delta_{2j}, Z_{1j}, Z_{2j}), (j = 1, 2, ..., n)\}\,$ 

where  $X_{ij} = T_{ij} \wedge C_{ij}$  and  $\delta_{ij} = I(T_{ij} < C_{ij})$ , for  $i = 1, 2$  and  $j = 1, 2, ..., n$ .

Here we assume that  $Z_i$  only affects  $T_i$  ( $i = 1, 2$ ), marginally. Let

$$
U_i = S_i(t | Z_i) = Pr(T_i \ge t | Z_i) (i = 1, 2).
$$
 (4.1)

Furthermore, we assume that

$$
Pr(U_1 \ge u_1, U_2 \ge u_2) = C_{\alpha}(u_1, u_2). \tag{4.2}
$$

In the following analysis, we assume that marginally the covariate effect follow the Cox Proportional Hazard model, such that

$$
\lambda_i(t) = \lambda_{i,0}(t) \exp(Z_i \beta_i) \ (i = 1,2), \tag{4.3}
$$

where  $\lambda_{i,0}(t)$  is the baseline hazard function. In Section 4.1, we modify the two-stage estimation approach. In Section 4.2, we apply our idea based on two-by-two tables to handle this more generalized situation.

#### **4.1 Two-Stage Estimation**

The first stage involves estimating pseudo-observations of  $(U_1, U_2)$ . Note that, under the Cox PH model,  $U_i = S_i(t_i | Z_i) = S_{i,0}(t_i)^{\exp(Z_i;\beta_i)}$  (*i* = 1,2).  $U_i = S_i(t_i | Z_i) = S_{i,0}(t_i)^{\exp(Z_i;\beta_i)}$  (*i* = 1,2). This implies that we need to estimate  $\beta_i$  and  $S_{i,0}(t_i)$  first. The regression parameter  $\beta_i$  can be estimated by maximizing the following likelihood

$$
L(\beta_i) = \prod_{\text{failure } u} \frac{\sum_{j=1}^n I(X_{ij} = u, \delta_j = 1) \times \exp(Z_{ij}'\beta_i)}{\sum_{j=1}^n I(X_{ij} \ge u) \times \exp(Z_{ij}'\beta_i)} (i = 1, 2).
$$
 (4.4)

The estimator of the baseline function can be expressed by Breslow's estimator:

$$
\hat{S}_{i,0}(t_i) = \prod_{t_{ii}\leq t_i} (1 - \frac{\sum_{t_{(j)}} I(X_i = t_{(j)}, \delta_i = 1)}{\sum_{t_{(j)}\in R} \exp(Z_{i(j)}\hat{\beta}_i)} (i = 1, 2).
$$
\n(4.5)

Then we can obtain  $U_1 = \hat{S}_{1,0}(T_1)^{\exp(Z/\hat{\beta}_1)}$  and  $U_2 = \hat{S}_{2,0}(T_2)^{\exp(Z/\hat{\beta}_2)}$ . Based on  $\{(U_{1j}, U_{2j}, \delta_{1j}, \delta_{2j}) \mid (j = 1, 2, ..., n)\}\$ , we can estimate  $\alpha$  by the following likelihood

function:

$$
\prod_{j} L(\alpha) = \prod_{j} C_{\alpha}^{(11)} (u_{1j}, u_{2j})^{\delta_{1j}\delta_{2j}} C_{\alpha}^{(10)} (u_{1j}, u_{2j})^{\delta_{1j}(1-\delta_{2j})}
$$

$$
\times C_{\alpha}^{(01)} (u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})} C_{\alpha} (u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})} (j = 1, ..., n). (4.6)
$$

For Clayton's model with  $C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\alpha-1}$ 1 1 2  $C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\alpha-1}$ , the above likelihood equals  $\prod_{j} L(\alpha) = \prod_{j} C_{\alpha}^{(11)} (u_{1j}, u_{2j})^{\delta_{1j} \delta_{2j}} C_{\alpha}^{(10)} (u_{1j}, u_{2j})^{\delta_{1j} (1-\delta_{2j})}$  $L(\alpha) = \prod_{\alpha} C_{\alpha}^{(11)}(u_{1i}, u_{2i})^{\delta_{1j}\delta_{2j}} C_{\alpha}^{(10)}(u_{1i}, u_{2i})^{\delta_{1j}(1-\delta)}$  $\prod L(\alpha) = \prod C_{\alpha}^{(1)} (u_{1j}, u_{2j})^{\delta_{1j}\delta_{2j}} C_{\alpha}^{(10)} (u_{1j}, u_{2j})^{\delta_{1j}(1)}$  $\times C_{\alpha}^{(01)}(u_{1j},u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})} C_{\alpha}^{(u_{1j},u_{2j})}^{(1-\delta_{1j})(1-\delta_{2j})}$   $(j=1,..,n).$  $(1-\delta_{1i})(1-\delta_{2i})$  $\times C_{\alpha}^{(01)}(u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})} C_{\alpha}(u_{1j}, u_{2j})^{(1-\delta_{1j})(1-\delta_{2j})}$  (j = 1,..., n  $\sigma_{\alpha}^{(01)}(u_{1i}, u_{2i})^{(1-\delta_{1i})(1-\delta_{2i})} C_{\alpha}(u_{1i}, u_{2i})^{(1-\delta_{1i})(1-\delta_{2i})}$  (j = 1,.., n). (4.7) where  $C_{\alpha}^{(11)}(u_1, u_2) = \alpha \times u_1^{-\alpha} u_2^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-2}$ 1 1 2 1  $C_{\alpha}^{(11)}(u_1, u_2) = \alpha \times u_1^{-\alpha} u_2^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-2},$ 

$$
C_{\alpha}^{(10)}(u_1, u_2) = u_1^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-1}
$$

and

$$
C_{\alpha}^{(01)}(u_1,u_2) = u_2^{-\alpha} \times (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{\frac{1}{1-\alpha}-1}.
$$

#### **4.2 Estimation based on Two-by-Two Tables**

Based on pseudo-observations  $\{(U_{1j}, U_{2j}, \delta_{1j}, \delta_{2j}) (j = 1,...,n)\}\)$ , we can construct the following two-by-two table:

$$
U_1 = u_1, \delta_1 = 1 \n\begin{array}{c|c|c}\nU_2 = u_2, \delta_2 = 1 & U_2 > u_2 \\
\hline\nN_{11}(du_1, du_2) & & N_{10}(du_1, u_2) \\
U_1 > u_1 & & N_{01}(u_1, du_2) \\
\hline\nN_{01}(u_1, du_2) & & R(u_1, u_2)\n\end{array}
$$

*Table: Two-by-Two Table based on pseudo-observations* 

The cell counts are defined as follows. Let

$$
N_{11}(du_1, du_2) = \sum_{j=1}^n I(U_{1j} = u_1, \delta_{1j} = 1, U_{2j} = u_2, \delta_{2j} = 1),
$$
  
\n
$$
N_{10}(du_1, u_2) = \sum_{j=1}^n I(U_{1j} = u_1, \delta_{1j} = 1, U_{2j} \ge u_2),
$$
  
\n
$$
N_{01}(u_1, du_2) = \sum_{j=1}^n I(U_{1j} \ge u_1, U_{2j} = u_2, \delta_{2j} = 1)
$$
  
\nand

and

$$
R(u_1, u_2) = \sum_{j=1}^n I(U_{1j} \ge u_1, U_{2j} \ge u_2).
$$

Accordingly the estimating function becomes:

$$
L(\alpha) = n^{-1} \int_0^{\tau_1} \int_0^{\tau_2} W(u_1, u_2) \{ N_{11}(du_1, du_2) - E(du_1, du_2, \alpha) \} = 0, \tag{4.8}
$$

where

$$
E_{11}(du_1, du_2, \alpha) = \frac{\theta(u_1, u_2)N_{10}(du_1, u_2)N_{01}(u_1, du_2)}{\theta(u_1, u_2)N_{10}(du_1, u_2) + R(u_1, u_2) - N_{10}(du_1, u_2)}.
$$

Consider the Clayton model:

$$
C_{\alpha}(u_1, u_2) = (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\frac{1}{\alpha-1}}.
$$
 (4.9)

The above likelihood function of  $\alpha$  can be simplified using the fact that  $\theta(u_1, u_2) = \alpha$ .

## **Chapter 5 Simulations**

#### **5.1 Data Generation**

Via simulations, we will examine finite-sample performances of several estimators of  $\alpha$ without and with covariates. We consider generating  $(T_1, T_2)$  from the Clayton model of the form:

$$
C_{\alpha}(u_1, u_2) = \begin{cases} (u_1^{-\alpha+1} + u_2^{-\alpha+1} - 1)^{-\frac{1}{\alpha-1}} & (\alpha > 1) \\ u_1 u_2 & (\alpha = 1). \end{cases}
$$
(5.1)

Note that  $\alpha = (1 - \tau)/2\tau$ , where  $\tau$  is Kendall's  $\tau$ . In particular, we will adopt the data generation algorithm for the Clayton model proposed by Prentice and Cai (1992).

#### **5.1.1 Data Generation without Covariates**

Step (i) Specify the value of  $\tau$  and compute  $\alpha = \frac{1+t}{1-\tau}$  $\alpha = \frac{1+\tau}{1-\tau}.$ Step (ii) Generate independent variables  $\{(U_{1j}, U_{2j})$   $(j = 1,...,n)\}\$ , where  $U_{ij} \sim$  $U(0,1)(i=1,2)$ .

Step (iii) Generate  $\{(T_{1j}, T_{2j})$  ( $j = 1, 2,...,n\}$ , such that:

$$
\gamma_j = (1 - U_{2j})^{-\frac{1}{\alpha}},
$$
  
\n
$$
T_{1j} = \alpha \times \log[1 - \gamma_j + \gamma_j (1 - U_{1j})^{-\frac{1}{1 + \alpha}}],
$$
  
\n
$$
T_{2j} = (1 - U_{2j})^{-\frac{1}{\alpha}}.
$$

Then  $(T_{1j}, T_{2j})$  follows Clayton  $(\alpha)$  and marginally  $T_{ij}$   $(i = 1, 2) \sim \exp(1)$ .

Step (iv) Generate  $\{ (C_{1j}, C_{2j})$  ( $j = 1, 2, ..., n$ ), both of which are uniformly

distributed.

Finally with  $\{(T_{1j}, T_{2j}, C_{1j}, C_{2j}) (j = 1,...,n)\}\)$ , we can create observed data  $\{(X_{1j}, X_{2j}, C_{2j}) (j = 1,...,n)\}\$  $\delta_{1j}, \delta_{2j}$ ) ( $j = 1, 2, ..., n$ ) such that  $X_{ij} = T_{ij} \wedge C_{ij}$  and  $\delta_{ij} = I(T_{ij} \le C_{ij})$  for  $i = 1, 2$ .

#### **5.1.2 Date Generation with Covariates**

 Now we generate data which include a binary covariate. We assume the marginal effect follows the Cox proportional hazard model (1972), such as:

$$
S_i(t) = S_{i,0}(t)^{\exp(Z_i \beta_i)},
$$
\n(5.2)

where  $Z_i$  is the covariate and  $S_{i,0}(t)$  is the baseline survival function at time  $t$   $(i = 1,2)$ . The general procedure can be stated as follows. Let  $S(T) = U$ , where  $U \sim U(0,1)$ , and under the Cox proportional hazard model, we have  $S_0(T)^{\exp(Z/\beta)} = U$ . Hence it follows that

$$
\log(S_0(T)) = \frac{\log(U)}{\exp(Z/\beta)},\tag{5.3}
$$

which implies that

$$
T = S_0^{-1} \left[ \exp(\frac{\log(U)}{\exp(Z'\beta)}) \right].
$$
 (5.4)

We still need to specify the form of  $S_0(t)$ . For most distributions, the inverse of  $S_0(t)$  may not have an explicit expression which increases the numerical difficulty in the analysis. In our simulations, we specify the baseline survival function to be  $S_0(t) = \exp(-t)$  and obtain the following explicit expression:

$$
T = \frac{-\log(U)}{\exp(Z/\beta)},
$$
\n(5.5)

where  $-\log(U)$  which follows exp(1).

The data generation procedure is summarized below.

- Step (i) Generate  $Z_{ij}$  from Bernoulli(0.5) for  $i = 1, 2$ .
- Step (ii) Generate failure times  $(T_{1j}^*, T_{2j}^*)$  $T_{1j}^*, T_{2j}^*$ ) for the baseline group with
- $Z_{ii} = 0$  using the above algorithm, where  $T_{ii}^{*} \sim \exp(1)(i = 1,2)$ .

Step (iii) Given the value of  $\beta_i$ , for those with  $Z_{ij} = 1$ , we set

$$
T_{ij} = \frac{T_{ij}^{*}}{\exp(Z_{ij} \beta_i)} \quad (i = 1, 2).
$$

Step (iv) Generate  $\{ (C_{1i}, C_{2i})$  ( $j = 1, 2, ..., n$ ), both of which are exponential distributed.

Finally with  $\{(T_{1i}, T_{2i}, C_{1i}, C_{2i}, Z_{1i}, Z_{2i})$   $(j = 1,...,n)\}$ , we can create observed data  $\{(X_{1j}, X_{2j}, \delta_{1j}, \delta_{2j}, Z_{1j}, Z_{2j}) (j = 1,2,...,n)\}\$  such that  $X_{ij} = T_{ij} \wedge C_{ij}$  and  $\delta_{ij} = I(T_{ij} \leq C_{ij})$ .

#### **5.2 Simulation Results**

#### **5.2.1 Results without Covariates**

 In this section, we evaluate two approaches based on two-stage estimation and the construction of two-by-two tables. Two sample sizes with  $n = 100$  and  $n = 500$  are considered. The parameter  $\alpha$  ranges form 1.2 to 19 which correspond to  $\tau$  from 0.1 to 0.9. For each estimator, the average bias and standard deviation of  $\alpha$  are reported based on 500 replications. To achieve the targeted censoring rates, 30 % and 60 %, we set  $C_i$  to follow *U* (0,5.5) and *U* (0,2.5), respectively for  $i = 1,2$ .

 Table 1.1 summarizes the results in absence of censoring. Note that for the approach of two-stage estimation, we also present the results when the first stage of estimation is performed parametrically. Recall that we assume the marginal distribution of failure time *X* is  $exp(\lambda = 1)$ . Hence, for the parametric two-stage procedure, we use

$$
\hat{\lambda} = \frac{\sum_{j=1}^{n} \delta_j}{\sum_{j=1}^{n} x_j}
$$
 (in complete data  $\hat{\lambda} = \frac{1}{\overline{x}}$ ) (5.6)

to plug in the second stage for estimating  $\alpha$ . This approach yields better results (smaller bias and smaller variation) than the semi-parametric two-stage procedure. As for the approach constructed based on two-by-two tables, it produces fairly nice results despite that it makes no assumption on the marginal distributions. Specifically it is fairly unbiased and the variance is only slightly larger than the parametric two-stage procedure. Note that the variation of all the estimators becomes larger when  $\alpha$  increases.

 Table 1.2 and 1.3 are the results in presence of external censoring. Although variation of the estimators are larger than those without external censoring, the estimators still perform well. For Table 1.1  $\sim$  1.3, the variation is close to zero with the increasing of sample size (from 100 to 500). Hence, we can conclude that all of the estimations satisfy the property of consistency.



#### **5.2.2 The Method Proposed by Hsu & Prentice**

 In this section, we examine the performance of the estimator proposed by Hsu and Prentice (1996) under the same settings. The results based on complete data are summarized below.

	$n=500$
$\alpha$	bias $\times 10^{-2}$ (st. error $\times 10^{-2}$ )
$1.\overline{2}$	$-2.283(5.861)$
1.5	$-6.701(7.396)$
1.85714	$-15.267(8.659)$
$2\overline{3}$	$-31.961(8.996)$
3.0	$-66.637(7.981)$
<b>4.0</b>	$-138.223(5.786)$
5.6	$-284.485(3.156)$
9.0	$-606.891(1.162)$
19.0	$-1602.436(0.860)$

*Table A: Original version of Hsu & Prentice's estimator with no censoring*  $\overline{a}$ 

Strangely, based on Table A, we found that  $\hat{\alpha}$  seems to be not consistent when  $\alpha \geq 2.\overline{3}$ . To investigate what caused the problem, we checked several things. The details are summarized in the Appendix. We suspected that the problem may be attributed to the estimation instability of  $\psi(t_1, t_2; \alpha)$  in (3.10) in some region of  $(t_1, t_2)$ . The plugged-in marginal estimators are usually unstable in the tail area. Hence we trimmed the integration area from  $[0,\infty)\times[0,\infty)$  to a bounded region. Because this modification has no theoretical justification, we only evaluate the case without censoring.

 Table B below contains the results for the modified estimator which is analyzed in a bounded region. Specifically, for each margin, we trim 50 % of the tail region. Based on Table B, we can know that both of bias and standard deviation of  $\hat{\alpha}$  have significant improvement. With the sample size increases from 100 to 500, the standard deviation of  $\hat{\alpha}$  have less

variation. Despite of the improvement, the method still performs not as well as the previous two approaches. One possible reason is that the model-based expectation  $\psi(t_1, t_2; \alpha)$  in (3.10) contains more nuisance parameters than the other two approaches.

$\alpha$	$n = 500$	$n=100$
	bias $\times 10^{-2}$ (st. error $\times 10^{-2}$ )	
$1.\overline{2}$	0.229(10.741)	4.398 (24.211)
1.5	$-0.162(13.234)$	3.805 (31.675)
1.85714	$-0.145(16.388)$	3.804 (39.416)
$2.\overline{3}$	$-0.489(20.883)$	4.530 (49.133)
3.0	$-0.161(28.358)$	5.530 (64.276)
4.0	0.922(39.522)	9.705 (89.874)
$5.\overline{6}$	2.931 (63.757)	12.754 (149.819)
9.0	13.172 (147.715)	43.050 (351.349)
19.0	104.310 (678.372)	322.146 (1652.888)

*Table B: Modified version of Hsu and Prentice's estimator with no censoring*

#### **5.2.3 Results with Covariates**

 We have proposed to extend two inference approaches to a more complex situation that covariates affect the marginal distribution. Now we check the validity of the extension by simulations. Here we assume the Cox Proportional Hazard model to describe marginal heterogeneity. For the two-stage estimation approach, we only report the results that the marginal distributions are estimated non-parametrically. The parameter of  $\alpha$  ranges from 1.2 to 19 and  $\beta_1 = \beta_2 = 0.8$ . We also evaluate the situation in presence of censoring with 30 % and 60 % censoring. To achieve the targeted censoring rates, we let  $C_i$  follow  $\exp(\lambda = 3.5)$  and  $\exp(\lambda = 1.5)$ , respectively (*i*=1,2). Two sample sizes with *n* = 100 and  $n = 500$  are evaluated. For each estimator, the average bias and standard deviation are reported based on 500 replications.

 Table 2.1 summaries the result with covariates in absence of censoring. Our focus is on comparing the two methods after adjustment for the effects of  $\beta_1$  and  $\beta_2$ . The variation of the two approaches is close. However, the two-by-two table approach seems to produce less biased estimates. Table 2.2 and 2.3 are the results in presence of right censoring. The estimators of  $\alpha$  have larger variation but still perform well. All of the estimators are consistent when the sample size increases. In the simulations not reported here, we find that the estimators of  $\alpha$  become invalid if the marginal heterogeneity is ignored.

#### **Chapter 6 Conclusion**

 In the thesis, we review three inference approaches for estimating the association parameter for copula models. The existing methods are originally developed for analyzing homogeneous data. Here we extend these methods to account for marginal heterogeneity explained by covariates.

The two-stage estimation procedure proposed by Shih and Louis (1995) is easy to implement but not applicable under more complicated data structures such as semi-competing risks data that involves dependent censoring. The proposed approach based on two-by-two tables is motivated by the Log-Rank statistics. In comparison, it is a simple procedure from both aspects of analytic derivations and computation. It also has nice performance in simulations. Since this approach only utilizes some moment conditions, it can be easily modified for different data structures. The estimator of Hsu and Prentice (1996) has poor performance in our simulations. If our numerical algorithm is correct, the poor performance may be caused by the plugged-in estimators of the nuisance functions.

The proposed method and the method by Hsu and Prentice (1996) are both moment-based procedures but their performances are very different. We have found that, for AC models, the odds ratio of the two-by-two table provides a better descriptive measure for the association. In contrast, the covariance function of martingale residuals proposed by Hsu and Prentice is much less natural. That is why it produces an estimating function that involves many nuisance parameters.



 *Table 1.1 Comparison of two approaches without external censoring.*

bias  $\times 10^{-2}$  (st.error  $\times 10^{-2}$ )



 *Table 1.2 Comparison of two approaches with censoring rate 0.3.*

bias  $\times 10^{-2}$  (st.error  $\times 10^{-2}$ )



*Table 1.3 Comparison of two approaches with censoring rate 0.6.* 



















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## **Appendix: Checking the Validity of the Method by Hsu and Prentice**





Finding: There seems to be a bound on  $\hat{\alpha}$ .

Investigation #2: Whether the above problem is caused by the root-finding procedure?



Finding: The estimating equation has a unique but wrong solution in some situation.

Investigation #3: Whether the plug-in estimators for the nuisance functions are not accurate?



*Figure A.3 the marginal survival function and its estimator* 



*Figure A.4 the cumulative hazard function and its estimator* 

Finding: The plugged-in estimator have reasonable performance only in some region.

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